

# Machine Learning Assisted Track Finding in the Belle II SVD

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# Some Information on Belle II

... can be found in talks given by

- **Sebastian Skambraks:** *The NeuroZ-Vertex Trigger of the Belle II Experiment*
- **Oliver Frost:** *Tracking in the Belle II Drift Chamber*
- **Jakob Lettenbichler:** *Tracking in the Belle II Vertex Detector*



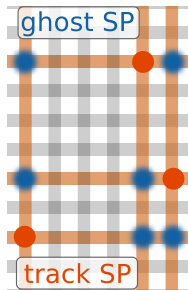
# Challenges and Short Recap of SectorMap

## Goal:

low momentum track finding down to  $p_T \approx 50 \text{ MeV}/c$

## Main Challenges:

- Energy loss and multiple scattering influence particle trajectory
- Limited reconstruction time
- Ghost SpacePoints on strip detectors



## SectorMap:<sup>a</sup>

- divide detector into small sectors
- use relations between sectors to define cut-off filters for hit combinations

<sup>a</sup>see talk by Jakob Lettenbichler



# Bringing Machine Learning into play

## Advantages and Challenges of the SectorMap:

- + **Fast filtering** with high efficiency
- Tuning of a **large number** of **filters** and **sector relations**
- Training very **resource demanding**

## Hopes in Supervised Machine Learning:

- + Exploit **generalization capabilities**
  - + Less sectors required
  - + Less training data required
- + Improved signal and background separation
  - + Higher coverage of input space

? Is it possible to exchange a **large number of simple filters** by  
a **small number of ML filters** ?



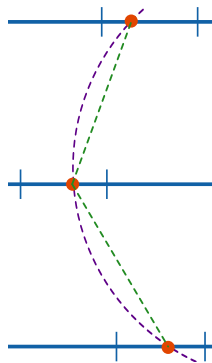
# The Approach and Training

## Incorporate Machine Learning into SectorMap:

2-SpacePoint combinations processed by standard filters

Use a **Boosted Decision Tree (BDT)** to filter  
3-SpacePoint combinations:

- inputs:  $x \in \mathbb{R}^9$  - ( $3 \times 3$ ) spatial coordinates of SpacePoints
- outputs:  $y \in \mathbb{R}$  - use **cut** to decide **signal/background**
- label: from **full detector simulation**
  - signal if all SpacePoints from **same MC particle**



# Some words on the simulation

## Simulation setup:

- limited  $\theta$ -range:  $60^\circ \leq \theta \leq 85^\circ$
- particle gun:  $10 \mu$  tracks per event
- low momentum range:  $100 \text{ MeV}/c \leq p_T \leq 145 \text{ MeV}/c$
- no additional background

## Results in:

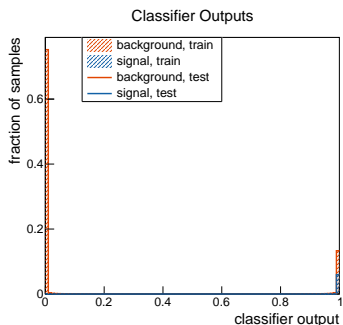
- track hits / ghost hits  $\approx 0.5$
- signal / background ration in input  $\approx 0.08$

## Expected in experiment:

- $\Upsilon(4S)$ -events: on average  $\approx 10$  tracks per event
- signal / background in input  $\approx 0.1$  (incl. machine bg)



# Classifier Performance



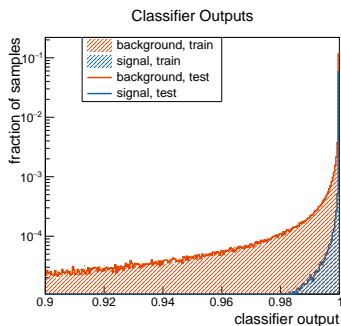
- good **clustering** of **signal** samples
- **cut** is defined to reach **99 %** **signal efficiency**
- majority of **background** **rejected**

	cut	bg. reject.
train	0.906	81.53 %
test	0.912	81.68 %

→ training a **classifier** for the purpose is **possible**



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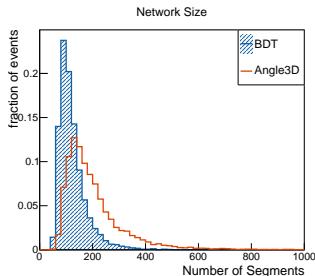
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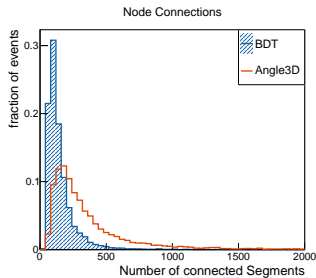
# Comparison with Angle3D filter

Both approaches used **same events** (for training and for testing)



- **Angle3D** and **BDT** with  $\approx 99\%$  efficiency after Cellular Automaton
- **Clone** and **ghost/fake rate lower** by factor  $\approx 3 - 4$  for **BDT**

- Network size is **indicator** for bg rejection
- **Smaller** networks processed **faster** by Cellular Automaton
- **BDT** yields smaller Networks



# Conclusion & Outlook

## Conclusions:

- Machine Learned Filter with promising results
- Tests not done on full detector and momentum range
  - Standard filters not affected
  - ML filters could degrade significantly

## Outlook and ToDo's:

- Test on full detector and momentum range
- Test with physics simulation data
- Compare execution time
- Test feasibility of different ML classifiers for different detector regions

## Suggestions:

- Any other thoughts or ideas from YOUR side?



# Backup