

Status of the Digital Simulation of the PXD

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Implementation of the PXD and SVD Digitizers in basf2

- **Digitizers simulate detector response based on simulated particle tracks.**
 - Currently, there are only simple gaussian-smear digitizers in basf2 using resolution data from the full ILC/-based simulation. Together with the Sensitive detector types and data objects (“hit types”) they form a simplistic simulation chain.
 - For real simulation studies, in particular of PXD background and SVD pattern recognition, more sophisticated simulation of detector response is **vital**.
- **Task: Implement the PXD/SVD digitizers used in the ILCsoft framework in basf2.**
 - The digitizers (written by Zbynek Drasal) are quite detailed and proven.
 - They are undergoing development towards even more detailed description of detector response (Zbynek – improved simulation of energy straggling; Benjamin Schwenker – lateral electric fields)
 - Also, the Sensitive Detector classes have to be updated, to properly handle secondaries.
- **The plan was to include the PXD digitizer in the first release of basf2.**



Only Simple Digitizer in basf2 1.0

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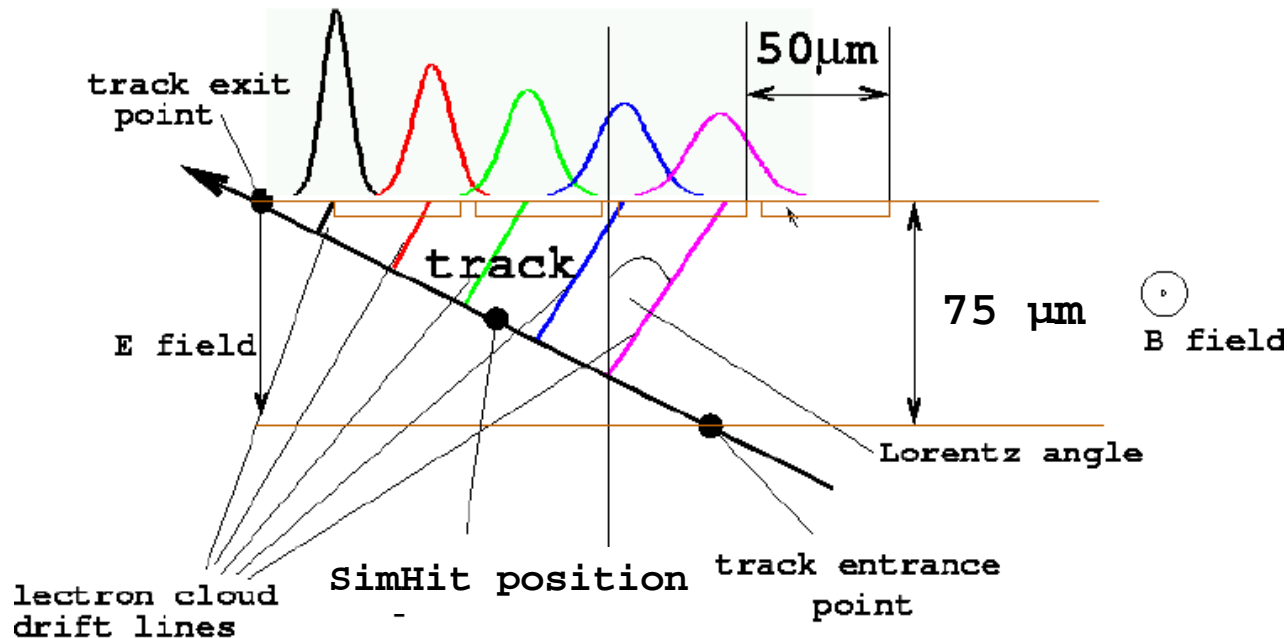
- **The “full” digitizer implementation is not ready for the first release of basf2:**
 - **The code needs a couple of days to go to svn**, and some more to be tested against the ILC digitizer.
 - **The SeinsitiveDetector class** (common to PXD and SVD) is in a similar state, albeit it is a simpler piece of software and also testing is much simpler.



The PXD digitizer: What it does

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- **For each simulated hit (PXDSimHit) obtained from Geant4**
 - **Track generation.** The SimHits are created where Geant4 detects a passage of a particle through an active detector. δ electrons are treated separately
 - **Ionization.** The track segment is divided into sub-segments (“ionization points”), whose charge is smeared according to the Landau distribution using the code borrowed from Geant4 (G4UniversalFluctuation). This provides substantially higher precision than in the generating “all-detector” Geant4 simulation.





The PXD digitizer: What it does (cont'd)

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- **Drift and diffusion.** The ionisation points are then drifted to the readout plane, Lorentz-shifted in the presence of a magnetic field and smeared by a Gaussian distribution to account for diffusion during the drift time.
- **Lateral diffusion.** Finally, the total charge of an ionization point is split into carrier groups of ~ 100 electrons. For each carrier group, a random walk in the readout plane is sampled until the internal gate of a pixel cell is hit.
- **Digitization.** For each pixel electrode one gets a signal dependent on how many ionization points contributed).
- **Background and noise.** The pixels are then populated by random electronic noise and background signal as appropriate.
- **Analog-To-Digital converters** will be used in the data processing pipeline, Therefore, the analog signals are converted first into digital values.



The PXD digitizer: What it does (cont'd)

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- **Hit reconstruction.** For practical purposes, digitization is coupled with hit reconstruction to avoid the storage of digits when they are not needed (the digits can however be saved if desired).
- **Clustering** is based on seed and neighbor threshold values.
- **Hit position** is estimated separately in each coordinate, by center-of-gravity for cluster projections of 1 or 2 pixels, and analog head-tail (approximate the cluster by a uniform charge distribution consistent with pixel signals) for larger clusters.
- **Output** The output of the digitizer is a collection of PXDHits, with each reconstructed hit containing (apart from sensor identification)
 - position estimate (corrected for mean Lorentz shift) and its error covariance
 - total collected charge (analog in electrons or digital in ADU)
 - references (relations) to SimHits that contributed.



So where's the problem?

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- **There is no major problem**
 - The main body of work is to translate the code from ILCsoft to basf2. There are no significant issues, rather a lot of small ones (units in empirical formulas of the Geant4 code, for example).
 - Basf2 is evolving – new features (implementation of MCParticles and relations) appearing – this makes the transition simpler than it was initially.
 - Geometry is no problem, in the basf2 implementation the hits are in local sensor coordinates, so the original geometry code can be disposed off completely.
 - **Things that actually need to be changed will be changed later:**
 - Automate calculation of error covariance of reconstructed hits.
 - Disentangle clustering/hit reconstruction as much as possible from the digitization code, but keep the efficiency of not storing digits if they are not needed. Maybe a plug-in that can be used in a standalone module or as a part of the digitizer module, and can be replaced by a different code to test.
 - Major task: simulate DHP and following processing.
 - “Last minute” issues (Andreas): check / fix the deposited energy smearing and handling of photons by the digitizer.



Schedule update

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- There is now little to finish for the first submission.
- It is to appear in the svn within one week (by 15. February).
- One more week is needed for the SVD digitizer (different code, but similar modifications to be made as for the PXD) .
- A test suite for the digitizers will be a necessary tool in further development. This will be proposed/discussed at the Munich framework/DAQ meeting in Munich.



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Thanks for your attention!