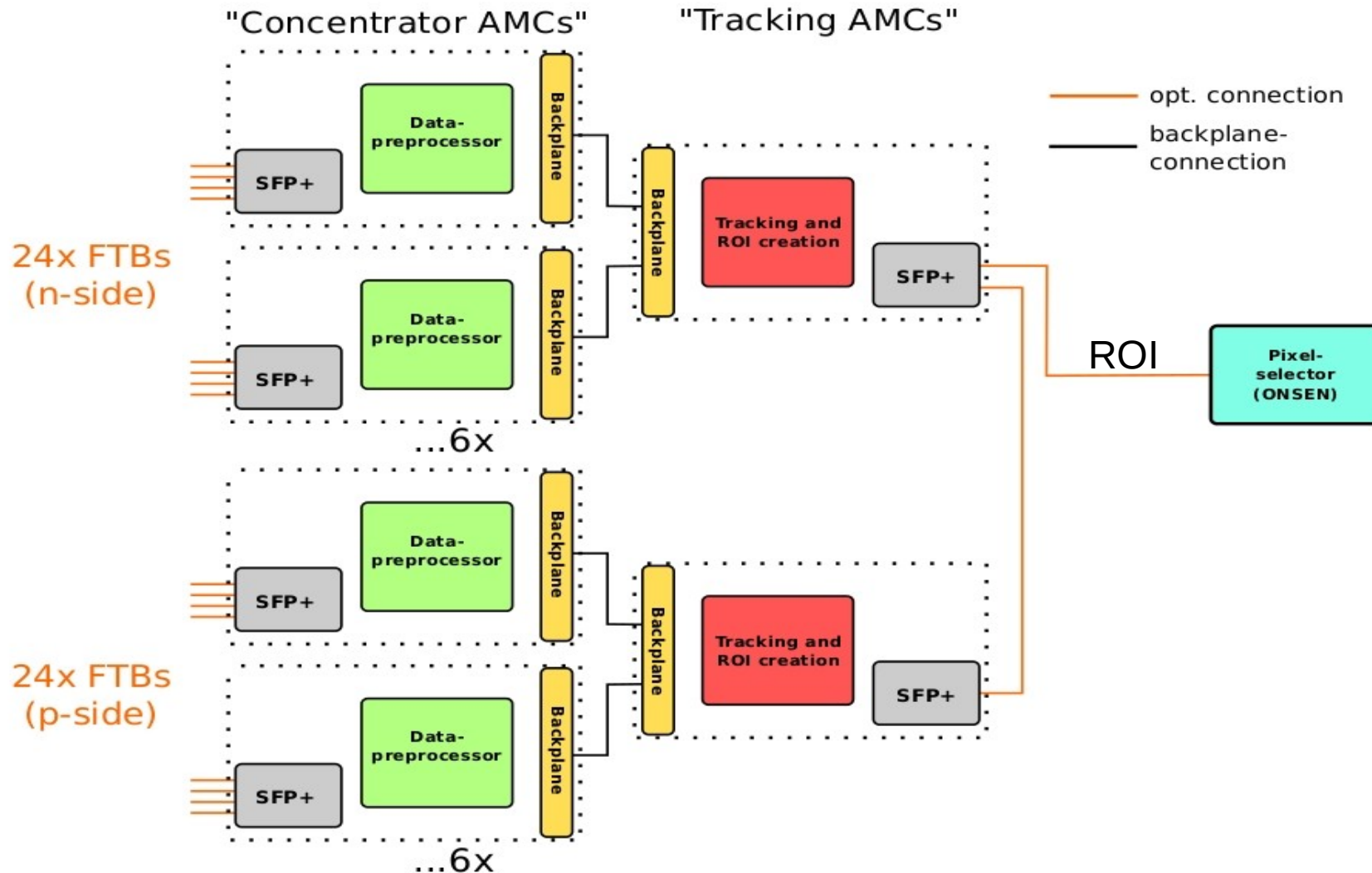


Status of DATCON

Bruno Deschamps, Christian Wessel,
J. Dingfelder, C. Marinas
University of Bonn



Connection topology of the DATCON



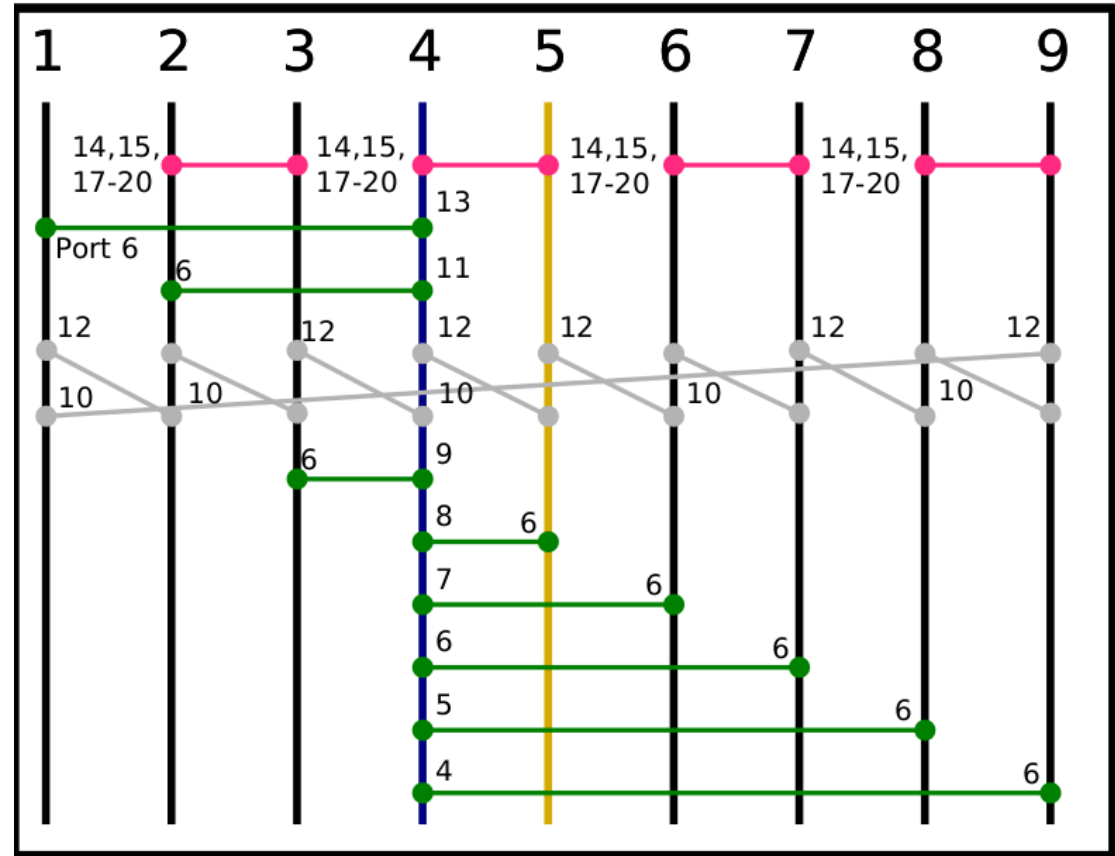
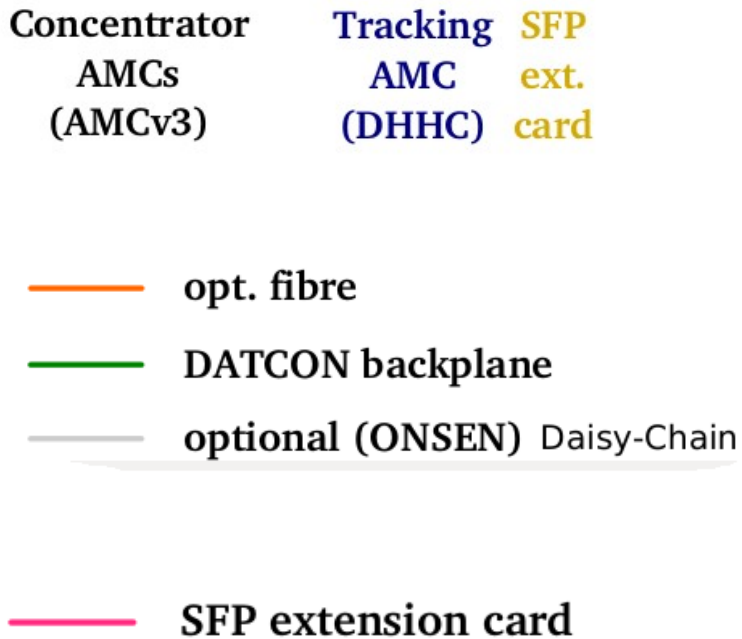
- **AMC v3.1**
 - **Used as concentrator**
 - **15 produced by IHEP-Beijing**

- **DHE v3**
 - **Used as tracking unit**
 - **3 received and recently tested by Igor**

- **SFP extension boards**
 - **Designed by Igor**
 - **5 received and tested**

New backplane design

Backplane Layout (fat-pipes)



- **Backplane designed by Pentair**
- **MTCA format**
- **Expected delivery : March**
- **2 for DATCON, 2 for ONSEN**
- **1 for backup**
- **JTAG connection problem solved**

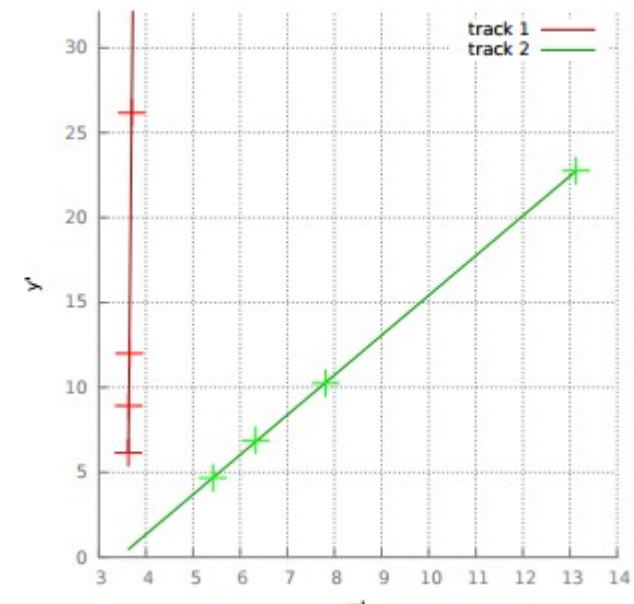
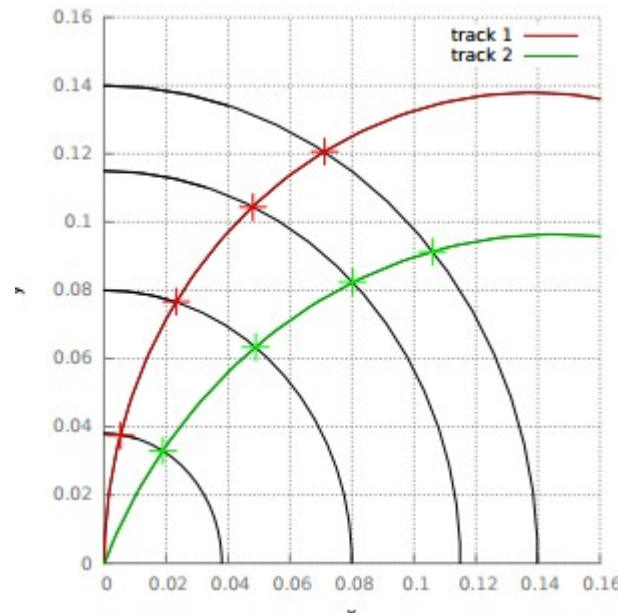


- **Default system for test beam → try to be as close as possible to final system**
 - **2 DHE for the tracking on n and p side**
 - **6 AMCs v3.1**
 - **2 MTCA crate equipped with new backplane**
 - **2 SFP extension boards**

- **If new crates don't arrive on time**
 - **Need to reduce to 3 layer tracking**
 - **P and n side tracking on only one DHE**

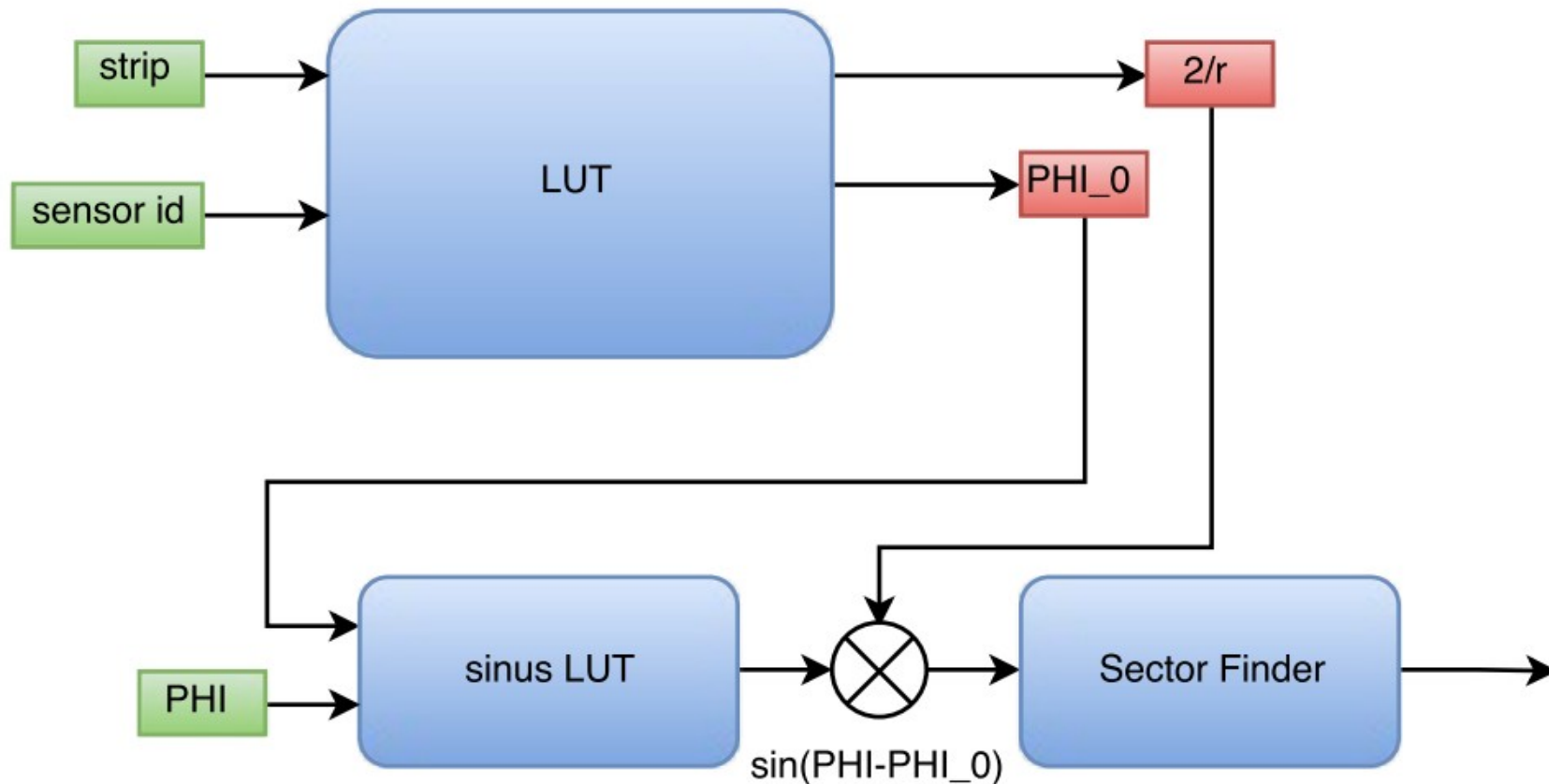
- **Use of the Hough transformation**
- $d = x \cdot \cos(\theta) + y \cdot \sin(\theta)$
- **Can only be applied for straight line (as previously implemented on FPGA)**
- **For circular track a conformal transformation is needed**

- $x', y' = \frac{x, y}{x^2 + y^2}$

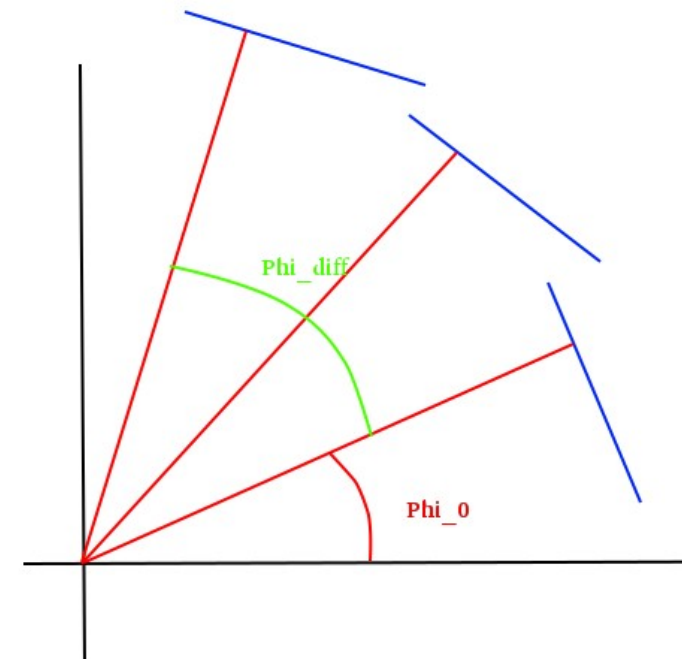
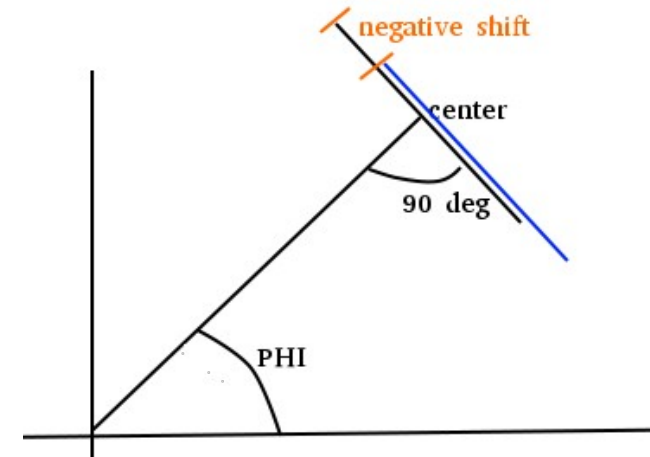


- **Hough transformation**
- **Works directly on circle**
- **Conformal mapping included**
- $$\rho = \frac{2 \cdot \sin(\varphi - \varphi_0)}{r}$$
- **Implementation with LUT**

FPGA implementation for phi



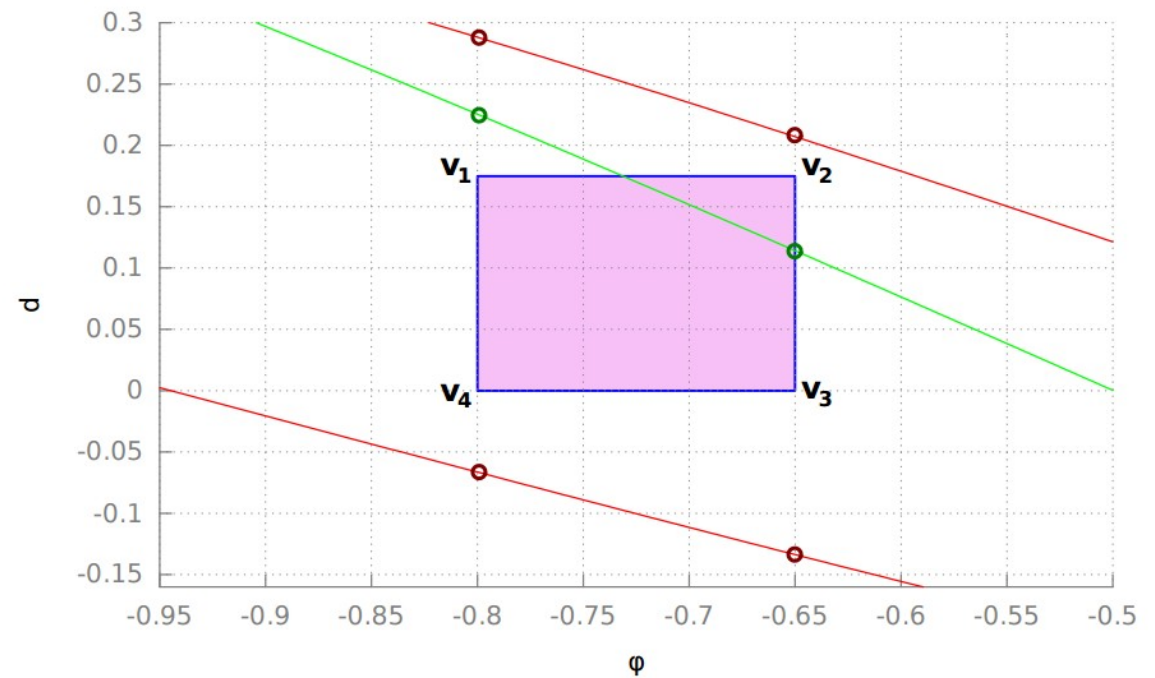
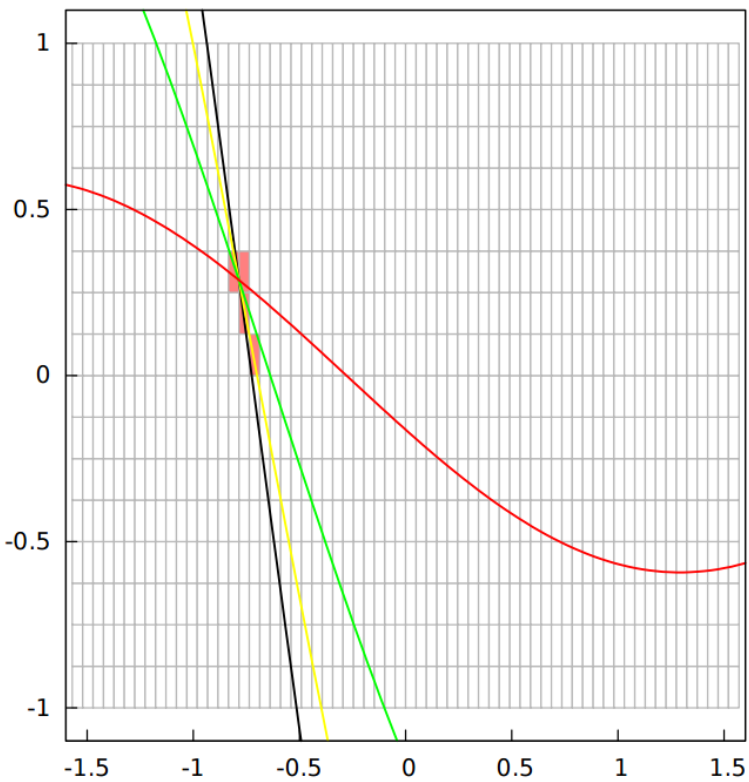
- **Sensor position defined by angle, radius and shift**
- **Only one sensor of each layer stored**
- **Each strip angle and radius can be returned from reference sensor**



- **For test beam**
 - **N strip only defined on y-z axis**
 - **Strip position, pitch and sensor position are known**
 - **No LUT needed**
 - **Not too much resource consuming function returns exact coordinate**

- **For full geometry x-y-z, solution has to be investigated**

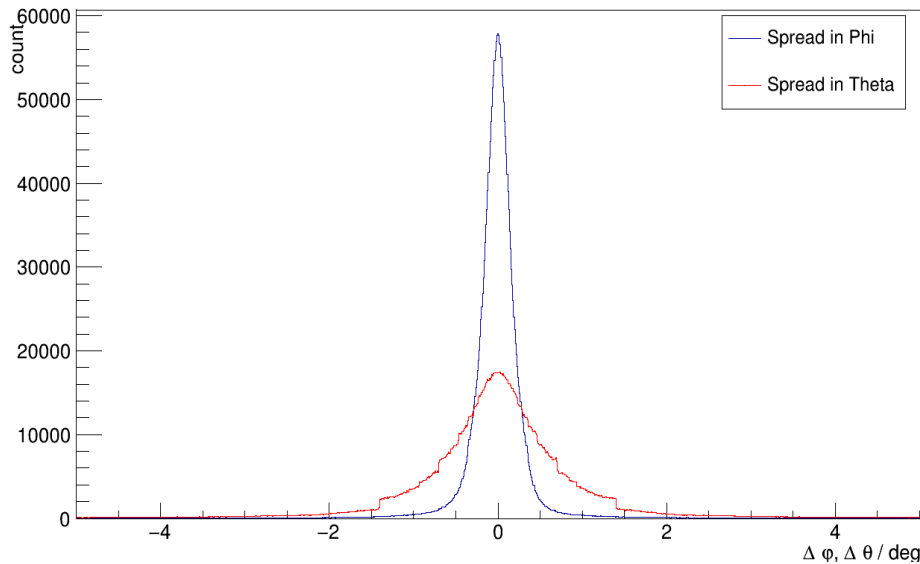
Intersection finder



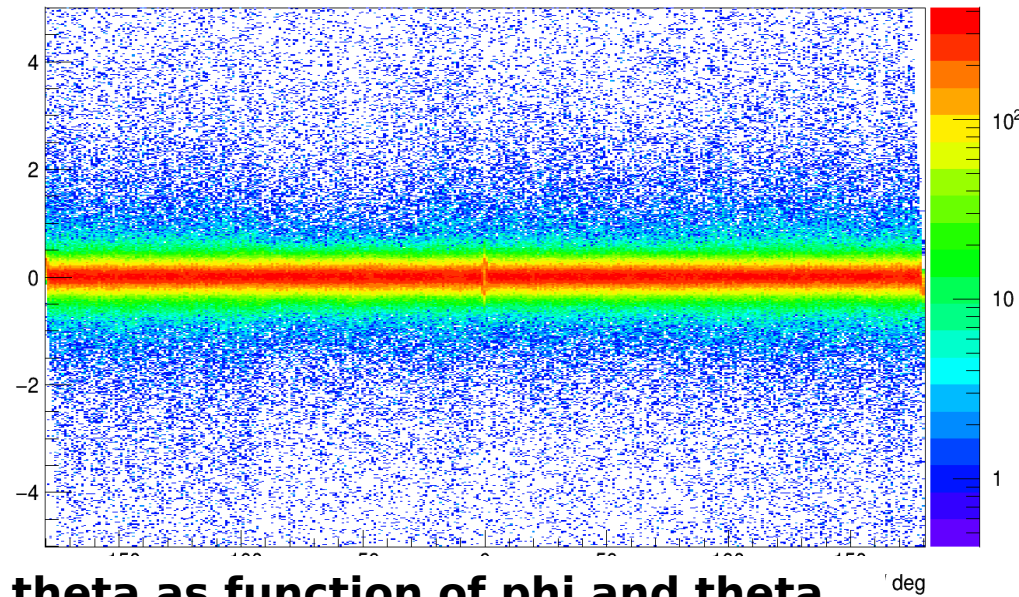
- **Setup:**
 - **Electrons only**
 - **$p \in [0 \text{ GeV}, 3 \text{ GeV}]$**
 - **$\theta \in [17^\circ, 150^\circ]$**
 - **$\varphi \in [-180^\circ, 180^\circ]$**
 - **256 sectors for φ (yields φ and curvature of the track) and 64 sectors for θ (yields θ of the track)**
 - **3 layer reconstruction**

Reconstruction results

Phi and Theta resolution

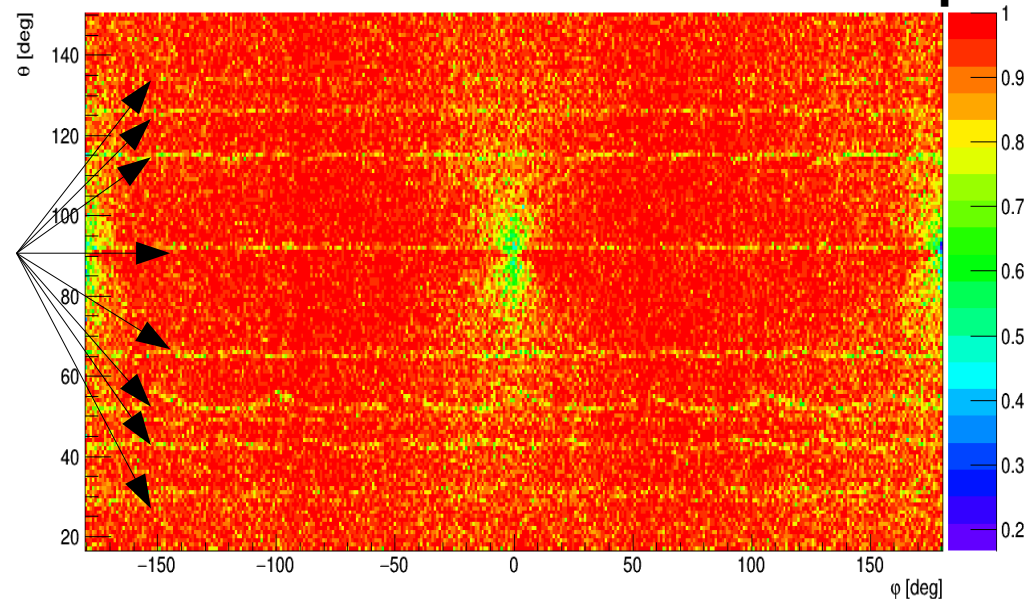


Phi resolution



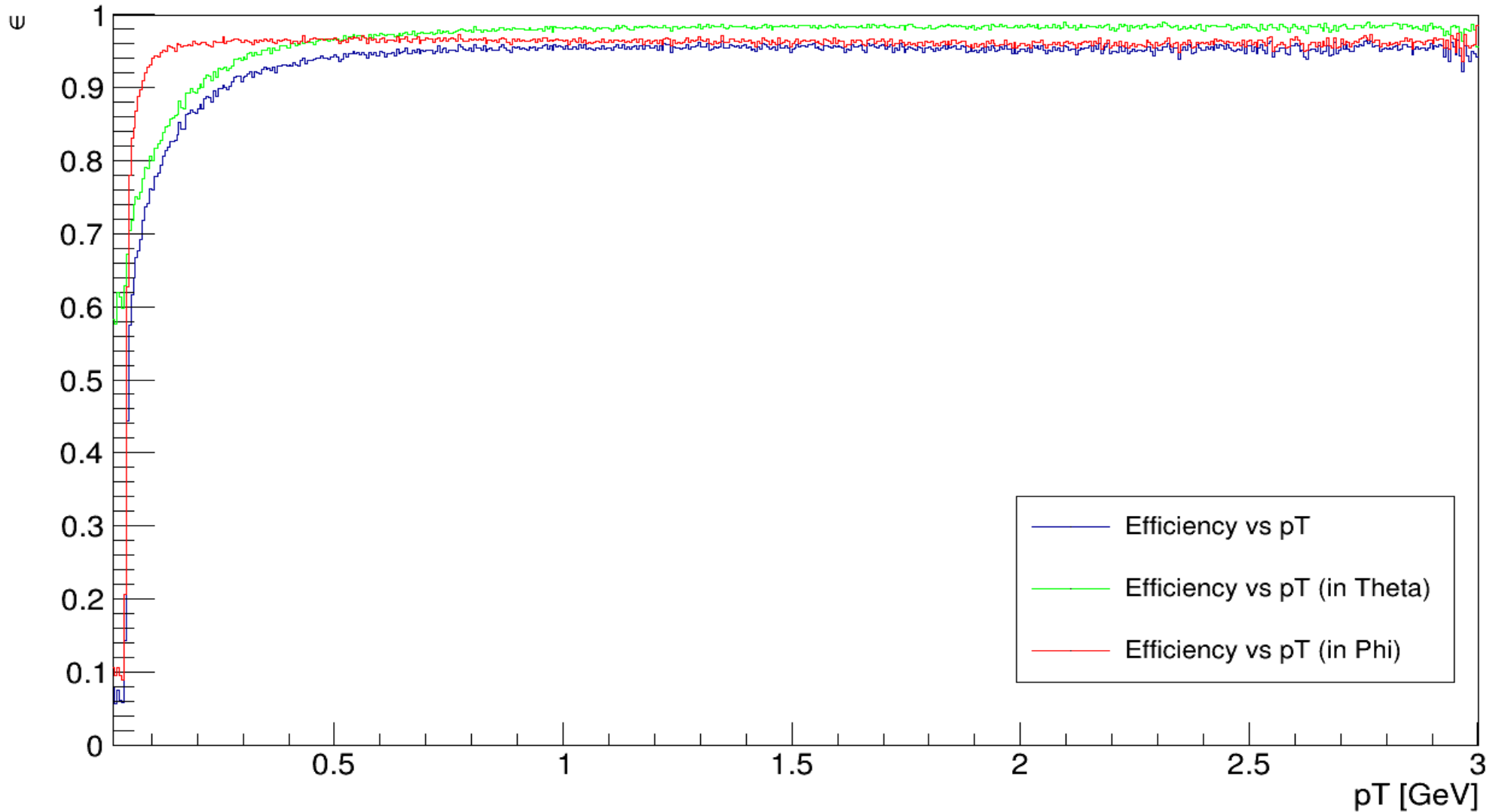
Efficiency of the reconstruction of theta as function of phi and theta

**SVD sensors
glued**



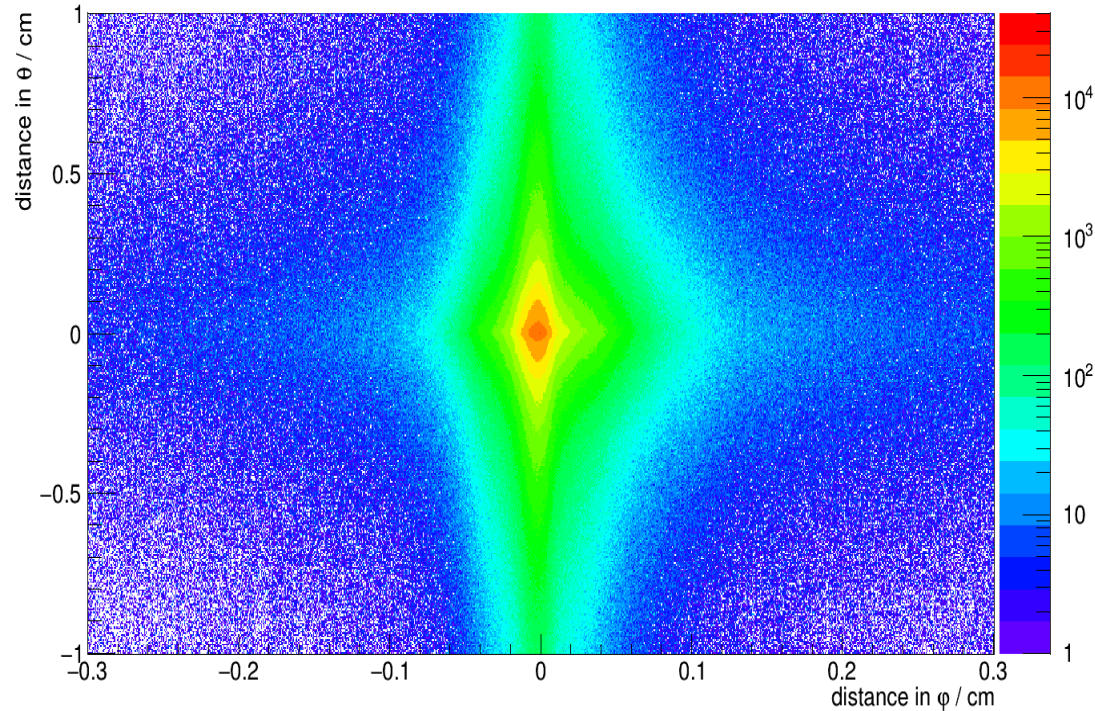
Simulation Results

Efficiency vs pT

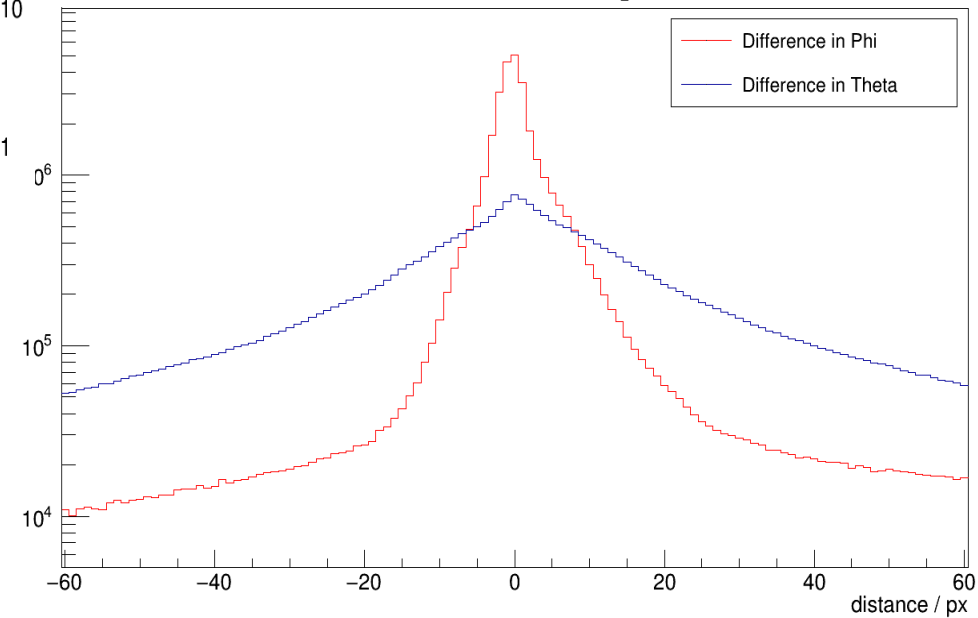


ROI calculation

MPH resolution in phi and theta



MPH resolution in phi and theta



- **The concentrators do not send coordinate anymore but strip ID**
- **The two methods work, tested on simulations**
- **Circle finding method on φ**
- **Straight line finding method on θ**
- **Works better for high p_T**
- **Problems with ROI calculation, esp. for positively charged particles**
- **Next steps**
 - **Prepare test beam (simulation and FPGA)**
 - **Make extrapolation work for positively charged particles**
 - **Improve the tracking and extrapolation algorithm (e.g. hits at detector edge only produce partial ROI)**
 - **Extrapolation on FPGA**
 - **Monitoring of the boards on EPICS**



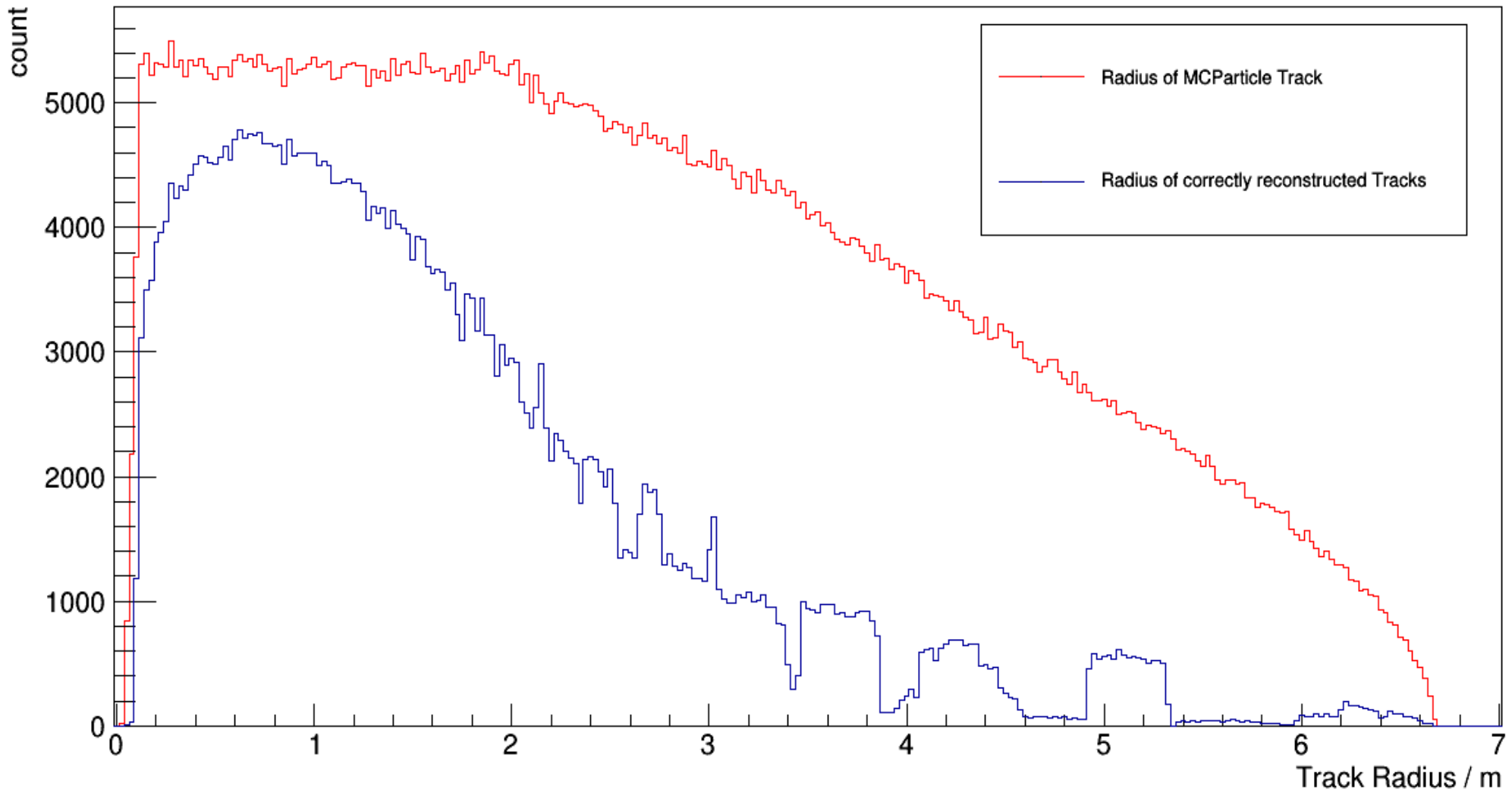
Thank you



BACKUP

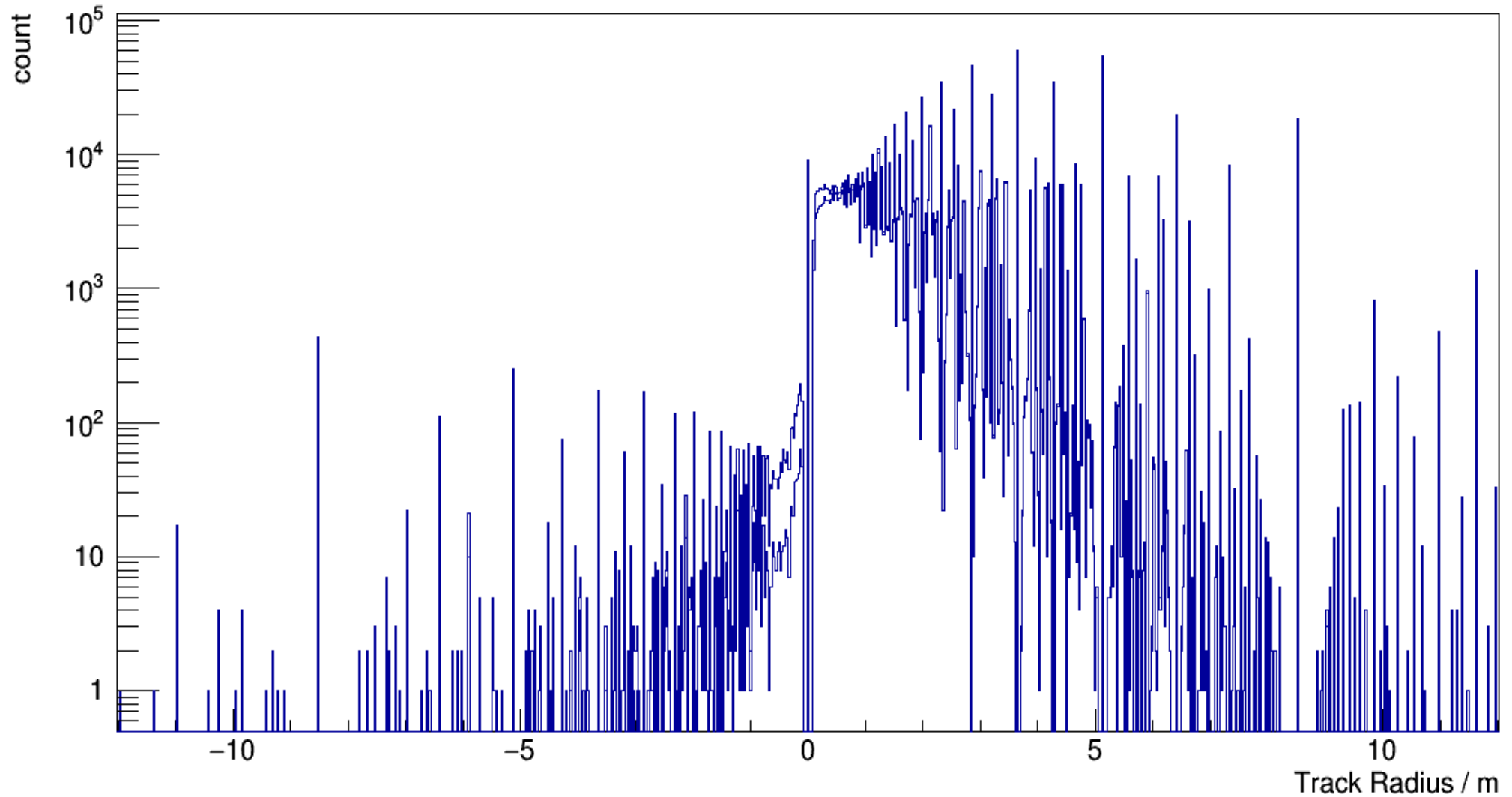
Simulation Results

Radius of MCParticle Track



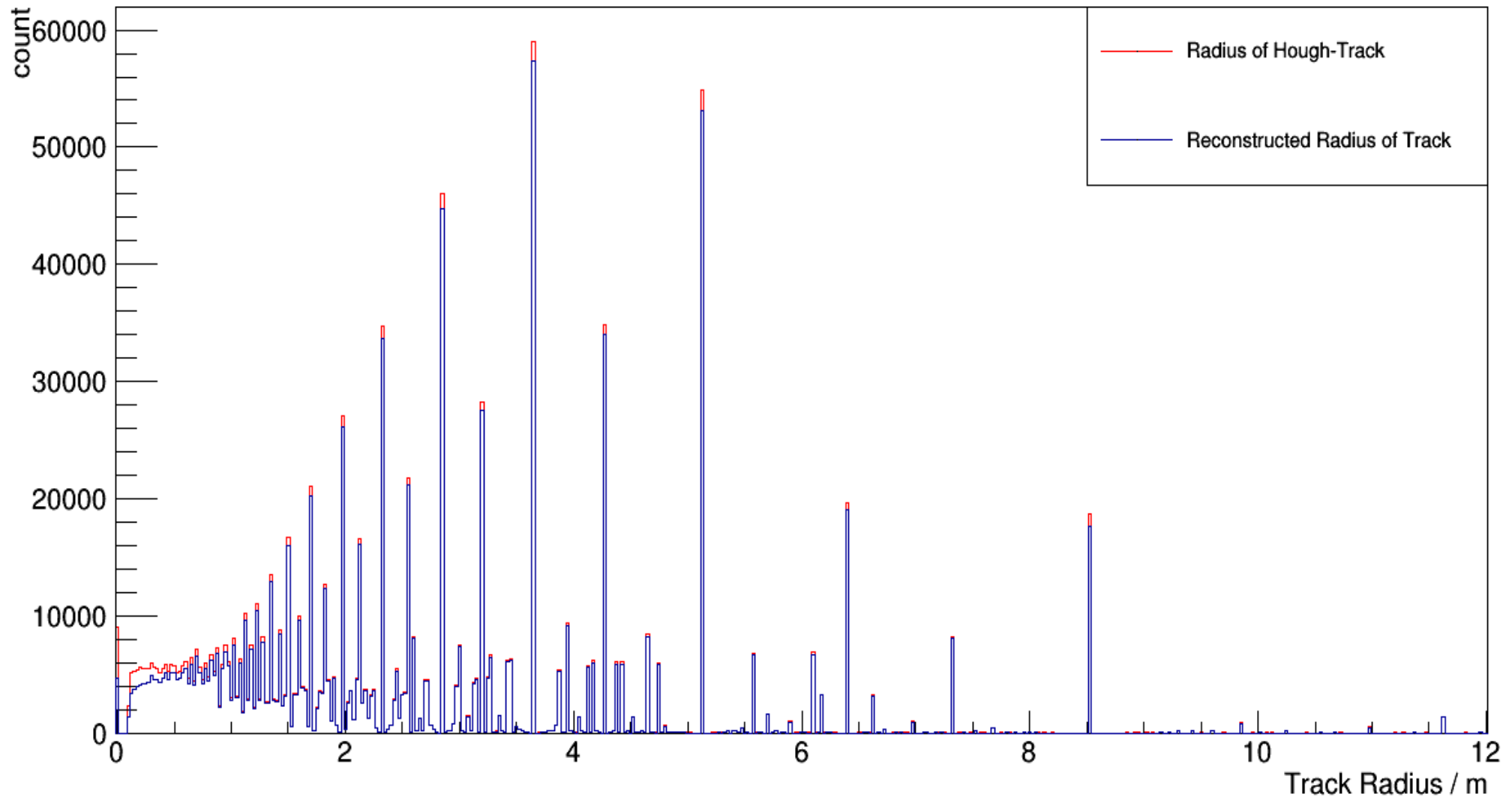
Simulation Results

Radius of Hough-Track



Simulation Results

Radius of Hough-Track



Simulation Results

Radius of Hough-Track

