

ATLAS Software Status and Plans

❑ Computing System Commissioning Goals:

- ❑ We have defined the high-level goals of the Computing System Commissioning operation during 2006 were defined
 - ❑ Formerly called "DC3"
 - ❑ More a running-in of continuous operation than a stand-alone challenge
- ❑ Main aim of Computing System Commissioning will be to:
 - ❑ test the software and computing infrastructure that we will need at the beginning of 2007:
 - ❑ Calibration and alignment procedures and conditions DB
 - ❑ Full trigger chain & Monitoring
 - ❑ Event reconstruction and data distribution
 - ❑ Distributed Data Management
 - ❑ Distributed Production (Simulation & Re-processing)
 - ❑ Distributed access to the data for analysis
- ❑ At the end of 2006
 - ❑ a working and operational system, ready to take data with cosmic rays at increasing rates



ATLAS Software towards Release 12

- ❑ Updating dead material
 - ❑ Cables, services, barrel/end-cap cracks, etc.
- ❑ Define reference coordinate systems
 - ❑ GLOB=installation survey, SOL(t), BEAM(t)
- ❑ Realistic B-field map taking into account non-symmetric coil placements
 - ❑ B-field map size issues...
- ❑ Displace detector (macro)-pieces to describe their actual positions
 - ❑ E.g. EM barrel axis 2mm below beam line and solenoid axis
- ❑ Include detector "egg-shapes" if relevant
 - ❑ E.g. Tilecal elliptical shape if it has an impact on B-field...
- ❑ Mis-align detector modules/chambers inside macro pieces
- ❑ Include chamber deformations, sagging of wires and calo plates, etc.
 - ❑ Probably at digitization/reconstruction level
- ❑ Exercise the conditions database access and distribution infrastructure
 - ❑ With COOL conditions database, realistic data volumes and routine use in reconstruction
 - ❑ In a distributed environment, with true distributed conditions DB infrastructure
 - ❑ Athena support for conditions data reading / writing / iteration
 - ❑ Reconstruction using conditions database for all time-varying data
- ❑ Largely assuming required samples are available and can be selected
- ❑ But also want to look at initial 2007/2008 running at low luminosity
 - ❑ Selecting events from the 'initial realistic data sample'
 - ❑ Issues of streaming - using calibration and physics data



Simulation

- Ability to simulate a realistic, misaligned, miscalibrated detector

Geometry description and use of conditions DB in distributed simulation and digitisation

Reconstruction

- use of calibration data in reconstruction
- ability to handle time-varying calibration
- Initially: static replication of conditions database – parameters in advance

Calibration algorithms

- Algorithms in Athena, running from standard ATLAS data (ESD, raw data?)

Organisation and bookkeeping (run number ranges, production system,...)

How do we ensure all the conditions data for simulation is available with right IoVs?

What about defaults for 'private' simulations ?



Calib/Align subdetector parameters

SCT/Pixel	Alignment, dead/noisy channels, module distortions, pixel calib/thresholds
TRT	Module align., wire position, t_0 , R-t, dead channels, resolution, efficiency
LAr	Electronics calibration, HV, cluster level corrections, dead material, misalignment
HEC	(Focus on energy/eta parameterisation)
TileCal	CIS calibration, cesium calibration, optimal filter coefficients
MDT	t_0 , R-t, alignment corrections, temperature/field/sag/space charge corr ⁿ
RPC	Pressure/temp, thresholds, HV/LV, currents, dead strip/efficiencies map, trig coinc.
CSC	ADC to strip charge, chamber alignment
TGC	Timing, delays, chamber alignment



Releases Schedule

- **Scheduled for 18 April 06**
 - A between Release 11.5.0 (4 April 06)
- **Primary goals**
 - Complete implementation of as-built geometry for all detectors
 - Conditions DB infrastructure in place and significant usage of COOL
 - Includes new COOL functionality (requires ROOT5)
 - Trigger AOD EDM in place
 - Implementation of MC Truth Task Force Recommendations
 - Implementation of Event Tag Working Group Recommendations
 - New Tracking validated and performance equal or better than alternatives
 - Backwards compatibility support in place for simulated data
- **Platforms and Compilers**
 - SLC3 with gcc 3.2.3 : is the only ATLAS supported OS/compiler
 - SLC3/gcc 3.4.4 will be added in the next few days
 - First in 32-bit mode (goal for release 12 in March)
 - Then in 64-bit mode ("functional but not validated" for release 13 in July)
 - Highly likely that **SLC4 will be CERN supported platform for LHC turn on**
 - CERN support for SLC3 until end 2006
 - ATLAS support for SLC3 at remote sites longer (need to decide until when)
 - Porting to SLC4/gcc 3.4.4 will start soon



MuonSpectrometer Geometry

Cleaning strategy (for Barrel / Endcap sector):

- We are building separately B(E)IL, B(E)IS, B(E)ML, B(E)MS, etc. with a veto in the MuonGeoModel chamber build() method (in MuonDetectorFactory001.cxx)
- Each station type represents **the unit** which one should care of clearing
- When two units are cleared, we put them together and clean the overlaps between them

This way, we will proceed for all the stations, last will be the feet

Configurations

- Release 10.4.1-11.1.0-11.2.0
- Layout "Rome-Final" , "MuonR0101.Initial"
- cmt version v1r18p20050501

HowTo on the MuonGeometryDC3 Wiki page

<https://uimon.cern.ch/twiki/bin/view/Atlas/MuonGeometryDC3>

which can be reached from the MuonSpectrometerSimulation Wiki Page

- <https://twiki.cern.ch/twiki/pub/Atlas/MuonGeometryDC3/HowToDoClashBusting.htm>



General Overview of Cleaning Status

So far, analyzed all barrel and endcap stations:

- ❑ remaining clashes in the barrel-region
 - ❑ https://twiki.cern.ch/twiki/bin/view/Atlas/MuonGeometryDC3#Barrel_Section
 - ❑ Most of the problems arise from conflicts between dead materials and chambers
 - ❑ no misplacements or wrong size of chambers or inert materials, but just mother volume definition for the chambers.
 - ❑ soon a proposal from Vakho and Andrea about how to avoid the definition of a station mother volume
 - ❑ Chambers, i.e. wires and strips are cross-checked with Amdc
 - ❑ We'd like to have similar cross check mechanism for dead materials
- ❑ remaining clashes in the endcap-region
 - ❑ https://twiki.cern.ch/twiki/bin/view/Atlas/MuonGeometryDC3#EndCap_Section
 - ❑ There are four major-problems in the end-cap within all chambers:
 - ❑ Support-Structures extending the Station-Volume
 - ❑ Clashes between the Support-Structures
 - ❑ Drifftubes extending the chambers
 - ❑ The Usual MuonSys?-Promblem
 - ❑ Detailed Report
 - ❑ https://twiki.cern.ch/twiki/pub/Atlas/MuonGeometryDC3/Clashes_mschott_EEEO.pdf



- **Muon versions for DC3:**
 - Goal: Muon spectrometer "as built" (more realistic...)
 - Muon Detector description: parameters from AMDB (activ & Dead)
- **Version R : Symmetric description (more or less validated) (see previous slides)**
 - MuonSpectrometer-R-01-01.Initial : muon tag in Oracle DB
 - Barrel/Endcap clash free for activ/activ part
 - **Full offline chain up to the RDO production tested for layout**
 - **'Muon-R-01-01.Initial' (ATLAS-DC3-03)**
- **Version R' : egg shape description (7mm maximum for sector5)**
 - MuonSpectrometer-R-01-01-initial_EGG: muon tag in Oracle DB
 - R' (should not be a problem)
 - soon in the pipe (11.4.0)
- **Version R'' : egg shape + chambers shifted (~1mm) & tilted(~1mrd) randomly**
 - MuonSpectrometer-R-01-01-initial_EGG_RNDM : muon tag in Oracle DB
 - R'' problems expected due to the misalignment input
 - but this version do not take into account
 - dead matter in forward region (big wheel)
 - tilt & shift of the big wheel and forward chamber as in the barrel
- **Work in progress to test at Geometry & Simulation level R' and R''**
 - R already in the pipe(11.3.0)
 - R' should be tested & validated before end of Feb (11.4.0)
 - R'' should be tested & validated before end of March (12.0.0)



“As built” Muon Spectrometer geometry for the simulation

End Caps: Big wheels global displacements

Proposed simple set of displacements:

$$\text{ECA} \left\{ \begin{array}{l} \text{EM wheel: } \delta x = 1\text{mm}, \delta y = 3\text{mm}, \delta z = 2\text{mm}, \delta\theta_z = 2\text{mrad} \\ \text{EO wheel: } \delta x = -2\text{mm}, \delta y = -1\text{mm}, \delta z = -10\text{mm}, \delta\theta_z = -1\text{mrad}, \delta\theta_x = 1\text{ mrad} \end{array} \right.$$

$$\text{ECC} \left\{ \begin{array}{l} \text{EM wheel: } \delta x = -1\text{mm}, \delta y = -3\text{mm}, \delta z = -2\text{mm}, \delta\theta_z = -2\text{mrad} \\ \text{EO wheel: } \delta x = 2\text{mm}, \delta y = 1\text{mm}, \delta z = 10\text{mm}, \delta\theta_z = 1\text{mrad}, \delta\theta_y = 1\text{ mrad} \end{array} \right.$$

No EI and TGC wheels displacements

=> Layout Version R' to be implemented in version 11.4.0 (clash free)

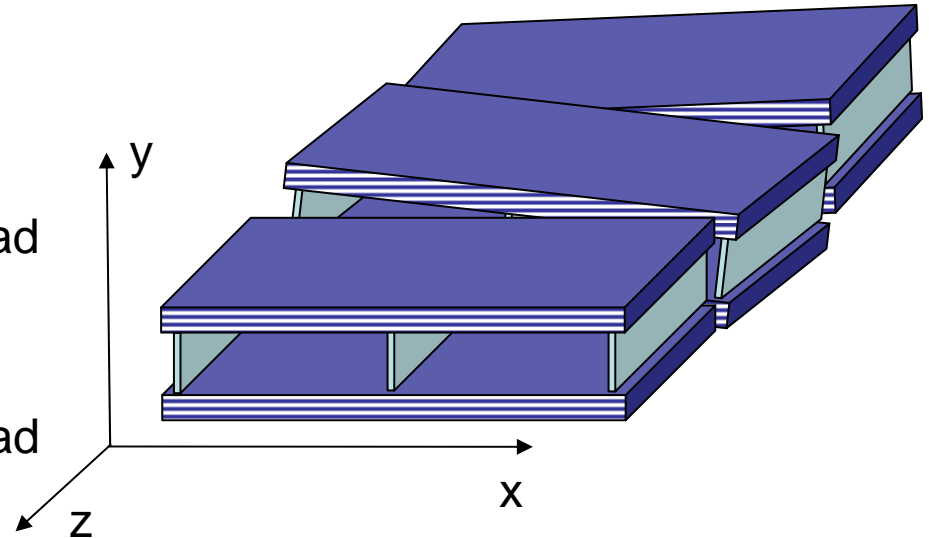


“As built” Muon Spectrometer geometry for the simulation (cont’d)

If clashes elimination at GeoModel/Geant4 level can be worked out (not guaranteed to be ready for CSC production):

Random chamber displacements (ranges are adjusted to minimize the risk of clashes):

barrel	$\Delta z = \pm 1 \text{ mm}$	$\Delta\theta_z = \pm 2 \text{ mrad}$
	$\Delta x = \pm 4 \text{ mm}$	$\Delta\theta_x = \pm 2 \text{ mrad}$
	$\Delta y = \pm 4 \text{ mm}$	$\Delta\theta_y = \pm 0.5 \text{ mrad}$
EC	$\Delta z = \pm 1 \text{ mm}$	$\Delta\theta_z = \pm 1 \text{ mrad}$
	$\Delta x = \pm 4 \text{ mm}$	$\Delta\theta_x = \pm 2 \text{ mrad}$
	$\Delta y = \pm 2 \text{ mm}$	$\Delta\theta_y = \pm 0.5 \text{ mrad}$



=> Layout Version R'' to be implemented in version 12.0 (Not guaranteed to be clash free!)



- In the CSC Samples the CB simulation will still be "à la DC2"
 - evtgen files produced with Geant3/GCALOR (P.Nevski) from 'old' pregenerated fluxes provided by the Radiation Task Force (M.Shupe)
 - Recorded when crossing "scoring volumes" (SV)
 - Kine information converted to HepMC/POOL (A.Nairz, NB)
 - Produced with different safety factors already at the generation level
- Simulation, digitization, reconstruction will be performed by the Central Production
 - Cuts in range for the simulation tuned to track low energy particles

Known problem: slight multiple particle counting due to neutral particles crossing more than one SV

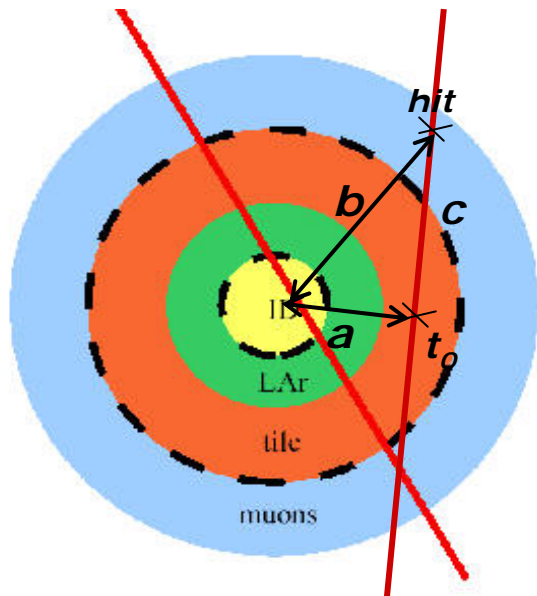
- An expected mean factor no larger than two with respect to the nominal fluxes

This is the best CB approximation available for the moment

- Used in the recent past by the reconstruction and trigger muon groups
- Work will be done to improve the present model



Muon System Simulation for Offline Commissioning with Cosmics



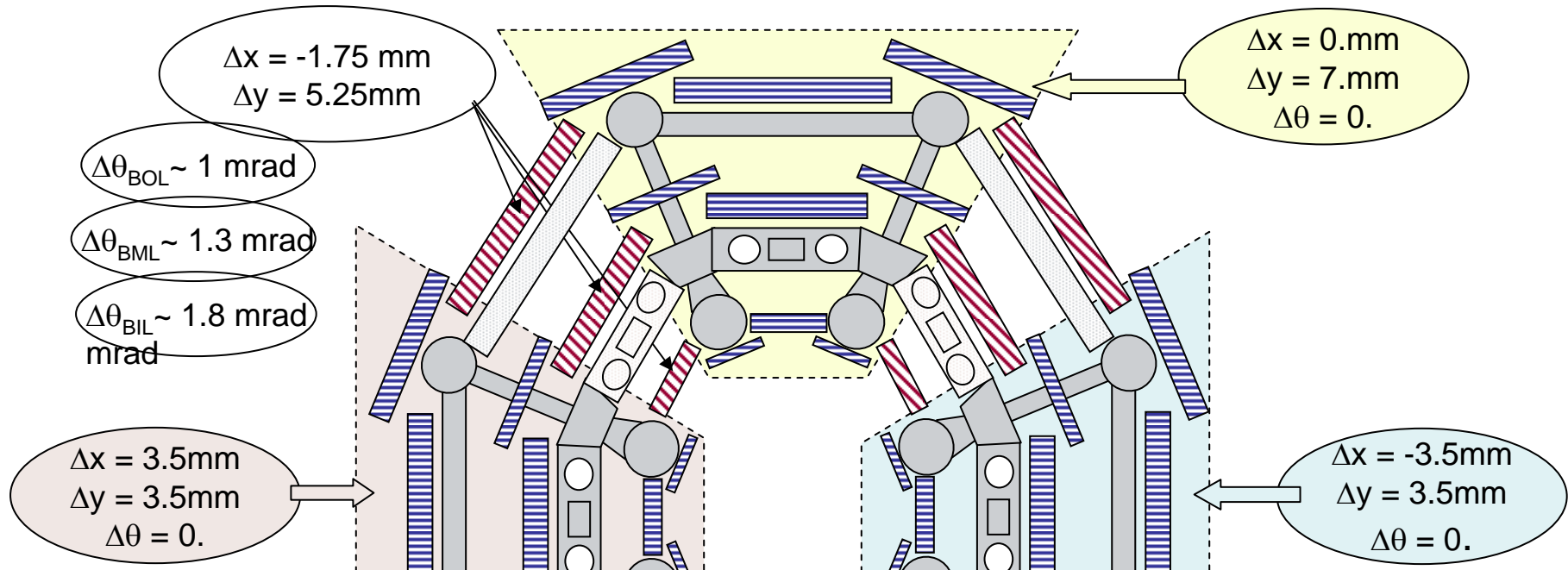
- Proposal to define t_0 as the time to the closest approach of the cosmic track to the $(0,0,0)$ vertex
 - Each track has its own t_0 which should be the same for all the subdetectors
 - In this scheme the time of flight is the distance of the hit w.r.t the t_0 point
-
- To calculate the time of flight for the cosmics in the simulation, the SensitiveDetector has been modified (in a private version for the moment)
 - The digitization windows match with this cosmic tof redefinition
 - Some validation samples have been produced
 - Validation efforts in collaboration with the reconstruction people (Stephane W. and Rosy N.)
 - When the SD will be fully validated, the SD code will be committed and a large scale production is foreseen
 - Needed by the LVL1 and LVL2 people



- All clashes in Barrel and Endcap region are understood
- Most of them are removed
- The clash-buster and Validation team has made great progress during the last week
 - This is also due to the good collaboration with Steve, Laurent and MuonGeoModel experts
- [Wiki-Web-page](#)
 - Restructuring the existing by putting all the necessary info
- ❑ **Full validation from Geometry to Digits between Releases has started**
 - *Giorgos D. is looking on Geometry*
 - RTT's
 - XO map
 - Material density for different values in ϕ
 - Positions of chambers
 - 'Eight Points For Our Chambers' to detect overlaps between chambers and between chambers and inert materials by means of Persint
- ❑ **Validation of Egg_shape layout (R') done (Matthias S.)**
- ❑ R' in Oracle for 11.4.0 (?)
- ❑ R' in MuonGeoModel (?)
- ❑ **We need time (~2 weeks)** for checks, fixes and possibly some further developments and (~ 2 weeks) testing the magnetic field
 - ❑ test of B1, B2, B3 – meshings
 - ❑ (provided(soon) by Laurent)
 - ❑ simulation pt=10,100,1000 GeV
 - ❑ adjustment of the size of the map for the DC3
 - ❑ The idea is to have a big step in the FM calculation therefore we'll have a less detailed map-MF



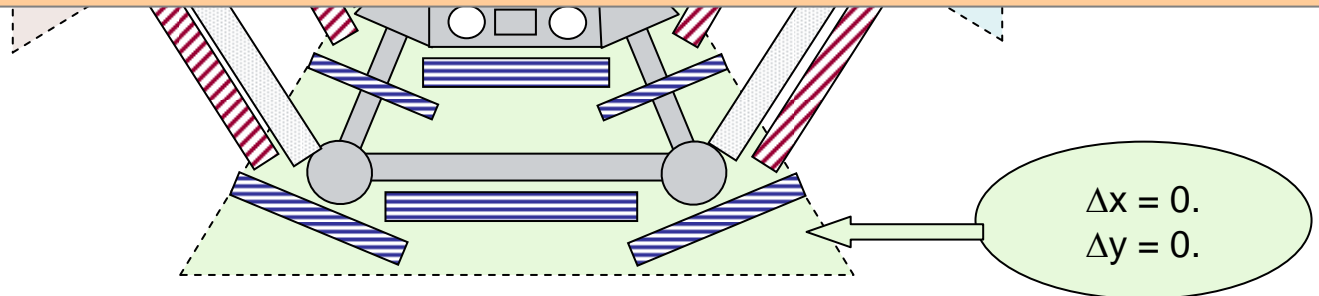
“As built” Muon Spectrometer geometry for the simulation



We expect no big differences in the PT-resolution, because

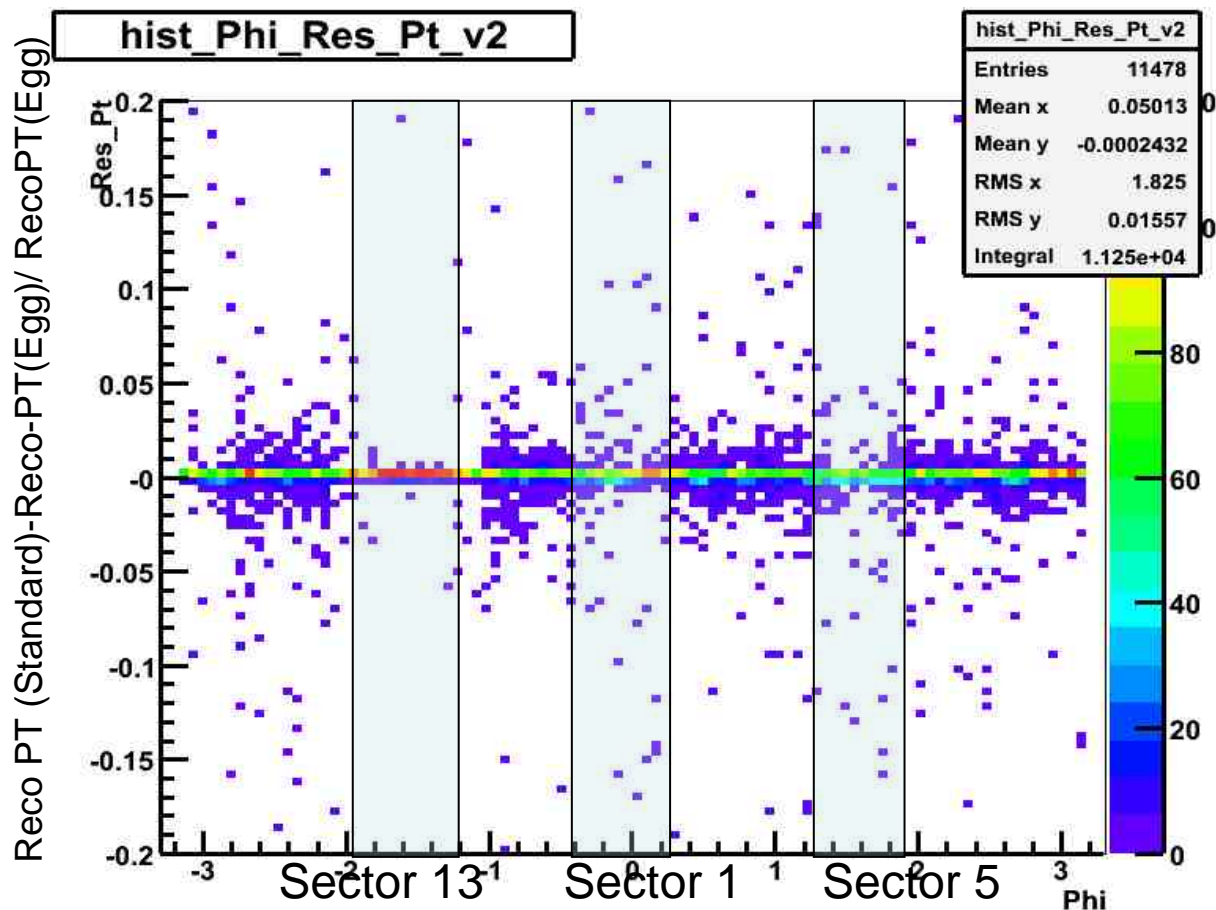
- section 13 is not touched at all
- there is no relative movements between Inner, Medium and Outer chambers of a given sector.
- Exceptions are only chambers 3,7,11 and 15.

Global barrel toroid deformation



Validation of the Egg-Shape Layout

- The Comparison between the Measured PT in the Standard and the Egg-shape-Layout on an **Event by Event Basis** provides a good opportunity to understand the Layout (Following Ideas from Jean-Francois



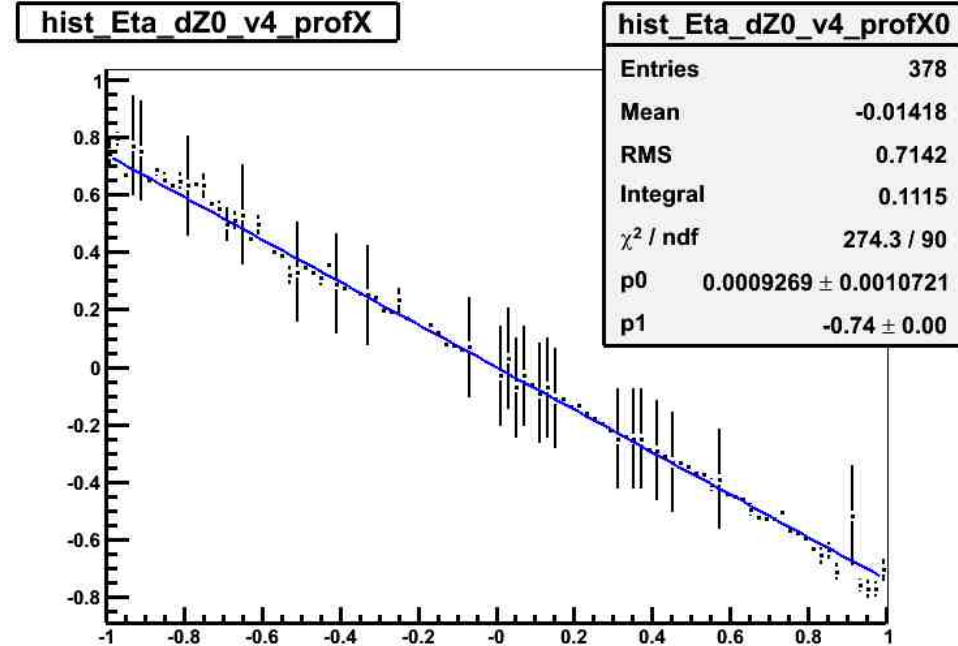
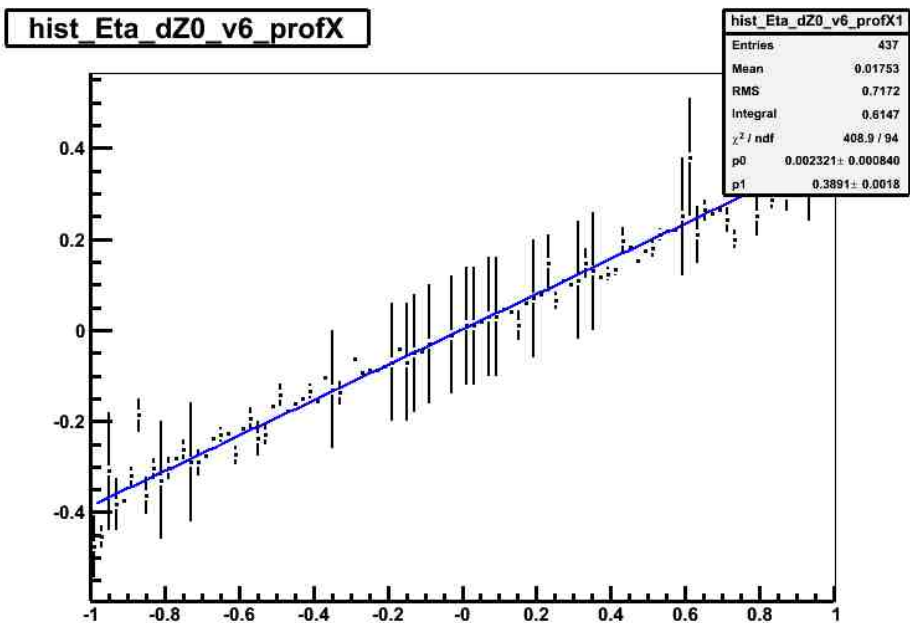
2006-03-02 12:20:45

- We expect no effect on the pT-Resolution for Sector 13: **OK**
- We expect very small effects on the pT-Resolution for Sector 1 and 5 and 9: **OK**
- We expect visible and identical effects for Sector 11 and 13 and Sector 3 and 7: **OK**



Validation of the Egg-Shape Layout

- Comparison between Impact-Parameter Z0 vs Eta on an **Event by Event Basis** provides a good opportunity to check the 7mm and the 3.5mm shift



- Sector 1: The line should start at -3.5mm and end at 3.5mm: **OK**

Others Sectors have been checked too.

- Sector 5: The line should start at 7mm and end at -7mm: **OK**



Validation of the Egg-Shape Layout

- Comparison between Parameter L0 vs Phi on an **Event by Event Basis** provides also a good opportunity to check the shifts
- $L0 = d\Phi_0 * \text{Distance} + R0$, where
 - $d\Phi_0 = \Phi_{\text{StandardLayout}} - \Phi_{\text{EggShapeLayout}}$
 - Distance = the Distance from Middle RPC to Interaction Point or Distance from Outer RPC to Interaction Point
 - $R0 = \text{Sqrt}(X^2 + Y^2)$, where X,Y=Impact-Parameters

Sector	dPhi*	dR0*	Distance M	Distance O	L0 with (M)	L0 with (O)	Expected [mm]
1	-0,000270	-1	7100	9800	-2,917	-3,646	-3,5
3	-0,000300	-1,5	7100	9800	-3,63	-4,44	-4,9
7	0,000280	1,7	7100	9800	3,688	4,444	4,9
9	0,000250	1,4	7100	9800	3,175	3,85	3,5

- *Gaussian Fit-Error 10 %
- Everything look fine ! (Other Sectors have been checked too)

