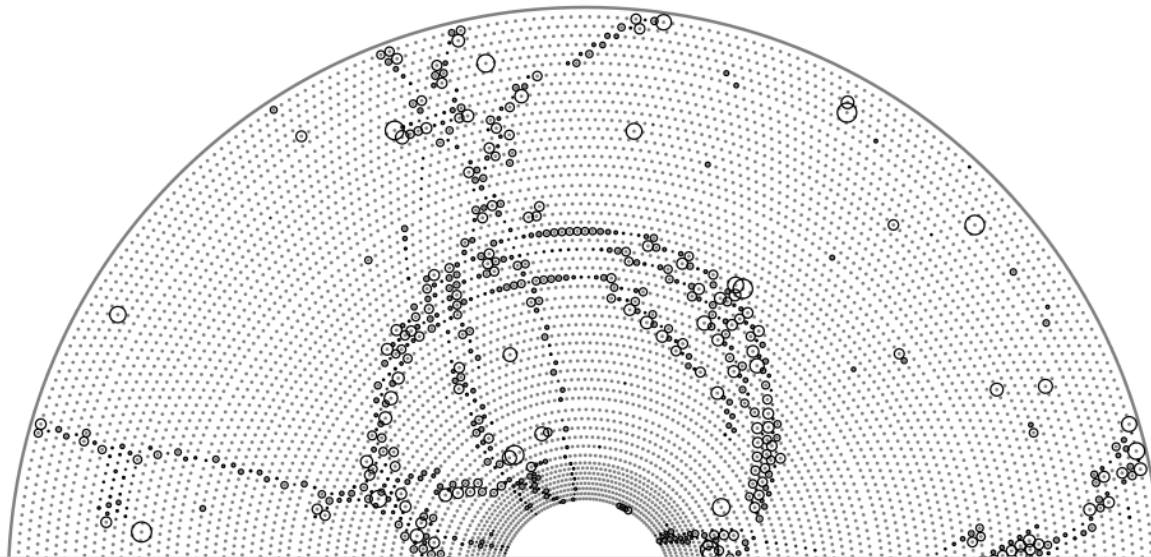


TrackFinderCDCLegendre: current status and new features

Viktor Trusov

04.21.2015 | F2F Meeting in Vienna

Karlsruhe Institute of Technology (KIT)



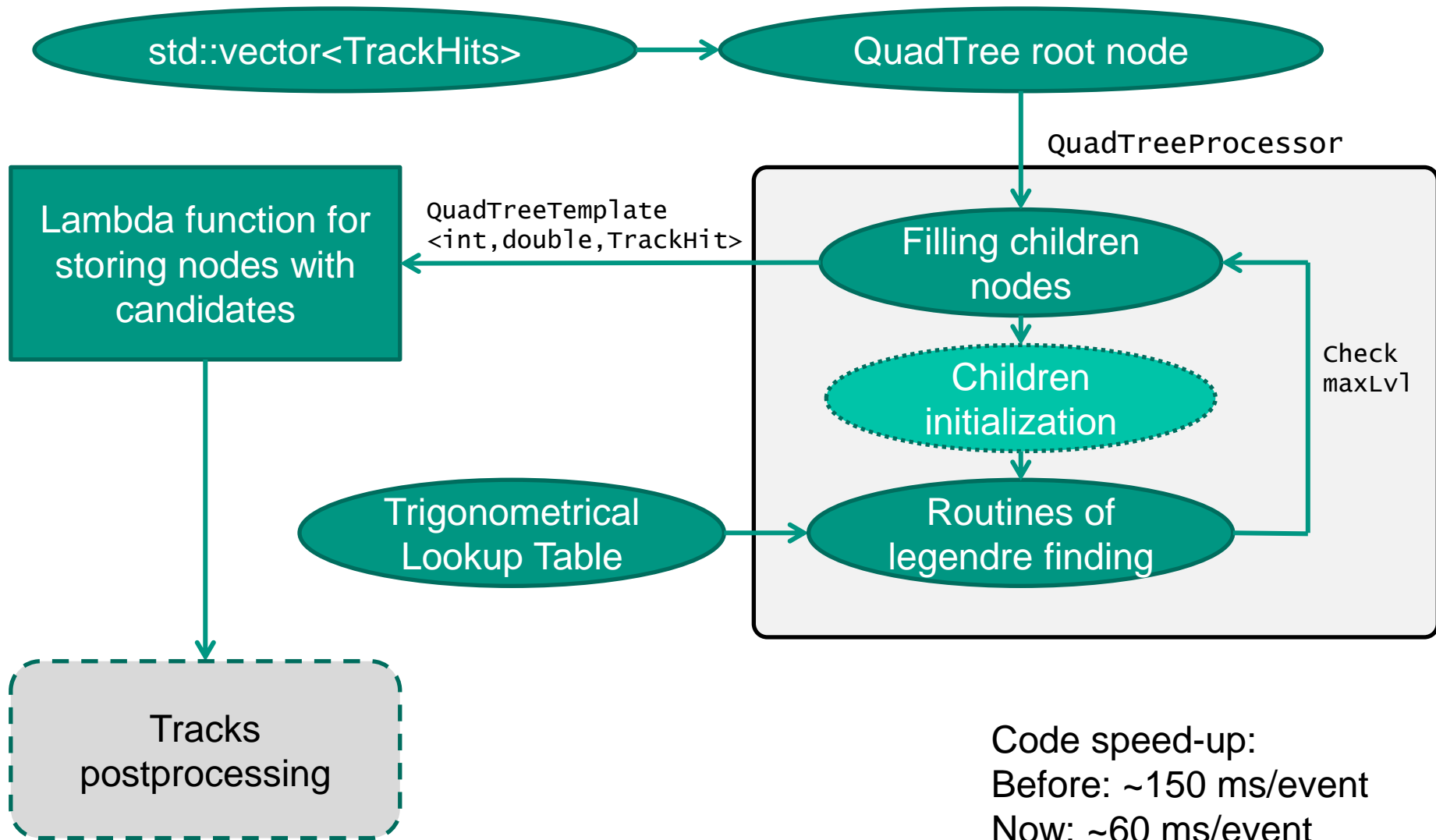
Quad Tree class template

- In Global track finder Quad Tree is the core of the algorithm
- Templating allows to use it not only for global track finding and solve such tasks as
 - Segment combination (see Nils' talk)
 - Apply for stereohits assignment
 - Use different algorithms for 2-d binary search

Quad Tree class template

- `QuadTreeTemplate<typeX, typeY, ItemType>` acts as dataholder:
 - Contains vector of items of type `ItemType`
 - Holds ranges assigned to current node
 - Holds pointers to parent and children nodes
- For working with `QuadTreeTemplate<>` structure processor class should be implemented. Generally must contain:
 - Routines for creating children nodes
 - Routines for filling nodes
- Templated Quad Tree can be applied for 2-d binary search in any phase space
 - But correct routines for working with objects of class `ItemType` should be implemented

How it works



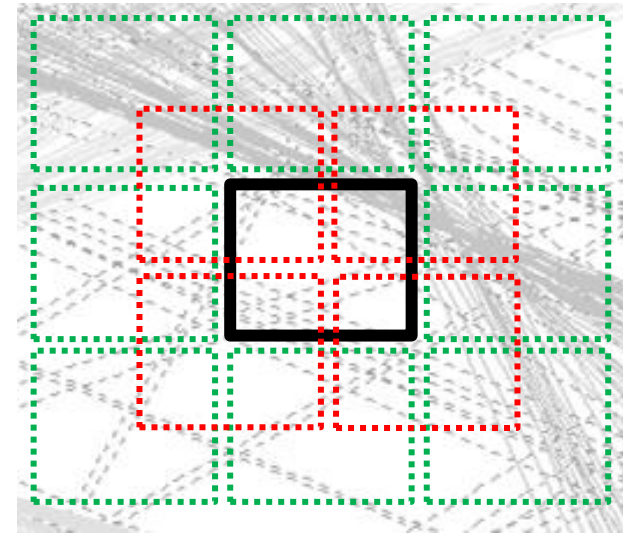
Code speed-up:
Before: ~150 ms/event
Now: ~60 ms/event

New routines for candidate postprocessing: Transformation with respect to given point

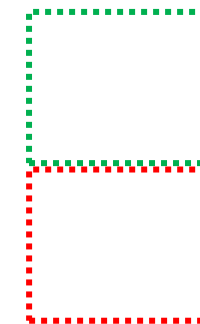
- This routine allows to add more hits to the track using circular fit and single quad tree node
- After fitting track POCA is taken as new reference point
- single QuadTree node is created and filled
 - Boundaries of node defined using parameters of the candidate
 - as $r_0 \pm \Delta r; \theta_0 \pm \Delta \theta$
 - r_0, θ_0 calculated from fit parameters
 - $\Delta r, \Delta \theta$ estimated using p_t of track
 - Legendre transformation performed with respect to new reference point
- This procedure allows to increase hit efficiency
 - Eliminates effect of spread of hits in legendre phase-space

New routines for candidate postprocessing: building associated nodes

- Track could be broken if intersection point of hits in legendre phase space is near to borders of QuadTree bins
- To decrease probability of breaking tracks associated nodes are built and filled
 - 8 neighboring nodes
 - 4 overlapped nodes
- Hits from most populated node is added to the track



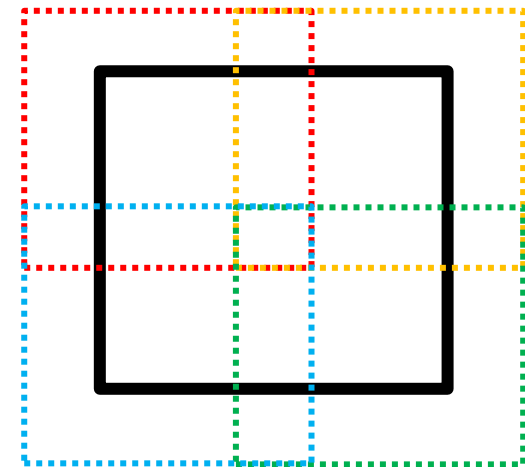
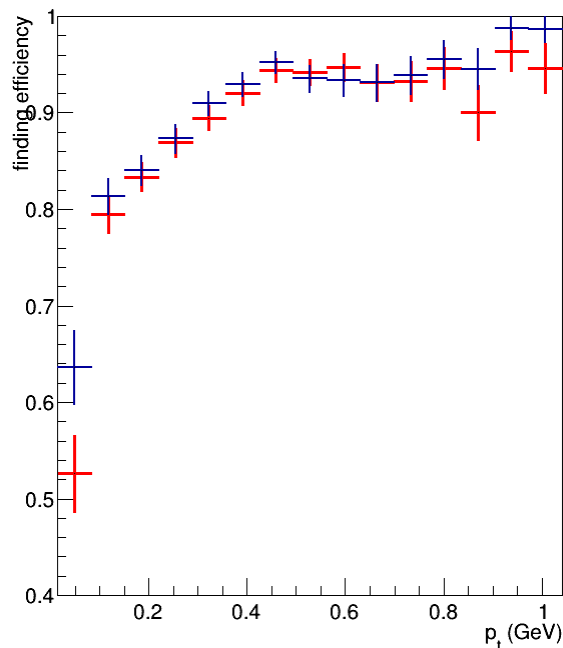
- Initial node



- Associated nodes

Low-pt region

- It turned out that for low-pt region deepness level of QuadTree should be much lower
- With decreasing maxLevel parameter for $p_t < \sim 150$ MeV efficiency was increased
- Another effect – increasing boundaries of children



What we gain?

	fake_rate	finding_efficiency	clone_rate	hit_efficiency
build-2015-04-03	0.3068	0.9155	0.0471	0.5512
build-2015-03-01	0.3150	0.8795	0.0475	0.4999

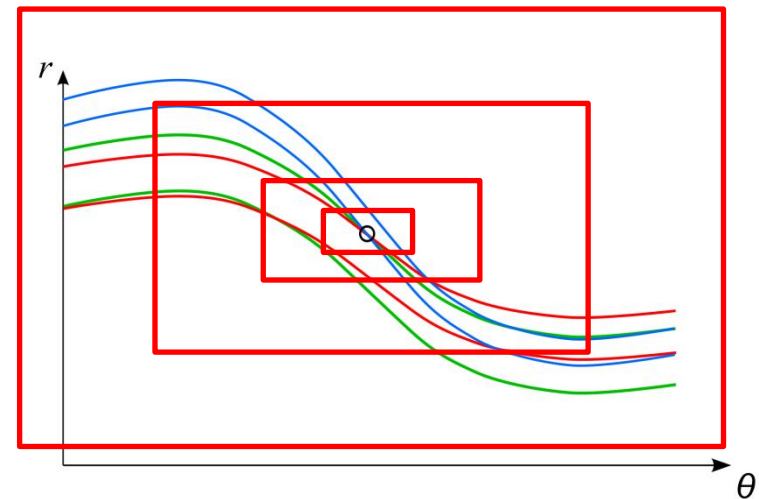
New tool: LegendreResolutionTest

- Intersections of hits in legendre phase space are affected by spreads
- Spread depends on p_t and d_0 of the track
 - Due to energy losses *low- p_t* tracks are mostly affected by spread
 - With increasing d_0 spread also increases
- We are able to tune QuadTree search strategy by introducing resolution which characterizes spread
- Main idea: make tool which allows to estimate best parameters of QuadTree
 - was: node marked as “with candidate” if reached maximal level of QuadTree search
 - should be: node possibly contains candidate if it’s “size” smaller than defined resolution
- In future could be applied to real data

How to measure spread and resolution?

- Using particle gun single tracks were generated
 - $p_t < 2 \text{ GeV}$
 - d_0 – normal distribution with $\sigma = 3 \text{ cm}$
- Using parameters of the track single QuadTree node was created
 - QuadTree node centered
- Boundaries of the node taken as whole legendre phase space
- If all generated hits could belong to the node – reduce its size by factor 2
- Repeat until desired number of hits still belongs to the node

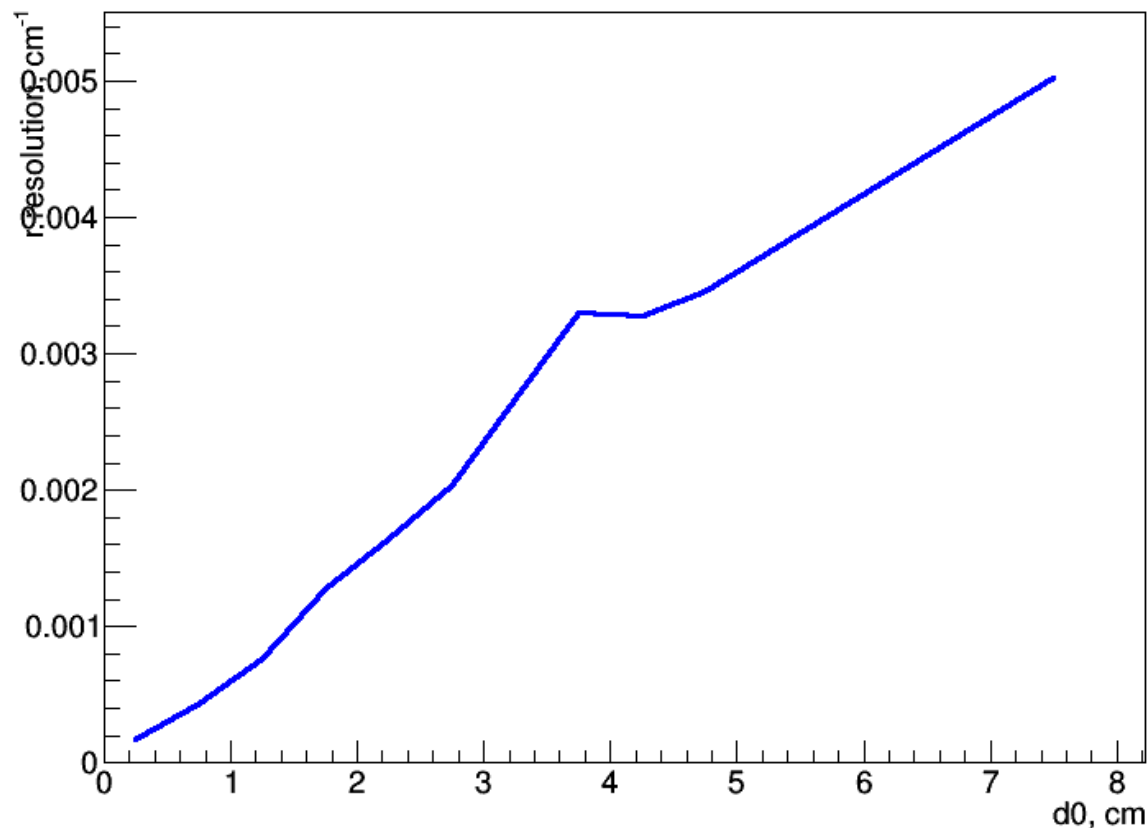
- Final size of node characterizes resolution for track with given parameters



Resolution – d_0

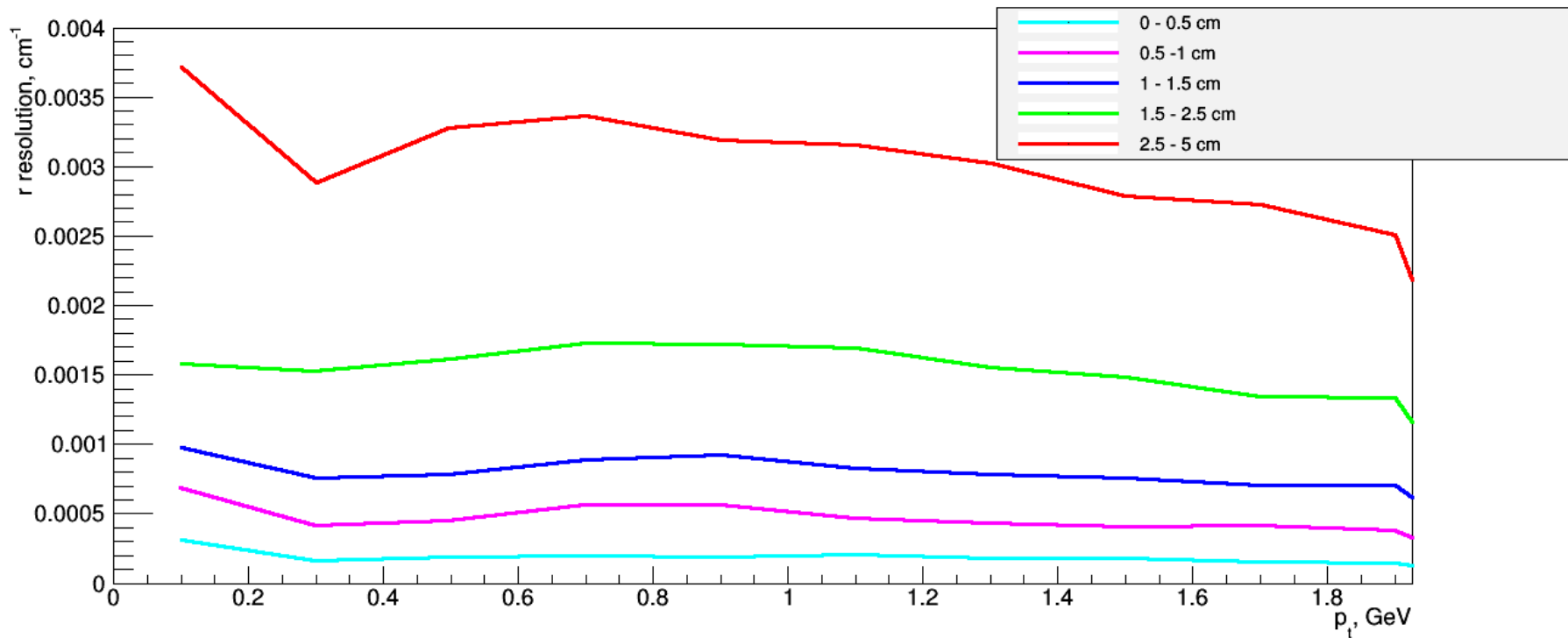
- 40 000 pions were generated
- Resolution strongly depends on d_0

Graph

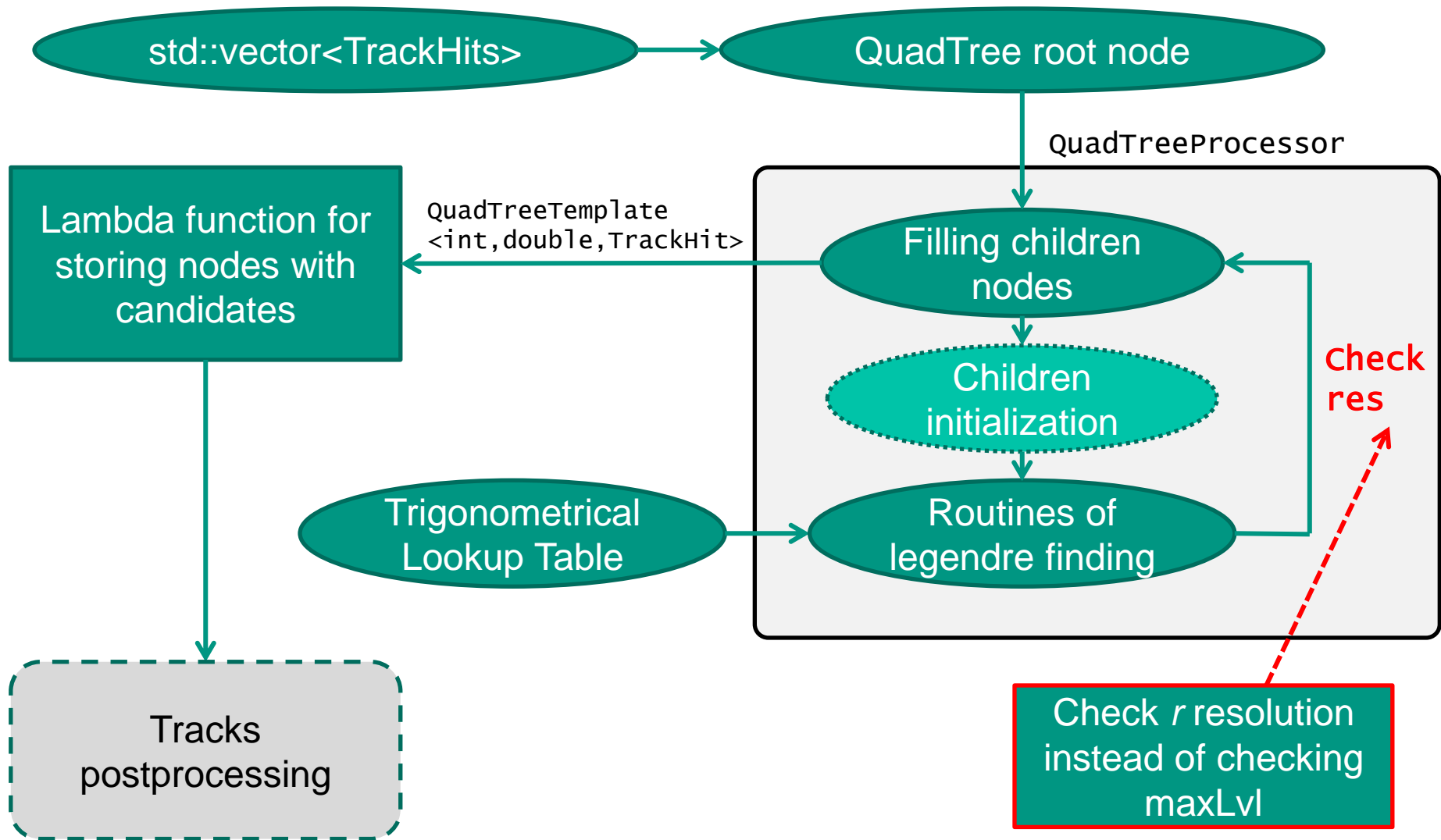


Resolution – p_t

- Resolution also depends on p_t
 - For lower p_t it's higher (as expected)
 - Unexpected: bump around 0.8 GeV

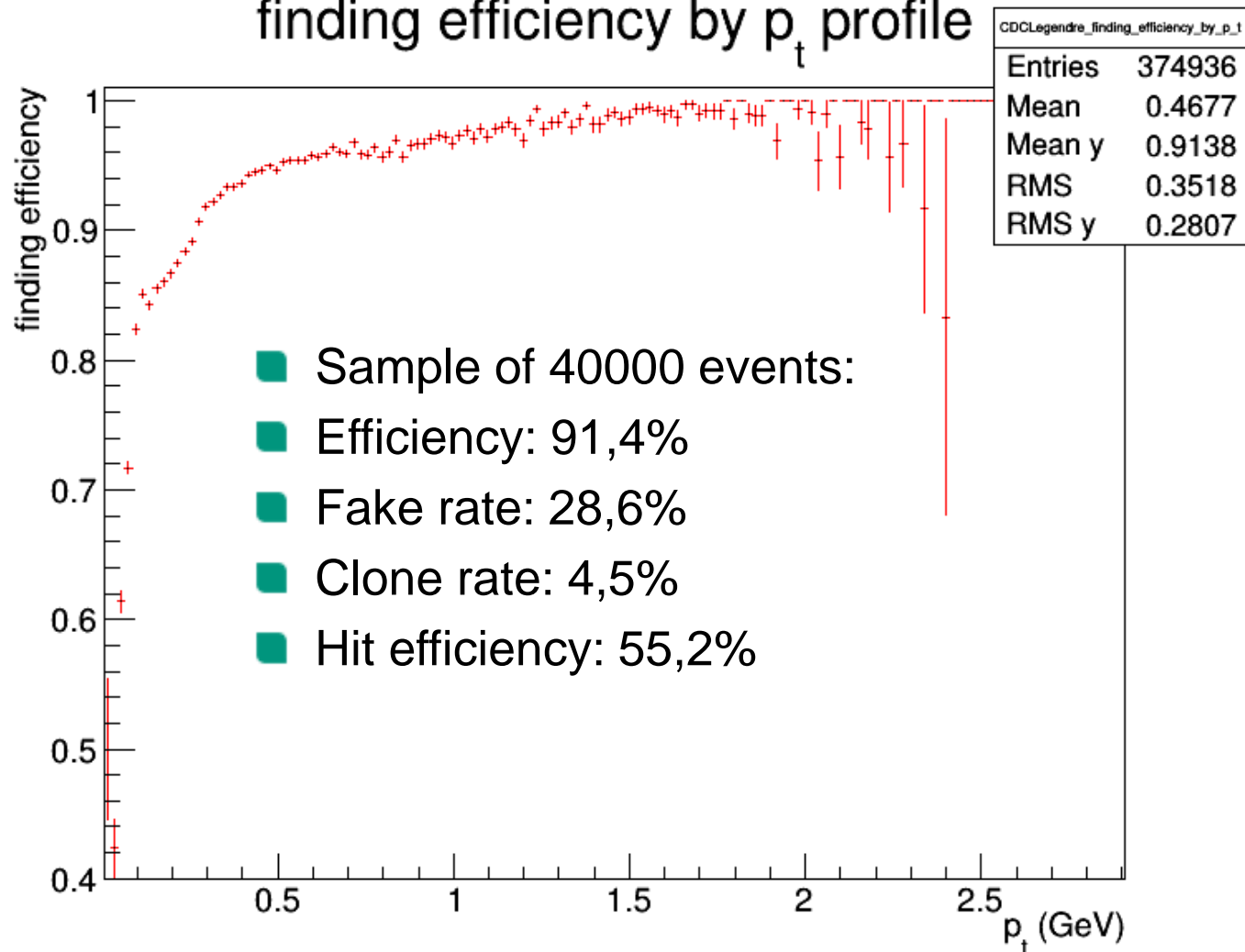


How to apply it



Efficiency

finding efficiency by p_t profile



Conclusions

- Few features were presented
 - Increased quality of track finding
- New tool in development
 - Will help to tune Global track finder
 - May be applied to real data

Thank you for attention!