

Slow Control for DATCON

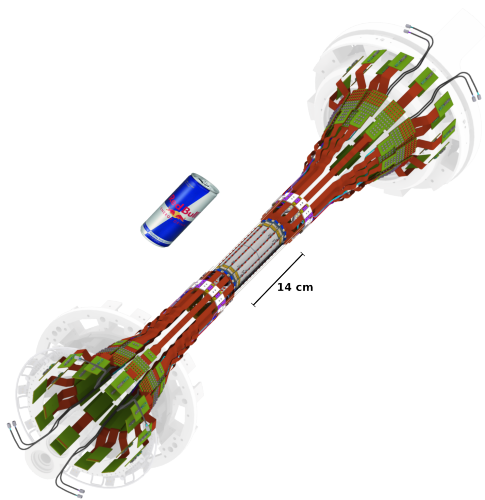
Michael Schnell

`schnell@physik.uni-bonn.de`

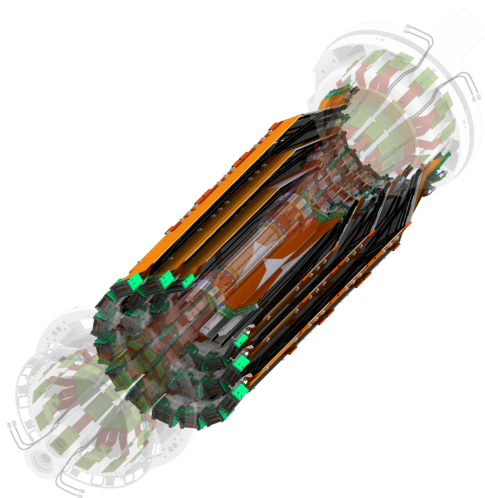
September 23rd, 2014



- 1 Introduction to the DATCON System
- 2 Performance of the Tracking Unit and ROI Calculation
- 3 Slow Control

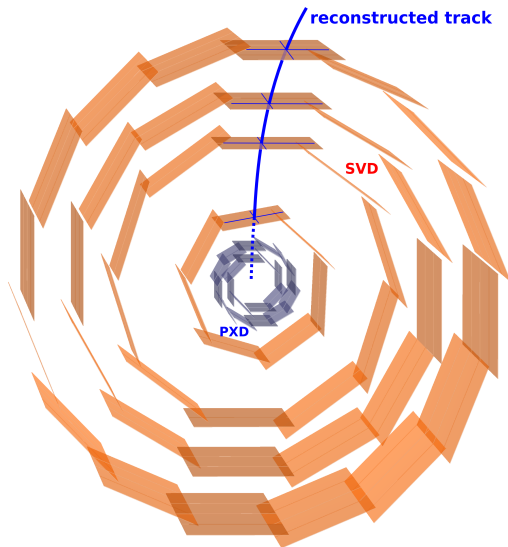


- 2 layers DEPFET Pixel Detector (PXD) with 8 million pixels (avg: 60 Gbps, max 256 Gbps)
- Data reduction required for PXD data (factor ~ 10)
- 4 layers Silicon strip Vertex Detector (SVD)
- Idea: Use hits in the surrounding strip detector, and extrapolate them to the PXD to select usable Pixels

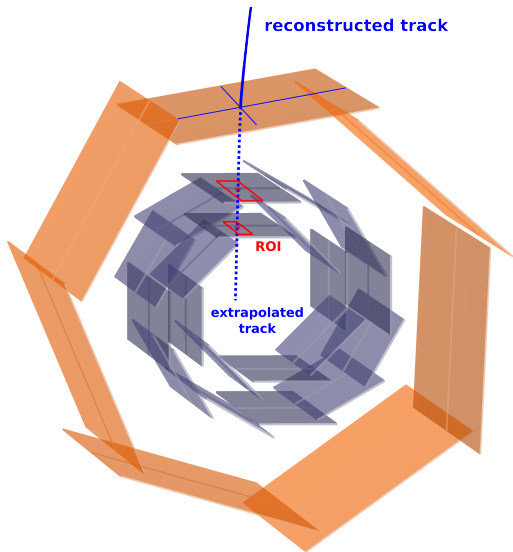


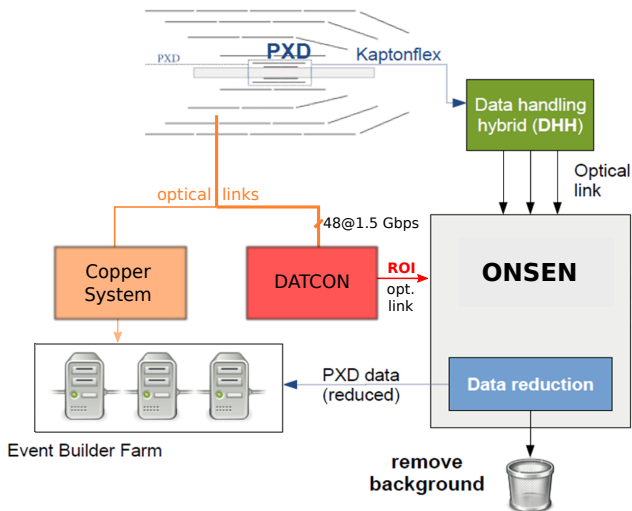
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- Complementary approach with two systems to save as much physics data as possible
- HLT: Track reconstruction based on sector-neighbour finding and neural network
- DATCON: Fast FPGA-based track reconstruction system using the Fast Hough Transformation

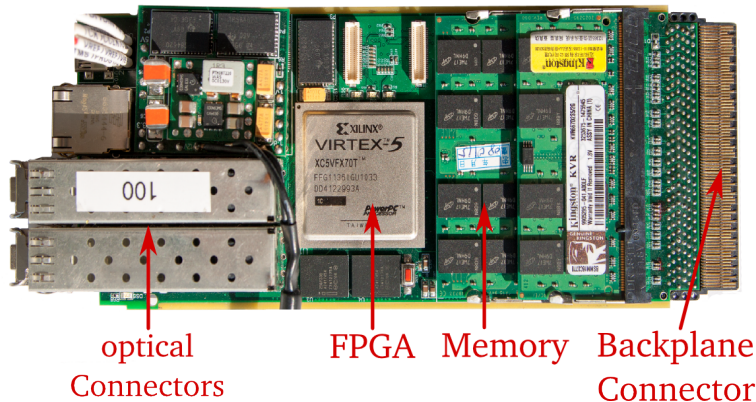


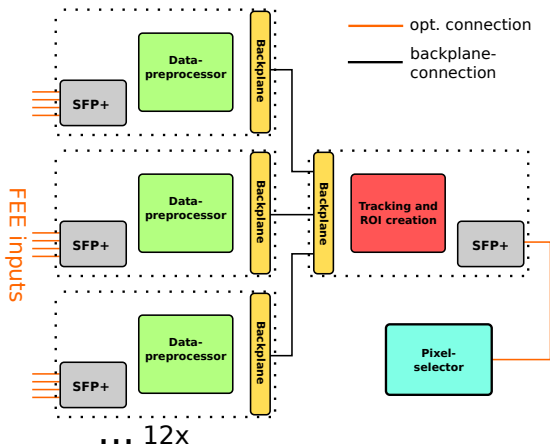
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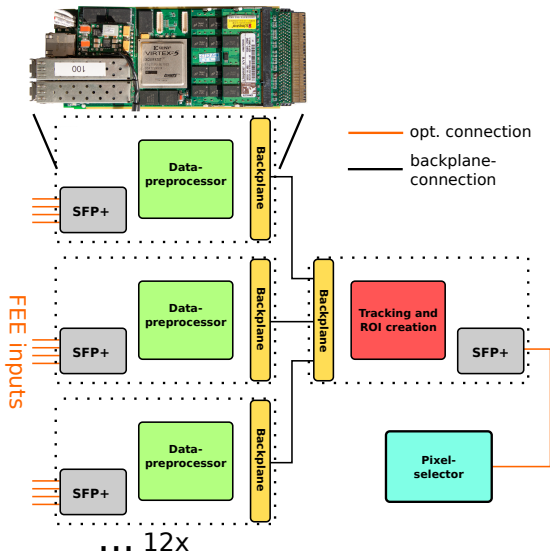


- Virtex 5 FPGA with 4 optical 6.25 Gbps transceivers
- Backplane with 6 ports and 1x Gbit Ethernet port
- 128x DSPs and 4 GB external memory





- Data Acquisition Tracking Concentrator Online Node (DATCON)
- 48 optical links from the SVD Front End Electronics (FEE)
- Average expected data rate: 6 Gbps
- 12x AMC for data acquisition and preprocessing
- 2x AMC for Tracking and ROI calculation



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- Concentrator (12 AMCs):
 - Acquire data from the SVD FEE (over Finesse Transmitter Board (FTB))
 - Decode SVD Data (4 run modes possible)
 - Noise filter (only in run mode 2)
 - Clustering
 - Coordinate translation and transmitter to tracking AMC(s)
- Tracking (one maybe two AMCs):
 - Reconstruct helix track parameters (with Fast Hough Transformation)
 - Extrapolation to PXD planes
 - Create ROIs, size depending on several criteria (e.g. track radius, number of iterations...)
 - Transmit ROIs to ONSSEN

- Tracking is based on Fast Hough Transformation
- Hough Transformation is able to find and fit straight tracks

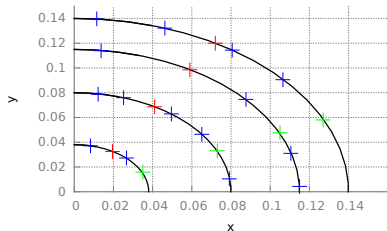
Simple Hough Transformation

$$y_i = m \cdot x_i + a \xrightarrow[\text{trafo}]{\text{Hough}} a = -m \cdot x_i + y_i$$

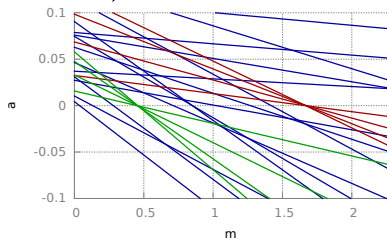
- Also works for arc tracks after conformal transformation

Conformal Transformation

$$x' = \frac{x}{(x-x_n)^2 + (y-y_n)^2}$$
$$y' = \frac{y}{(x-x_n)^2 + (y-y_n)^2}$$



Hough transformation



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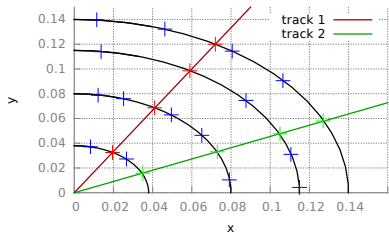
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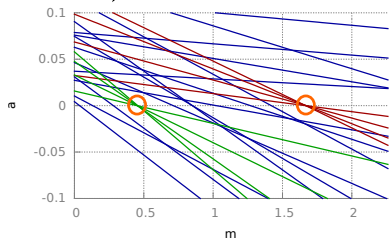
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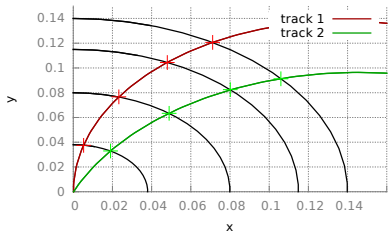
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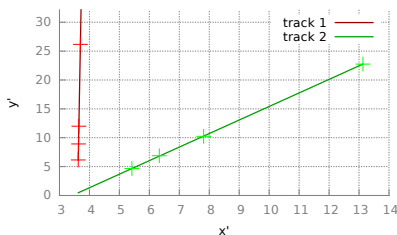
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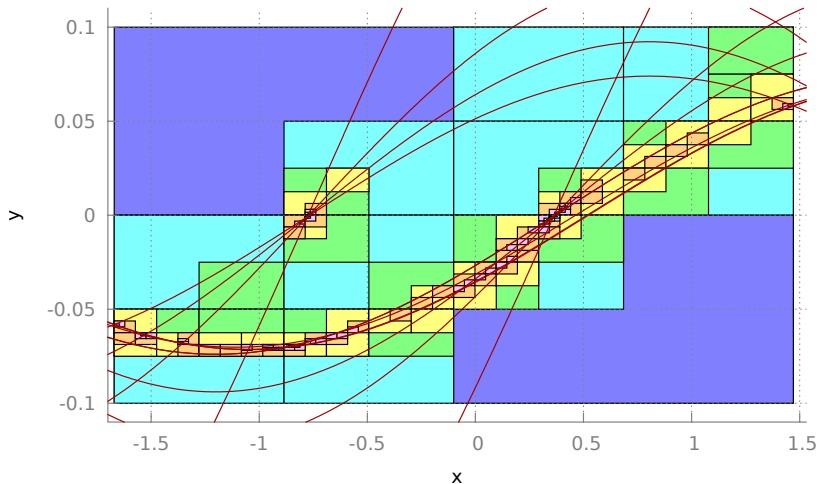
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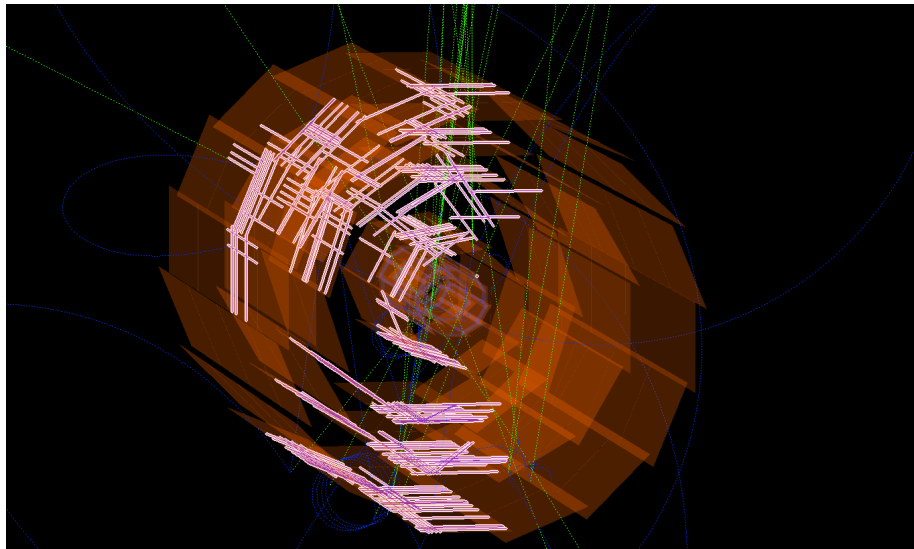


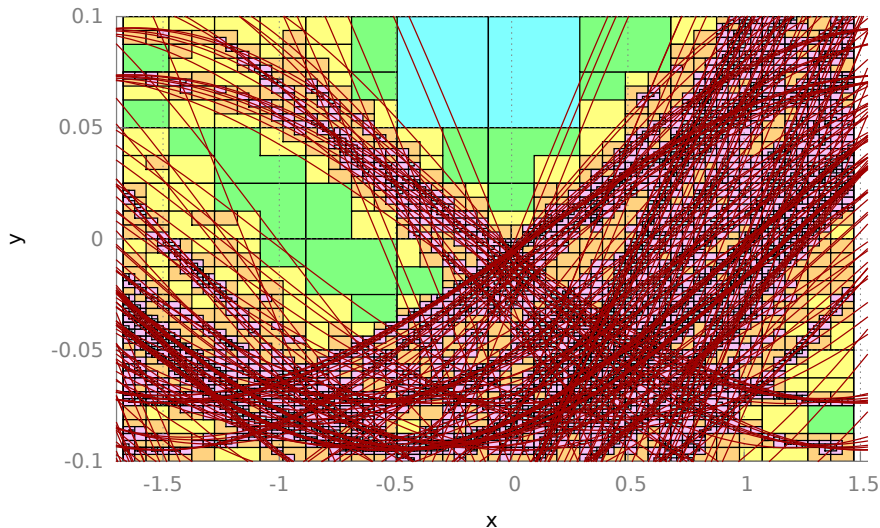
Conformal Transfo.



Fast Hough Transformation (colors represent depth of iteration)

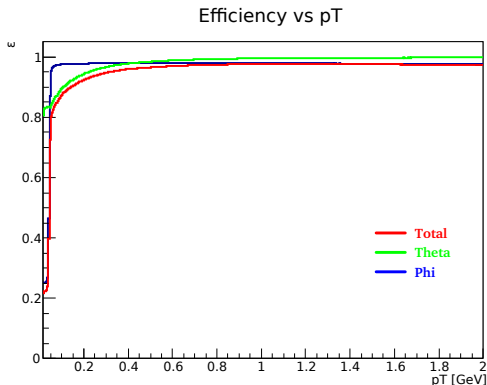






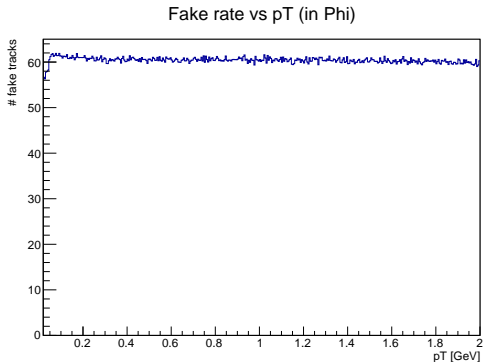
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- Constant high efficiency in r - φ @ 0.98 % down to 40 MeV
- Theta efficiency falls under r - φ -efficiency at 300 MeV
- Caused by linear fit of sine-shape like function in z -direction



- Total efficiency limited by theta (later compensated in ROI extrapolation, small but long ROIs)

- Average fake hits constant at 60 hits/event
- High number of fake hits caused by high occupancy events
- Or by close tracks events



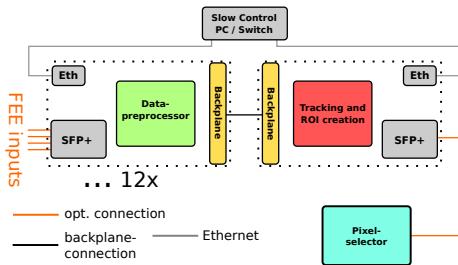
- Caused by the TC merger algorithm (lots of combinatorics in hits)
- Should be fixed with new Hough Space clustering algorithm and cut-off threshold

- 640 million events (10 tracks per event), Momentum from 50 MeV to 3 GeV and Background (QED, RBB, Toushek, Beam-Gas)
- Flexible ROI size from (8x16 px) up to (12x160 px) (depending on momentum estimated by r)
- Total ROI efficiency (number of primary track hits on the PXD inside ROI): 95.2 percent
- Curler extrapolation still missing! (only two MPH per track)
- Data Reduction Factor (DRF): 45

1 Introduction to the DATCON System

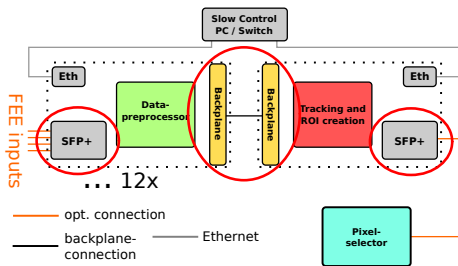
2 Performance of the Tracking Unit and ROI Calculation

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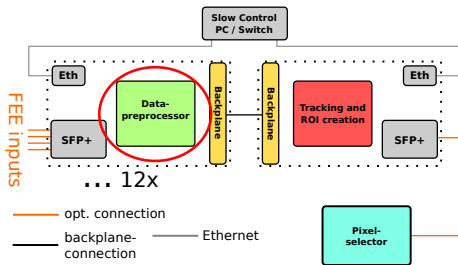
- Present system based on UDP protocol and a custom status 16 Byte long vector payload transmitted over Gbit Ethernet
- Optical and backplane (Aurora) link status: channel up, PLL status, hard, soft and CRC errors

- Concentrator: run mode of the SVD, number of clusters found, storage status: full, empty, (maybe: number of events stored)
- Tracking: number of tracks processed and ROI found, triggers, some statistics about ROI size
- Switch to IPBus possible (also used in DHH)



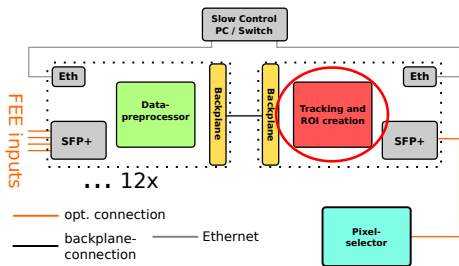
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- DATCON is passive system, when SVD data arrives it is immediately processed without delay (no timing and control signals required)
- Load of FPGA firmware over JTAG chain (same requirements as ONSEN system)
- Reset signals to get the system back to the normal operating state in case of failures
- Monitoring of temperature and voltages of all FPGAs
- Update of several LUTs
 - Alignment constants for all 12 Concentrating AMCs
 - Some settings for the tracking unit
 - Programming the adaptive ROI size registers
- Power cycle and crate monitoring (temperature, fan speed, other health parameters) over IPMI

```
urxvt
tp ~/prog/datcon/trunk/tools/concentrator_ctr1 > ./control

Concentrator Control Panel

CMD > s
Info: Send 1 packet(s) with request
Cont mode: off
Info: Receiving Message from 10.0.0.1:54345 16 Bytes received now, 16 Bytes total
Status word: 1: 7740 3: 0000 5: 0000 7: 5038 9: 5B1C 11: AB00 13: 0000 15: 0000 valid

Lane:          SFP 0          SFP 1          SFP 2          SFP 3
Channel:       up           up           up           down
PLL:           locked        locked        locked        locked
Frame Err:     0            0            0            0
Soft Err:      0            0            0            0
Hard Err:      0            0            0            0
CRC Err:       0            0
Accumulated
CRC errors:    0            Rate: 0/s @ 1408708106
Number of
packet(16 bit): 45957        45509
Run mode:      2            2

Lane:          Back 0          Back 1          Back 2          Back 3
Channel:       down         down         down         down
PLL:           locked        locked        locked        locked

Storage Status
Coord0         Coord1
Empty:         1            0
Full:          0            0
CMD > █
```

```
urxvt
tp ~/prog/datoon/trunk/tools/tracking_ctrl > ./control

Tracking Control Panel

CMD > s
Info: Send 1 packet(s) with request
test 0
Info: Receiving Message from 10.0.0.1:54345 16 Bytes received now, 16 Bytes total
Status word: 5580 0000 0000 4055 18DC 9505 0000 0000 valid

Lane:      SFP 0      SFP 1      SFP 2      SFP 3
Channel:   up        down      up        down
PLL:      locked    locked    locked    locked
Frame Err: 0         0         0         0
Soft Err:  0         0         0         0
Hard Err:  0         0         0         0

Storage Status
Coord      ROI 1      ROI 2
Empty:     0         0         0
Full:      1         0         1
State:     0
CRC Err:   0
CRC Num:   0      Rate: 0/s @ 1408713125

Back 0      Back 1      Back 2      Back 3
Lane:      down      down      down      down
Channel:   down      down      down      down
PLL:      locked    locked    locked    locked

Tracking Stats
Total:     23517 tracks
Rate:     290.333 tracks/s
Avg:      0.699 tracks/event
Trg:      415.100 trg/s
CMD > █
```

- Monitoring of the Finesse Transmitter Board (FTB)
- B2link register access done by Katsuro
- FADC slow control?

Thank you for your attention!

