

TB 2008 Analysis in Valencia

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Test Beam Setup





- General view
- 6 Modules at once
- 1 rotating module





SPS Time Measurements: 3 weeks of data



□ Voltage scans: Cross-check, we're running in optimal settings

> V_{Bias} to the waffer 150-220V

 $\succ V_{Edge}$

 $\succ V_{ClearHigh}$

Angular scan: To study resolution vs. Cluster size

▷ -5, -4, -3, -2, -1.5, -1, -0.5, 0, 0.5, 1, 1.5, 2, 3, 4, 5, 6, 9, 12, 18, 36

Beam energy scan: To analyse wheter the separation "multi-scattering-intrinsic resolution" is performed correctly

> 20, 40, 60, 80, 120 GeV

□ Large statistics:

> Charge collection uniformity studies

> In-pixel studies

3.5 TB of data

20 Million events







	d0 (32x24)	d1 (32x24)	d2 (24x24)	d3 (32x24)*	d4 (32x24)	d5 (32x24)
Sig3x3(ADU)	1339	1497	1704	1715	1508	1654
Noise (ADU)	12,7	13,4	12,7	13,4	12,8	13,2
SNR	105	112	134	128	118	125
SeedSignal(ADU)	69%	56%	59%	61%	63%	64%
ENC (e ⁻)	345	326	286	284	309	290
g _q (pA/e ⁻)	283	316	360	363	319	350

*CCCG: Average value between two halves

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Position resolution





<u>Residuals</u>: Difference in position between the resulting track and the found hit

Resolution: Standard deviation of the residual distribution







Test Beam at CERN: Operational aspects

> 6 DEPFET planes (64x128 pixels matrices) working at the same time on beam. 5 telescope planes and 1 DUT.

> 20 Mevents collected. Analysis in progress!

Data analysis and processing

- > DUT (450 μ m thick) presents good SNR, low noise and high gain.
 - > For 50 μ m, SNR will be smaller by a factor 9.
- > Matrix working in optimal settings, cross check with lab measurements.

> Position resolution ~2,5µm, including telescope, intrinsic and multiple-scattering contributions.

- > Energy scan could helps to separate the m.s. resolution contribution.
- > Charge uniform over the matrix surface. No masked pixels.





Thank you very much!





Analysis framework: ILC (EUTelescope) Software

RAW DATA Reader/Converter \rightarrow Converts the native raw DEPFET format (.dat) to the LCIO (Linear Collider Input-Output) raw format, with the proper event structure and the correct event model

PedestalNoiseProcessor \rightarrow Calibrate the output of each pixel detector in order to remove the constant and useless signal. Together with this pedestal value also the noise figure is estimated as the witdth of the pedestal distribution. This can be done in two different ways: Producing the pedestal and noise from a specific run or assuming a known initial value and then keep them update

ClusterFinder \rightarrow Scan the matrix looking for clusters mean to look for a group of space correlated pixels all having signal above a certain threshold.

ETACorrection \rightarrow Used to calculate the center of the cluster. It is used as a non linear weighting function in the charge center of mass calculation. Is an experimental approach based on the fact that the probability to find the cluster center is flat over the pixel sufrace. A certain region does not collect more cluster centers than another. The ETA correction is made in two orthogonal directions

HitMaker \rightarrow This processor must convert a local cluster in the detector frame of reference to space point in the telescope frame of reference. This processor access to the geometry repository.

Alignment \rightarrow MILLEPEDE II package. Loops over all events and finds track candidates. Obtain the global parameters \rightarrow the alignment constants. Linear least squares problem solved by a simultaneous fit of all parameters. A large number of tracks can be considered for the alignment.

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Double pixel structure

Merging two pixels (common source) for reduce the size

