

# **Recent** Genfit Work

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# Glass Half Full

- we are now on github
- much deeper understanding of the RK code
- Iots and lots of git checkins

#### Glass Half Empty

- no new features in the RK code (yet)
- no way of syncing git repo and basf2 repo
- still no paper, no manual

### Luckily there are other people

- Tadeas Bilka: RecoHits and alignment for BKLM
- Nils Braun: energy loss in track fits
- Markus Prim: progress with electron energy loss





M. Prim and myself now use github for GENFIT devlopment

- master is still svn
- no real way of sync'ing
- > I just clone the git repo into basf2/genfit2/code2 and got from there

https://github.com/TobiSchluter/genfit





I want to determine  $T_0$  in the track fit

- need to understand how to understand how to evaluate Jacobians containing time in the numerical propagation (i.e. RK)
- derived how this works
- then found paper that describes how to evolve Jacobians

#### Wisdom

"Two weeks of work in the laboratory can save you a mornings trip to the library" (well, it did take the better part of a day, not two weeks).

Working through this precisely and reading the literature, I noticed one possible issue.





- ► In the Runge-Kutta we carry the variables  $(q/p, \mathbf{x}, \mathbf{T} = d\mathbf{x}/ds \text{ along some path length } s$ . One important point is that the tangent  $\mathbf{T} = d\mathbf{x}/ds$  is a unit vector.
- But the RK procedure does not guarantee this: for a step of length *S* it calculates  $T_{n+1} = T_n + (S \times \text{some function})$ , based on the Lorentz-force law and the specific RK scheme.
- So after each step, T is normalized, viz  $T \mapsto T/|T|$

#### Question

does this normalization destroy the quality of the RK estimation?

#### Answer

After spending a week developing an RK that behaved better (less non-converged tracks, yay!) and maintained this condition (differential geometry for the win) ... I realized that my ingenious method contained a mistake / incomplete thought and wasn't actually correct





## But I could convince myself that the normalization does no harm

```
(* These should resemble sin / cos series *)
v = RKN[vStart = {0, 1, 0, 1, 0, 0}, fMag, h];
Series[v, {h, 0, 7}] // MatrixForm
```

drixForm=

$$\begin{pmatrix} h - \frac{h^3}{6} + 0 [h]^8 \\ 1 - \frac{h^2}{2} + \frac{h^4}{24} + 0 [h]^8 \\ 0 \\ 1 - \frac{h^2}{2} + \frac{h^4}{24} + 0 [h]^8 \\ -h + \frac{h^3}{6} + 0 [h]^8 \\ 0 \end{pmatrix}$$

normalize[v] // Series[#, {h, 0, 5}] & // MatrixForm

#### trixForm=

$$\begin{pmatrix} h - \frac{h^3}{6} + O[h]^6 \\ 1 - \frac{h^2}{2} + \frac{h^4}{24} + O[h]^6 \\ 0 \\ 1 - \frac{h^2}{2} + \frac{h^4}{24} + O[h]^6 \\ -h + \frac{h^3}{6} + O[h]^6 \\ 0 \end{pmatrix}$$

E.g., with or without normalization the fourth-order RK method that we're using reproduces correctly the power series of sine and cosine up to the fourth order for a planar track in a homogeneous field.





# A speed-up that did not happen

- with a RK one make on fixed-size step. If one wants to find the function values at some intermediate point, one has to reevaluate from scratch
- during boundary finding, we actually go back and forth a few times
- there is a method of polynomial approximation (``dense RK'') that allows to approximate with the same quality at intermediate points at the cost of (in our case) two additional intermediate evaluations
- I implemented this, no speed gained (though it may become interesting in the future)





Our current RK code is complicated, difficult to follow

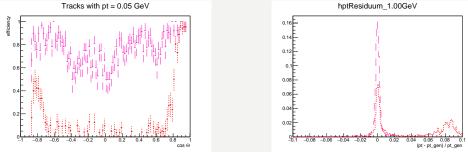
- ▶ it is derived from old Fortran code from the age where you could still outsmart the compiler
- expressions are optimized for minimal redundancy, hard to actually see the Lorentz-force in there
- energy loss is evaluated after propagation, this limits propagation steps, and adds several layers
  of complexity

So, since I had to rewrite this anyway in order to add flight-time to the variables that appear in the Jacobian, I set out to rewrite this, evaluating energy loss in the RK proper.





Of course, this wasn't as simple as I hoped: in my synthetic testcases the new implementation works as well or better than the old code (nice). But in basf2 ...



- efficiciency drops for very low p<sub>T</sub> (others look fine), definitely not what's expected if you deal with energy loss correctly
- weird double peaks in momentum: lots of investigation: current status: 1) doesn't affect tracks in the upward 45 degrees 2) the bad tracks don't take material into account, even though the stepper sees it 3) I would not expect an overestimation of momenta if material is missed





## The good

- Runge-Kutta even with normalization is fourth order
- new RK code is shorter, much simpler

#### The bad

new RK code loses efficiency at low p<sub>T</sub>

# The ugly

- weird double peaks
- my contract runs out end of October ...