Procedure

Results 000000 0000 000 Summary



The VXD alignment

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January 11, 2016

Procedure 00 Results 000000 0000 000

Outline

Introduction

Procedure

Results

Convergence Choice od samples and inputs The standard deviation study The bias study The shift of 3rd Layer

Summary





- **Constraints** fix the otherwise undefined degrees of freedom corresponding to global translations and rotations of VXD. They are realized by requiring that the sum of alignment correction per each parameter (projected to global system) is zero. We use them because otherwise we would need to fix some sensor.
- **TrueHits** are MC simulation objects, they are the records of passage of simulated particles through a sensor.
- **Clusters** are reconstruction objects. They represent reconstructed hits based on fired pixels or strips.

Results 000000 0000 000 Summary



Validation of Millepede algorithm

Tracks used for alignment:

- Physics process with high counting rate
- Cosmic-ray muons

Alignment study:

- Convergence of alignment parameters of sensors
- The study of choice of samples and inputs
- The shift of 3rd layer

Introduction	Procedure	Results
00	00	000000 0000 000

Summary

Introduction

Procedure

Results

Summary

Results

Procedure

- Generation of samples:
 - 1. Muons generated from IP by ParticleGun (90 000 events)
 - 2. Upsilon(4S) (60 000 events)
 - 3. Cosmics generator (60 000 events)
 - 4. Pair of muons from $Z^0 \rightarrow \mu^+ + \mu^-$ (30 000 events)
- Merging of 20 samples
- 10 independent simulations (\sim 200 samples)
- Outputs:
 - Mean value with standard deviation (std)
 - Standard deviation of Millepede algorithm (std_mille)



Results 000000 0000 000



Geometry of sensors and parameters

- All sensors at ideal position (without misalignment)
- Using constraints
- Local parameters for each sensor:
 - 1. Shifts: *u*, *v*, *w*
 - **2**. Rotations: α, β, γ
- Mean value as bias (difference between ideal and calculated position)

Layer ID	Ladders	Sensors	Parameters
1	8	2 · 8	2 · 8 · 6
2	12	2 · 12	$2\cdot 12\cdot 6$
3	7	2 · 7	$2\cdot 7\cdot 6$
4	10	3 · 10	$3\cdot 10\cdot 6$
5	12	4 · 12	$4\cdot 12\cdot 6$
6	16	5 · 16	$5\cdot 16\cdot 6$
	65	212	1 272

Procedure

Results

Summary

Introduction

Procedure

Results

Convergence Choice od samples and inputs The standard deviation study The bias study The shift of 3rd Layer

Summary

Procedure

Results

Using ParticleGun by TrueHits

1 sensor 2



The samples do not converge to expected values.



Procedure 00 Results

Summary



Upsilon by TrueHits





The samples do not converge to expected values and Upsilon's values are similar as ParticleGun.

Procedure 00 Results



Summary



Procedure

Results

Summary



MuonPairs by Clusters



The samples do not converge to expected values and MuonsPairs's values are different as Upsilon or Cosmics.

Procedure

Results



Uspilon and Cosmics by TrueHits (ZigZag)



Procedure

Results





Procedure

Results

Upsilon and Cosmics by Cluster





The standard deviation of rotations is smaller than MuonPair. and the wedge sensors have the highest deviation.

Procedure

Results

MuonsPair and Cosmics by Cluster



The standard deviation of shifts is smaller than Upsilon and the wedge sensors have the highest deviation.



Procedure

Results





The range of rotations is shorter than MuonPair.

Procedure

Results

MuonsPair and Cosmics by Cluster



The range of shifts is shorter than Upsilon.



Procedure 00 Results

Summary



The shift of 3rd Layer

The study of shift:

- Layer: 3rd
- Sensors: all
- Position:
 - Before: 37.99 mm
 - After: 38.99 mm
- ParticleGun and Cosmics by TrueHits
- Bias of rotations: (-0.27, 0.27) mrad
- Standard deviation:
 - Shifts: (0, 2.26) μm
 - Rotations: (0, 0.084) mrad

Procedure

Results ○○○○○ ○●○ Summary



Before the shift



Bias of shifts are in range (-7.72, 7.72)

Procedure

Results

Summary



After the shift



Bias of shifts are in range (-9.99, 9.99) The change are connected with u and w coordinate.

Procedure 00 Results 000000 0000 000

Summary



Status

Recommendations

Mixture of samples

The shift of 3rd layer

· Worse result at u and w coordinate

The best result

- Shifts (by mixture of Muons and Cosmics):
 - Mean: (-6.34, 6.34) μm
 - Standard deviation: (0, 1.31) μm
- Rotations (by mixture of Upsilon and Cosmics):
 - Mean: (-0.124, 0.124) mrad
 - Standard deviation: (0, 0.084) mrad

Procedure 00 Results

Plans

- Combination of three types samples
- Comparison between Clusters and TrueHits
- Changing constraints for fixed CDC wires

The study of impact to tracking parameters



Summary

Backup



The ladder numbering of VXD







The sensor numbering of VXD





The SVD

Cosmics by Cluster





Upsilon by Cluster





MuonPairs by Cluster





Cosmics by Cluster





Upsilon by Cluster





MuonPairs by Cluster





Upsilon and Cosmics by Cluster





MuonsPair and Cosmics by Cluster



