Optimization Studies with Single Tracks



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Detector/Sensor simulation and track reconstruction







Analysis procedure



Results



Study optimization of PXD using single tracks and impact parameters

Optimization chain







Detector simulation software: Mokka (geant4 based, ILC framework)





Detailed simulation of DEPFET sensor signal:

- Global to local reference system transformation performed
- **Ionization points** generated (energy loss fluctuation added + electron-hole pairs created)
- Signal points generated:

drift of electron-hole pairs

drift path calculated

Lorentz shift in magnetic field + diffusion sigma calculated

- Signal redistributed according to diffusion, cell ID calculated
- Hits produced (pixels with signal above threshold (2xnoise) found + position calculated)
- Local to global reference system transformation

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Clustering built into the digitizer (performed on the hit level)

Landau energy deposit not taken from geant4 instead parameter from MIP used.

Simulation SVD



Digitization procedure:

- Generation of electron-hole pairs along the path
- Drift of electron-hole pairs in the electric field
- Diffusion of electron-hole pairs due to multiple collisions
- Lorentz shift of electron-hole pairs in the magnetic field
- Calculation of mutual micro-strip crosstalk (missing: intermediate strips)
- Generation of gaussian-type noise: electronics
- 2 Clustering step:
 - Seeds + neighbouring strips found based on S/N cut (separately in Z & R-Phi)
 - Hit position calculated based on COG algorithm



all possible candidates in Z & R-Phi merged to 2D hit (ghosts produced)





Landau energy deposit taken from geant4

Reconstruction



Tracking performed in Marlin (ILC framework)

- 🕨 Silicon (PXD, SVD) tracking + CDC tracking 🗼
- Tracks with impact parameters (+ its errors)

Definition impact parameter:

Merge Silicon and CDC tracks



Getting the impact parameter resolution



Resolution defined as width of peak (Signal)

Different possibilities: RMS, RMS 90, Gauss fit, double Gauss fit ...

In order to study tails 🗼 Use fit of distribution

Different fitting methods were tested:

• Gauss

double Gauss

stable and reliable fit

- triple Gauss
- Gauss + exponential
- Gauss + double exponential

Fitting method:



Pre-fit using Gauss

- 2 Values from pre-fit as start values for double Gauss fit
- 3 Smaller sigma of the two Gauss functions is taken
 - Intersection of the two Gauss functions separates signal region from tails



For each d0/z0 value 200 new values of d0/z0 are calculated:

The new values are filled into 200 histograms

- Mean of histogram "sigma" is resolution
- 2 sigma range defines asymmetric error of resolution (quantile function used)

 $dO_{new} = dO + RandomGauss(0, Error_{dO})$

D0 :: 0.1 GeV :: 55 degree

Sigma

4 e d0 [mm]

80 700

200 100

Mean



Constant pixel size, 1600 pixels, Pixel size: 1. layer: 50 x 47.7 μ m 2. layer: 50 x 73.4 μ m

	thickness	rad 1. layer	rad 2. layer	BP outer rad	BP Au	
50um_HC	50 µm	18 mm	22 mm	16.5 mm	~	
50um_NB	50 µm	13 mm	22 mm	10.0 mm	\checkmark	🖕 Base
50um_NBnoAu	50 µm	13 mm	22 mm	10.0 mm	×	line
75um_NB	75 µm	13 mm	22 mm	10.0 mm	~	
75um_NBnoAu	75 µm	13 mm	22 mm	10.0 mm	×	
100um_NB	100 µm	13 mm	22 mm	10.0 mm	~	
100um_NBnoAu	100 µm	13 mm	22 mm	10.0 mm	×	

Momentum (GeV)

- 0.1 slow pion
- 0.3
 - .3
- **0.5** average hadron momentum
- **1.5** J/Psi
- **5.0** mu/mu

Angles (degree) + 1 degree smearing

- **35.0** forward region
- 80.0 central region

55.0





d0

d0 θ = 55 degree





effect of multiple scattering bigger, because path in sensor is longer for smaller angles.





Momentum [GeV]



Tails are non Gaussian and contain contributions from

- multiple scattering
- pattern recognition, track fitting (tracking)

Example: track multiplicity





Detailed simulation of PXD and SVD response is implemented

- Detailed studies on resolution and tail extraction started
- Optimization chain for single tracks works
- Preliminary result: thin detector help

Problems found:

- Resolution distribution shows core gaussian peak with non gaussian tails
- Size of tails is considered to be important for optimization
- Sources of non gaussian tails: **multiple scattering** (to be optimized)

tracking

- Studies at present are not able to disentangle both effects
- Pattern recognition not optimized for low momentum (< 1GeV) particles

Next steps:



Monte Carlo based pattern recognition for optimization studies



Develop simple model for background simulation