







# **All-Silicon Petals**

#### DEPFET workshop Ringberg, March 2019

Guillem Vidal, IFIC (UVEG/CSIC) Valencia

Special thanks: Marcel Vos, M.A. Villarejo, Martín Perelló (IFIC) Laci Andricek (MPG/HLL), Malte Frövel, Maria de la Torre (INTA) Carlos Marinas (U. Bonn), David Moyá, Ivan Vila (IFCA)



GENERALITAT



**Guillem Vidal** 

### What do we want to achieve

Impact parameter resolution expected at ILC

$$\sigma_{ip} = 5 \ \mu m \oplus \frac{10}{p\beta \sin \theta^{3/2}} \ \mu m.GeV/c$$

- Spatial resolution of the inner layer close to ≈ 3µm (which corresponds to a pitch 17µm)
- Low material budget to minimize multiple scattering,  $\approx 0.15\% X_0$ /layer
- Alignment at the micron level capabilities.



### **ILD tracking**





### **Tracker sub-systems**

Beam pipe

Vertex Detector (VXD)

Silicon Intermediate Tracker (SIT)

Time Projection Chamber (TPC)

Silicon Envelope Tracker (SET)

### The ILD tracker and FTD

- Mixed silicon (vertex, FTD, SIT, SET) and gaseous system (TPC)
- Seven disks cover the forward region between the TPC and the beam pipe.
- Innermost two disks pixelated single layer of silicon sensors
- Five outer disks equipped with a double layer of strip-based silicon sensors



### The role of FTD in tracking



Number of hits in different subsystems vs. polar angle In the case of ILD

-Barrel covers angles between 90-25 degrees

-The Time Projection Chamber also decreases the number of hits with the angle

*-The Forward Tracking Disks cover the angles between 25 and 7 degrees* 

### **Pixelated disks**

### Technologies for pixelated FTD 1 & 2



- All technology options remain open
  - DEPFET
  - CMOS
  - FPCCD
  - 3D-integrated
  - SOI
  - ...
- Conceptual adaption of barrel design to disk geometry for some technologies, but no fully engineered design



# DEPFET active pixel detector technology

These DEPFETs meet most ILC requirements

DEPFET

e Pixel Dete

DEPFET active pixel detectors All-silicon ladder Belle II/ILC

> self-supporting signal and power lines read-out & steering electronics

## **DEPFET beyond Belle II**







Laci Andricek

Next 10 years: significant improvement in technology

Upgraded lithography offers opportunities for better signal amplification (S/N ratio, resolution, read-out speed)

40% Material Budget reduction

→ less material with small modifications/improvements of module technology within reach



Sensitive layer

Cu layer

Total

Switcher thickness

DEPFET workshop, Ringberg, March 2019

75 µm

500µm

0.21 %X0

only on periphery

50µm

75µm

0.13 %X0

only on periphery

### **Ladder to Petal**



### Based on DEPFET technology:

- -Power distribution
- -Material
- -Mechanical stiffness





### Adapt the ladder design to FTD 1 and 2

Ladder becomes a petal

Read-out ASICs on outer perimeter

Dimensions reflect ILD design

Silicon petal design at IFIC in collaboration with Ladislav Andricek (MPG-HLL)

#### Material budget:

Thinned sensor area =  $50 \ \mu m \ Si = 0.05 \ \% \ X_0$ Thicker rim "frame" =  $500 \ \mu m \ Si = 0.5 \ \% \ X_0$ 



### **Dummy production**

Heater circuits on the sensor (single AI metal layer)



Kinematic mounting slots:

- 3D constraint
- Allows thermal expansion

### **Thermo-mechanical performance**



### **All-silicon petals**

Production at silicon lab of the Max Planck society in Munich





## **Carbon Fibre disk production**



Design by Miguel Angel Villarejo (IFIC)



#### Machined at Ramem (Madrid)



Goal: gain hands-on experience with Production and operation of an ultrathin Carbon Fibre + silicon structure

Carbon Fibre produced at INTA in Madrid,

composite material group, Malte Frovel and Maria de la Torre

### Planarity



7.6 7.55 7.5 7.45 7.4 7.35 7.3 7.35 7.3 7.25 7.2 7.15 7.1

The CF disks have been extensively mesured in a precise metrology system.

Planarity over 30 cm:

- peak-to-peak ~ 500 µm
- RMS ~ 200 µm



7.6 7.55 7.45 7.4 7.4 7.35 7.25 7.2 7.25 7.2 7.15 7.1



### **Petals positioning**

Holes produced in the carbon fiber with high precision machine, with +-100 µm tolerance

PEEK inserts placed in holes with a precision jig, to achieve better placement precision of the Silicon sensors









### **Petals positioning**

### Relative precision of the PEEK inserts: $\pm$ 50µm from nominal position



72

### **Material budget**

FTD1	
Carbon f ber + cyano-ester resin	0,0376535
Honeycomb (aramide)	0,0006276
Peek inserts	0,0019486
Peek screews	0,0014073
Inserts glue	0,0006495
Total X/X0 %	0,0422866

#### Material in % of $X_0$ , averaged over area

FTD2	
Carbon f ber + cyano-ester resin	0,0383109
Honeycomb (aramide)	0,0006385
Peek inserts	0,0020261
Peek screews	0,0014633
Inserts glue	0,0041013
Total X/X0 %	0,0465401

Weight: less than 15 g

Disk contributes less than 0.05% of a radiation length to the material budget

X-ray map of the material in FTD1:

![](_page_18_Picture_9.jpeg)

DEPFET workshop, Ringberg, March 2019

### **Mounting the Silicon petals**

#### Controlled torque

![](_page_19_Picture_2.jpeg)

#### Deformation and vibration measured with precision

![](_page_19_Picture_4.jpeg)

![](_page_19_Picture_5.jpeg)

### Petals modal analysis

![](_page_20_Figure_1.jpeg)

![](_page_20_Picture_2.jpeg)

### Petals modal analysis

The natural vibration modes (eigenfrequencies) are measured as a function of the torque applied on the screws that fix the Silicon on the three mounting positions

The eigenfrequency increases with the torque applied to the screws (the joints are elastic; petal degrees of freedom are modified as the torque increases)

![](_page_21_Figure_3.jpeg)

The eigenfrequency saturates at about 300 Hz

0,3 - 0,5 cN·m for a completely clamped petal

### **Petals stabilization**

Deformations due to background vibrations and temperature variations is stable within 48 hours between +-  $1\mu m$  in Z

A 1 day transitional period of time needed before stabilization

![](_page_22_Figure_3.jpeg)

# Air cooling & mechanical stability

![](_page_23_Picture_1.jpeg)

Ph.D. thesis Nacho Garcia, U. Valencia, 2016

Dummy petal in CERN wind tunnel

Vibrations remain acceptable for air speed up to several m/s

![](_page_23_Figure_5.jpeg)

### Petal deformations vs. air velocity

Measurements repeated on CF disk, with the petal clamped in a fully controlled way

Deformations due to thermal expansion of the sensor are sizeable: 10 µm when not cooled

Deformations due to laminar air flow increase with air velocity: less than 1 µm up to 4 m/s

![](_page_24_Figure_4.jpeg)

### **Measurement in realistic conditions**

For a maximum temperature gradient over the sensor area of 10K, air cooling at 1m/s is sufficient for nominal power  $\rightarrow$  RMS of 0,2 - 0,4 µm.

![](_page_25_Figure_2.jpeg)

![](_page_25_Picture_3.jpeg)

### **Summary so far**

- Petal mounting precision better than 50 µm
- Petals stability without distortions within +- 1  $\mu m$
- Petal distortion under realistic load depends on torque applied to screws
- Carbon fiber structure of 0,045  $X/X_0$ % with first modal frequency of 1 kHz
- First natural frequency of petals in a safe regime, above 200Hz
- Air cooling with ~ 1 m/s air flow yields a  $\Delta T$  of 10K in the sensitive region
- Vibrations are limited to 0.2-0.4  $\mu m$

![](_page_26_Picture_8.jpeg)

![](_page_26_Picture_9.jpeg)