PXD DAQ Discussion München HLT & PXDDAQ Workshop 22.02.2011

More algorithms for PXDDAQ ATCA

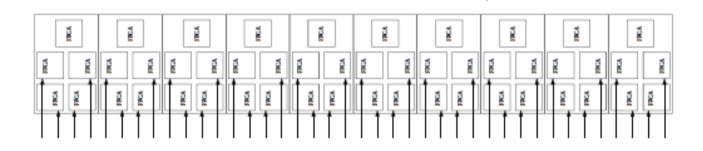
- cluster finder
 - remove 1-pixel cluster for large ϑ
 no problem, as <u>inside</u> ROI
 - Low p_T tracks = high dE/dx cluster finder problem, as <u>outside</u> ROI! requires extra pass of all PXD hits > time consuming!
- pedestal algorithm
 plan: last event before injection burst might contain all pixels
 not clear yet, if ATCA
 (because JTAG connection to frontend connection is needed anyway,
 maybe from extra PC, which then can run pedestal algorithm)
- alignment algorithm (i.e. solving coupled differential equations)
 -> construction site, nobody yet (although required by SVD ROI algorithm)
- PXD-only subevent Building
 RAM access and sorting algorithm (time consuming)
 if we need to run the other algorithms,
 can this probably be shifted to 2nd event builder farm?

PXS Subevent Builder



Note: backplane link is also RocketIO

40 FPGAs (data receive optical links) + 10 FPGAs (routing to backplane)



40 FPGAs for storing complete events



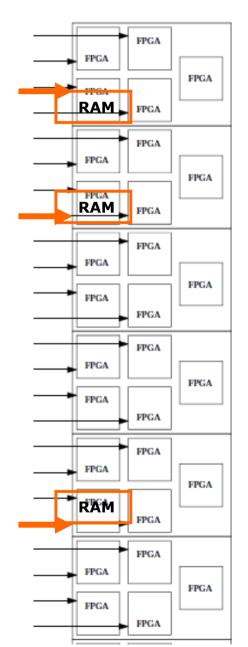
optical links
here not connected

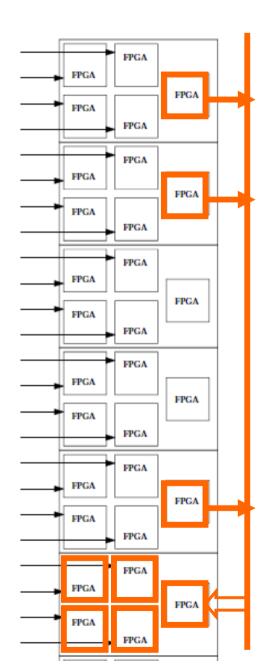
receive data by optical links

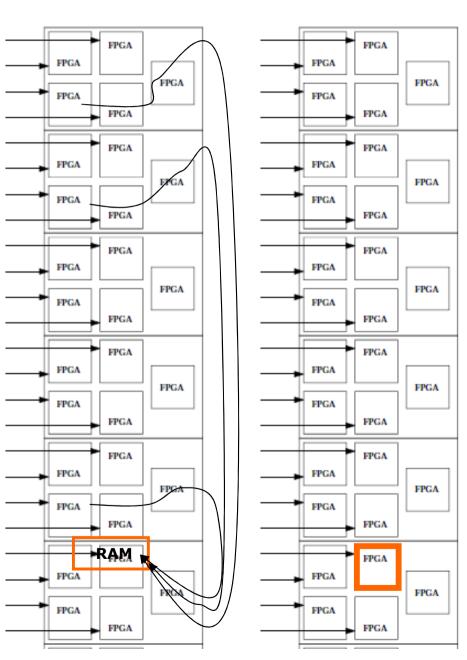
Notify all bookkeeper FPGAs

Move (copy and delete) via ATCA backplane

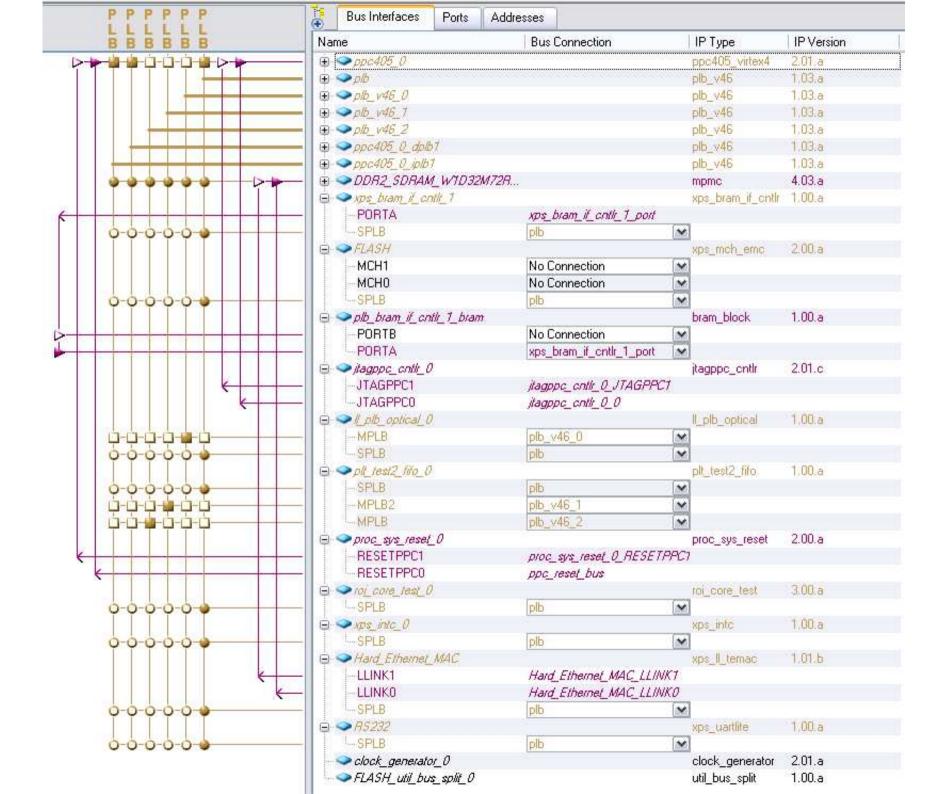
wait for HLT







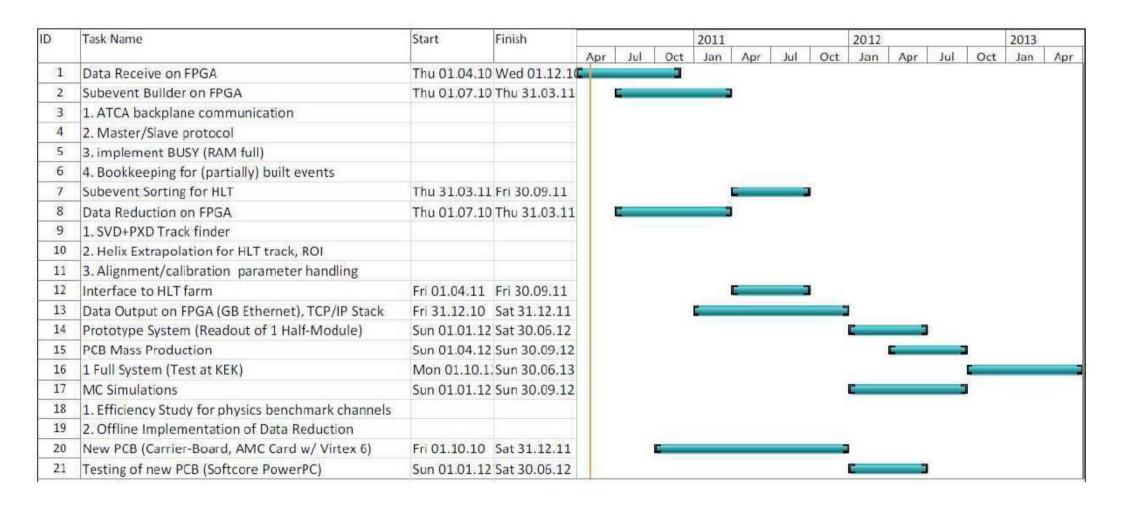
Lange, Münchow, Spruck (Gießen) | PXD DAQ Algorithms



More algorithms: what's the problem?

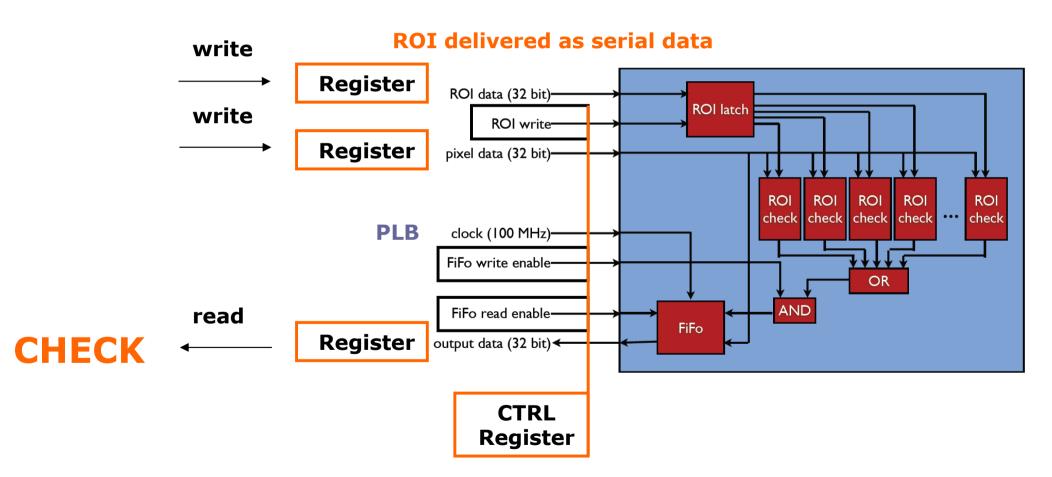
- FPGA resources are limited not only ROI algorithms on FPGA, but PLB bus, FIFOs, optical link, RAM memory controller, ... it is already using >50%
- possible solution: 2nd ATCA shelf
 4 additional CN
 (e.g. for SVD, running the SVD-only ROI algorithm)
- Main problem: was not foreseen neither in the project milestone plan nor in the project financial plan

Cluster finder was not considered yet for the project plan (neither pedestal algorithm)



ROI Algorithm

parallel in ROI



Register #5 (write ACK, read ACK) is not needed anymore (removed now)

cluster finder

- Andreas Wassatsch, ASIC on DHH?
- which algorithm?
 - walking 2-dim and updating, averaging ADC of neighbour pixels
 - sliding window, e.g. sum ADC 3x3 pixel
 - find high ADC, then sum around it
 - -> in any case needs additional arithmetic operations, so probably computational bottleneck
- RAM bottleneck question:
 how to do it, when only touching each pixel 1x
- if we need the cluster finder on CN,
 we would need an something like a "manifest"