

# VXDTF studies: Current Status of TrackCand Converter Modules

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# Motivation for SpacePointTrackCand and Converter Modules

## Why do we need SpacePointTrackCands and Converter Modules?

- FilterCalculator shall work with SpacePoints in the future
- Some of current problems should be circumvented by the use of SpacePoints
- VXDTF returns SPTCs (in the future) but genfit works with GFTCs → conversion in both directions needed

### Glossary:

- SPTC - SpacePointTrackCand
- GFTC - genfit::TrackCand



## Basic Working Principle of Converter Modules

- Using **Relations** between **Clusters** and **SpacePoints**
- exemplary for GFTC2SPTCConverter:

```
for all Cluster in GFTC do  
  if Cluster not marked as used then  
    clusterSPs ←  
    Cluster.getRelationsFrom<SpacePoint>()  
    tcSpacePoint ← get appropriate from ClusterSPs  
    add tcSpacePoint to SpacePointTrackCand  
    mark all Clusters used by tcSpacePoint as used  
  end if  
end for  
add additional information to SpacePointTrackCand
```

- for SPTC2GFTCConverter vice versa without having to find appropriate Clusters



# Getting the appropriate SpacePoint

## GFTrackCand

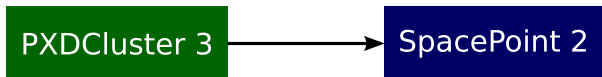
detId	hitId
1	3
2	1
2	2
2	7
2	4



# Getting the appropriate SpacePoint

GFTrackCand

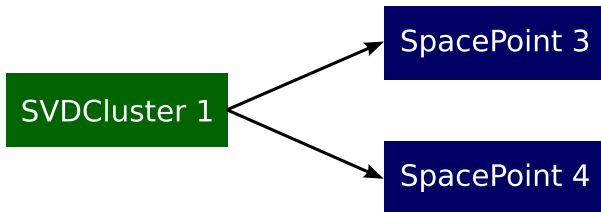
detId	hitId
1	3
2	1
2	2
2	7
2	4



# Getting the appropriate SpacePoint

GFTrackCand

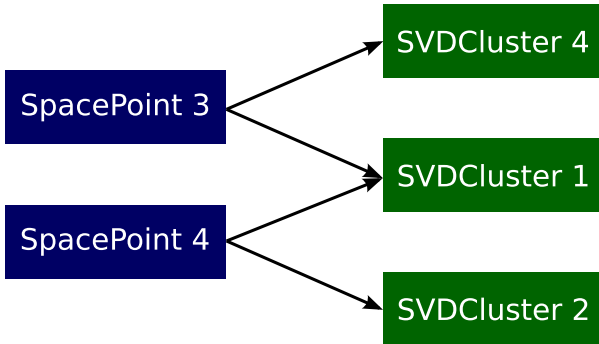
detId	hitId
1	3
2	1
2	2
2	7
2	4



# Getting the appropriate SpacePoint

GFTrackCand

detId	hitId
1	3
2	1
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2	7
2	4



# Getting the appropriate SpacePoint

GFTrackCand

detId	hitId
1	3
2	1
2	2
2	7
2	4

SpacePoint 3

both valid

SpacePoint 4

SVDCluster 4

SVDCluster 1

SVDCluster 2

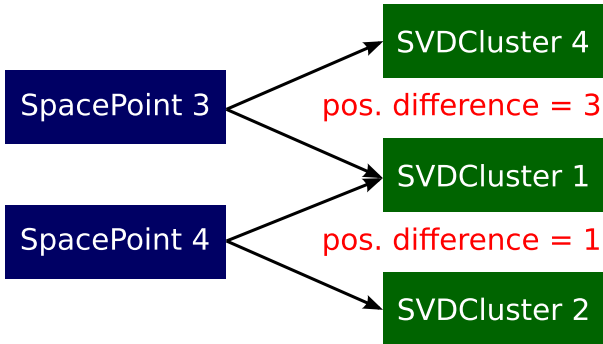




# Getting the appropriate SpacePoint

GFTrackCand

detId	hitId
1	3
2	1
2	2
2	7
2	4



# Getting the appropriate SpacePoint

GFTrackCand

detId	hitId
1	3
2	1
2	2
2	7
2	4

**reject SpacePoint**

~~SpacePoint 3~~

pos. difference = 3

SVDCluster 4

SVDCluster 1

pos. difference = 1

SpacePoint 4

**accept SpacePoint**

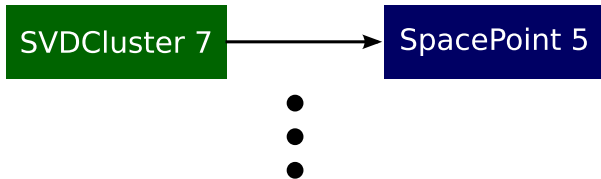
SVDCluster 2



# Getting the appropriate SpacePoint

GFTrackCand

detId	hitId
1	3
2	1
2	2
2	7
2	4



# Getting the appropriate SpacePoint

## Features of the appropriate SpacePoint:

- Clusters are contained in SpacePoint and not already used by another SpacePoint → **SpacePoint** is **valid**
- Clusters have a position difference of 1 → TrackCandHits appear in **consecutive order** in GFTC

## Current Problems/Issues:

- Clusters of GFTC **not checked** for same **sorting parameter** → can lead to **wrong ordered** TrackCandHits in back transformation
- Efficiency rather low if the strictest possible checks are enabled → **~ 70 – 75 %** (for GFTC to SPTC)



## Checking if a TrackCand is curling

Checking if a SPTC is curling by comparing the **direction of flight** for two consecutive SpacePoints (for all SpacePoints in the SPTC):

- if direction of flight **changes** for one SpacePoint → SPTC is curling, can be split at this SpacePoint
- else → SPTC is **not curling**



## Checking if a TrackCand is curling

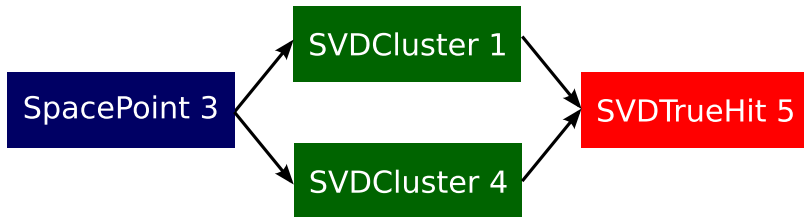
### Algorithm for getting the **direction of flight**:

```
 $\vec{P} \leftarrow \text{TrueHit.getGlobalMomentum}()$   
 $\vec{X} \leftarrow \text{TrueHit.getGlobalPosition}()$   
 $L_P \leftarrow (\vec{X} + \vec{P}).\text{Perp}()$   
 $L_X \leftarrow (\vec{X}).\text{Perp}()$   
if  $L_P > L_X$  then  
     $\text{dirOfFlight}$  is outwards  
else  
     $\text{dirOfFlight}$  is inwards  
end if
```

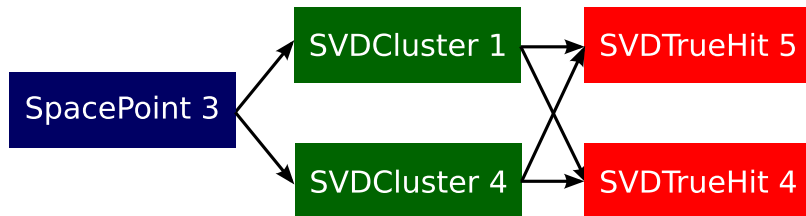
Note:  $\text{Perp}()$  returns the radial component in cylindrical coordinates,  $\rho$



From SpacePoint to TrueHit, ideal case:



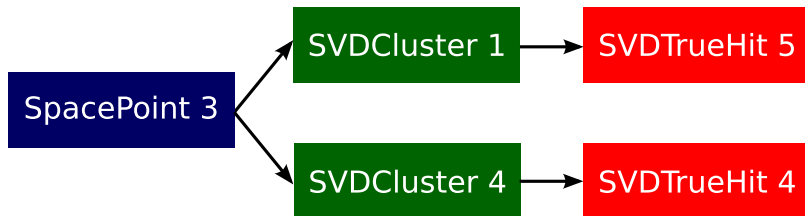
**From SpacePoint to TrueHit, 'issue cases':**  
more than one shared TrueHit



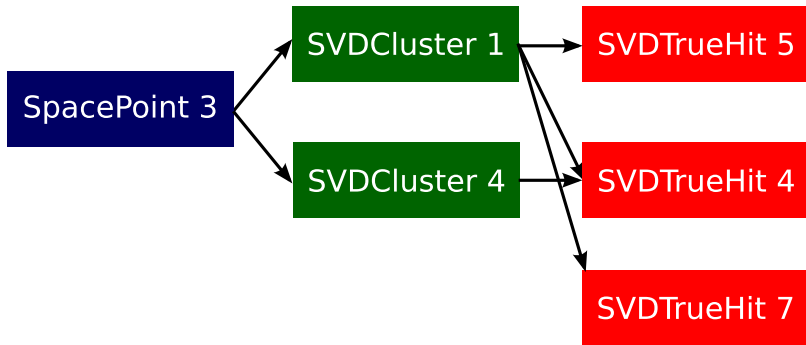


## From SpacePoint to TrueHit, 'issue cases':

no shared TrueHits

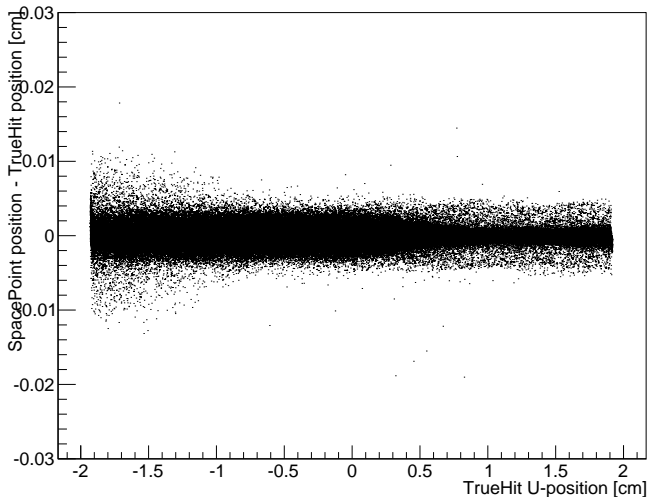


## From SpacePoint to TrueHit, 'issue cases': shared and unshared TrueHits



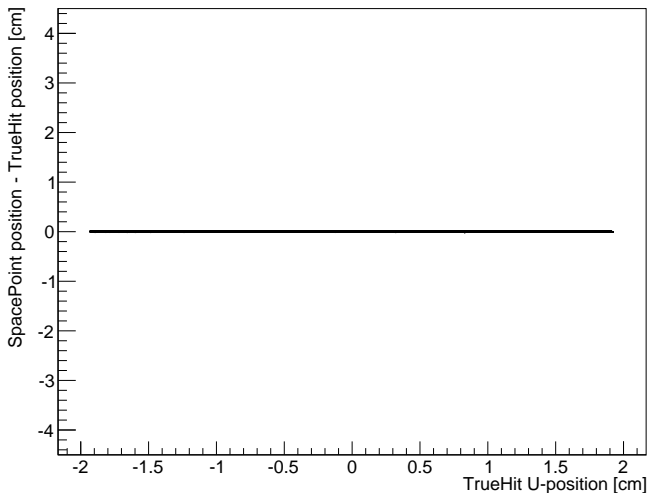
## Position residuals vs. TrueHit position, with 'ideal cases':

position residuals vs TrueHit position U, layer 3

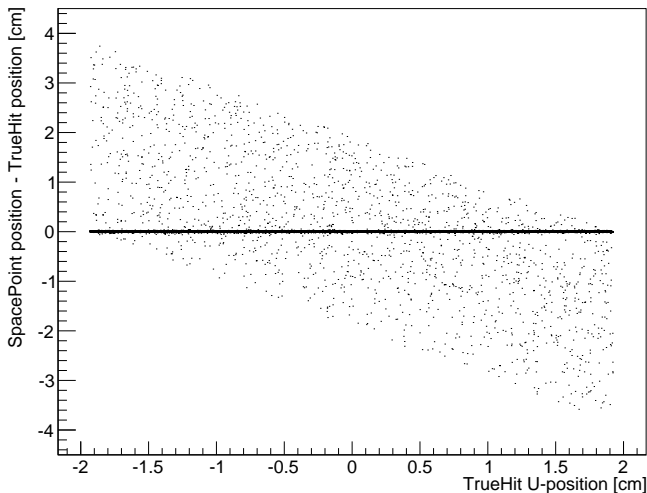


## Position residuals vs. TrueHit position, with 'ideal cases':

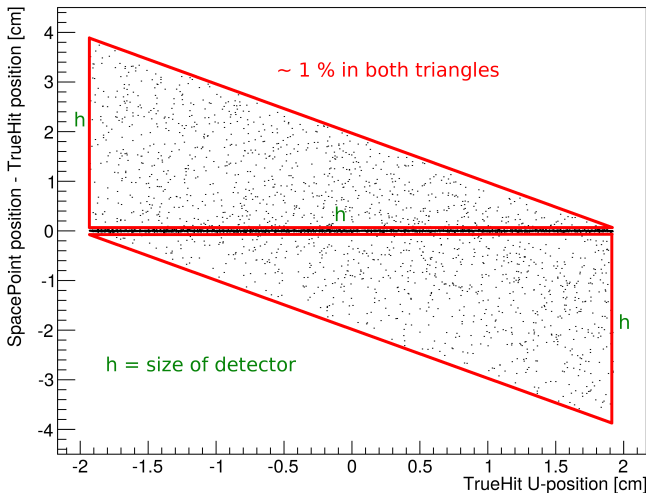
position residuals vs TrueHit position U, layer 3



## Position residuals vs. TrueHit position, with 'issue cases': position residuals vs TrueHit position U, layer 3



## Position residuals vs. TrueHit position, with 'issue cases': position residuals vs TrueHit position U, layer 3



## Outlook: The Topic Of My Thesis

### **Development of a Neural Network Based Track Finder for the Belle II Vertex Detector and Implementation in the Belle II Software Framework**

#### Goals and Next Steps:

- first step: towards generating an enhanced SectorMap with neural networks
- related: feed CA with prior information from neural networks
- long term goal: quality estimation of track candidates with neural networks
- already done: simple MATLAB studies on segment finding (in testbeam setup) with simple neural networks



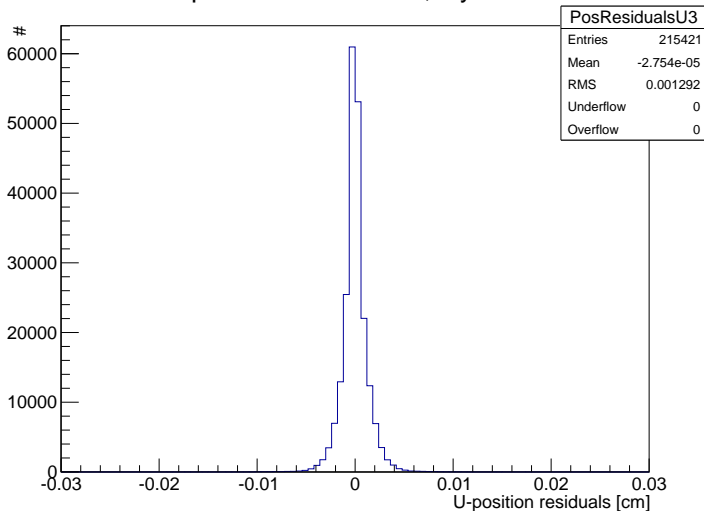
# Thank You!



# Supplementary

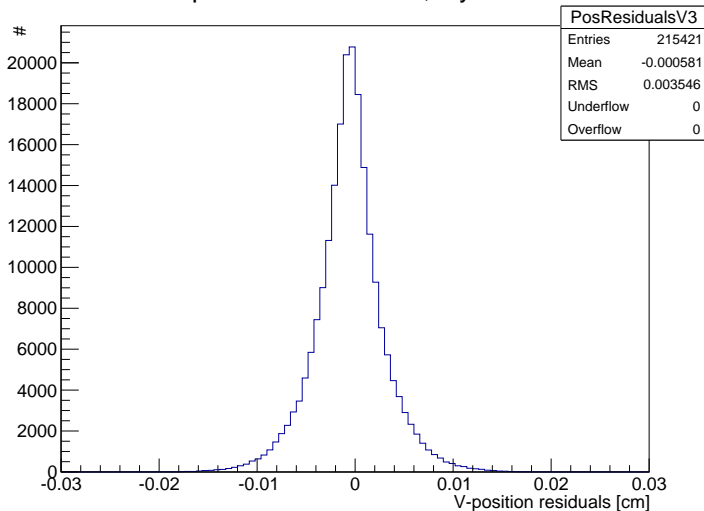
# Histograms of position residuals for ideal cases

## position residuals U, layer 3



## Histograms of position residuals for ideal cases

position residuals V, layer 3



# Position Residuals vs TrueHit position for PXD

position residuals vs TrueHit position U, layer 1

