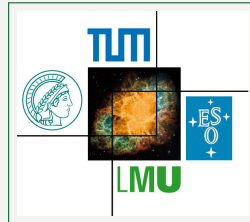
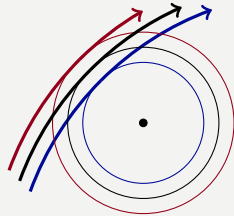
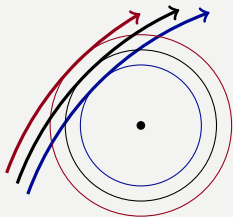
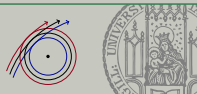


## Event Time from Tracks

Tobias Schlüter (LMU)  
2015-12-18





## Measurement Procedure

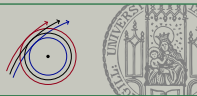
- ▶ passing charged particle ionizes gas
- ▶ gas cloud collapses on wire
- ▶ difference  
 $T(\text{passage of particle}) - T(\text{collapse})$   
gives distance of passage

## How do we know the passage time?

Usually:

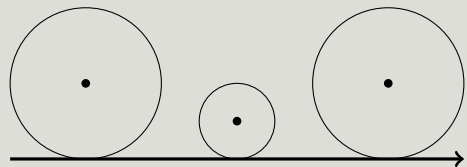
- ▶ Starting time of the track is evaluated
- ▶  $T(\text{Passage}) = \text{Track Length} / \text{Velocity}$

A drift chamber is a device that measures **time**, positions are inferred.

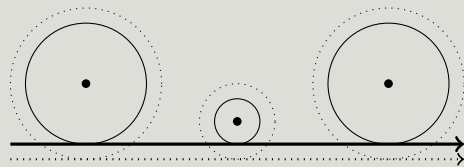


The simplest case, straight lines, all hits on one side.

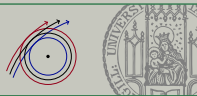
### Correct Timing



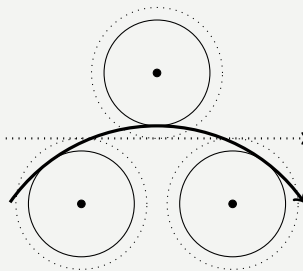
### Passage Time Underestimated



- ▶ position measurement depends on the evaluated drift time
- ▶ In this simple case a bias in time leads to bias in position.



Let's misadjust the passage time estimate ...and fit



- ▶ the track fit can be very sensitive to correct starting times
- ▶ thus we can find an optimal time for each event or track



Tracking problem:

$$\chi^2 = \sum_{\text{hits } i} (m_i - H_i s)^T R_i^{-1} (m_i - H_i s) = \min$$

Minimize the distance between the measurements  $m_i$  and the projections  $H_i$  of the track parameters  $s$ , i.e. the residuals  $r$ , weighted by the residual covariances

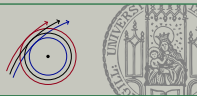
$$R_i = V_i - H_i C H_i^T$$

( $V_i$  measurement covariance,  $C$  covariance of track params)

Alignment problem:

$$\chi^2 = \sum_{\text{tracks } k} \sum_{\text{hits } i} (m_{ik}(a) - H_{ik} s_k)^T R_{ik}^{-1} (m_{ik}(a) - H_{ik} s_k) = \min$$

Find the track parameters  $s_k$  and the set of alignment parameters  $a$  that simultaneously minimize this  $\chi^2$ .

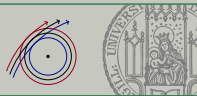


Once everything is linear, the  $\chi^2$  minimization separates in two parts (very convenient!):

1. find track parameters (i.e. fit the tracks)
2. find the optimal alignment parameters (i.e. align)

## Solution

$$a - a_0 = - \left( \sum_{ik} \frac{d}{da} r_i(s_k, a) \Big|_{a=a_0} \cdot R_{ik}^{-1} \cdot \frac{d}{da} r_i(s_k, a) \Big|_{a=a_0} \right)^{-1} \left( \sum_{ik} \frac{d}{da} r_i(s_k, a) \Big|_{a=a_0} \cdot R_{ik}^{-1} \cdot r_i(s_k, a_0) \right)$$



Once everything is linear, the  $\chi^2$  minimization separates in two parts (very convenient!):

1. find track parameters (i.e. fit the tracks)
2. find the optimal alignment parameters (i.e. align)

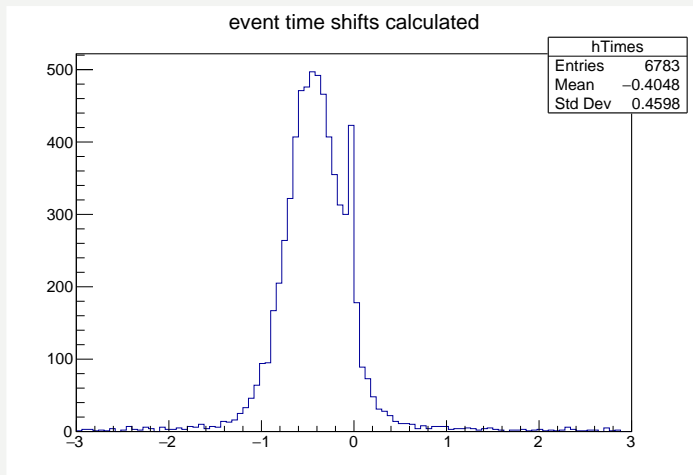
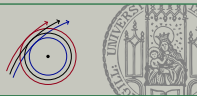
## Solution

$$a - a_0 = - \left( \sum_{ik} \left. \frac{d}{da} r_i(s_k, a) \right|_{a=a_0} \cdot R_{ik}^{-1} \cdot \left. \frac{d}{da} r_i(s_k, a) \right|_{a=a_0} \right)^{-1} \left( \sum_{ik} \left. \frac{d}{da} r_i(s_k, a) \right|_{a=a_0} \cdot R_{ik}^{-1} \cdot r_i(s_k, a_0) \right)$$

We can do this for the *event time* (just take only tracks from one event, and think of a shift in time like you would about a shift in space):

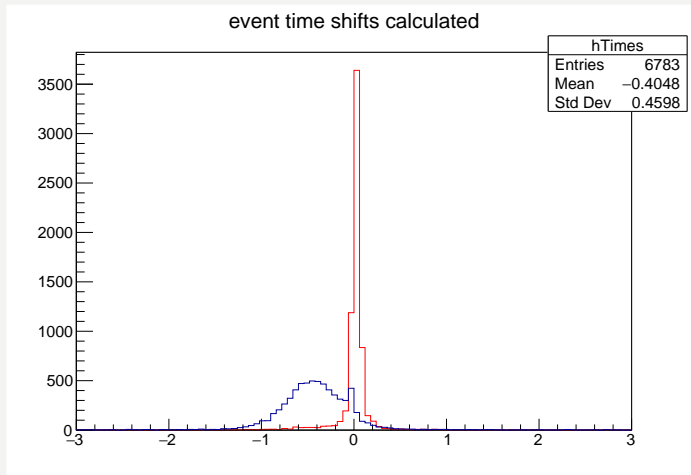
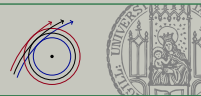
$$t - t_0 = - \frac{\sum_{ik} \left. \frac{d}{dt} r_i(s_k, t) \right|_{t=t_0} \cdot R_{ik}^{-1} \cdot r_i(s_k, t_0)}{\sum_{ik} \left. \frac{d}{dt} r_i(s_k, t) \right|_{t=t_0} \cdot R_{ik}^{-1} \cdot \left. \frac{d}{dt} r_i(s_k, t) \right|_{t=t_0}}$$

Implemented after some preparatory work: this works best with the full covariance matrix for the track (usual Kalman only gives local covariances), need derivatives of the  $x-t$  relation.

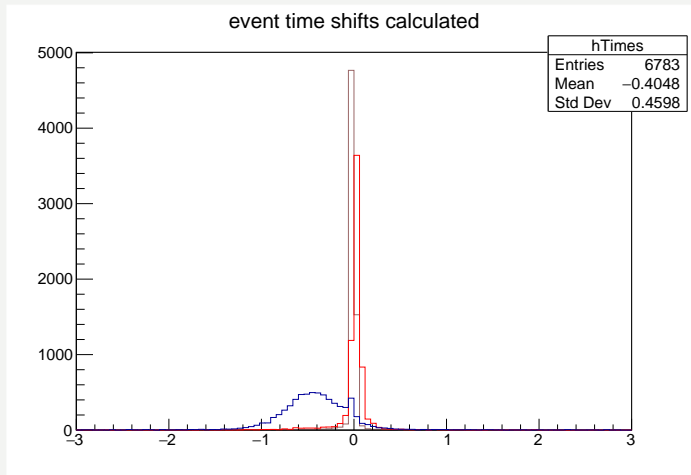
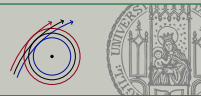


Initial calculation:  $\approx 0.5$  ns wide distribution, not centered at zero, weird peak at zero (reasons not yet investigated, probably initial calculation in `GenFitterModule` not precise, weird peak from numerically bad cases)





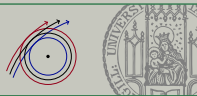
After one iteration: peak becomes sharper, moves beyond center.



After two iterations: peak even sharper, nicely centered (visible in finer binning)



1. distribution for individual tracks is broader than what was shown (as expected), also moves to center (as expected)
2.  $P$ -value distribution shows no discernible improvement (which is a bit weird, but maybe it's a really small improvement)
3. very promising
4. of course this could be grown into a complete alignment ;-)



At our low momenta, propagation speed depends considerably on the particle species ( $m_\pi : m_K : m_p = 1 : 4 : 7$ )

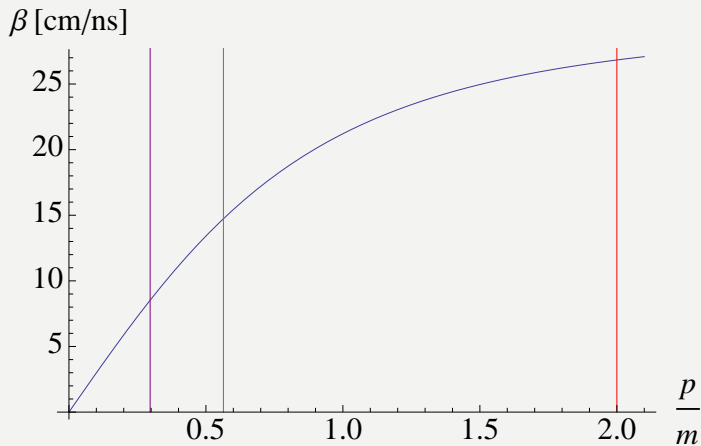
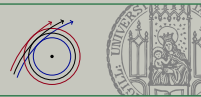


Figure: Velocity as function of  $p/m$ . Same momentum ( $p = 2m_\pi = 280$  MeV) is indicated for protons, kaons and pions



The main issue will be the separation of the errors from the drift and from the time measurement. For this, we need to invert the  $x-t$  relations which give the distance as function of the drift time. Here is a typical  $x-t$  relation for one cell, depending on various track impact angles. (Linear relation in red.)

