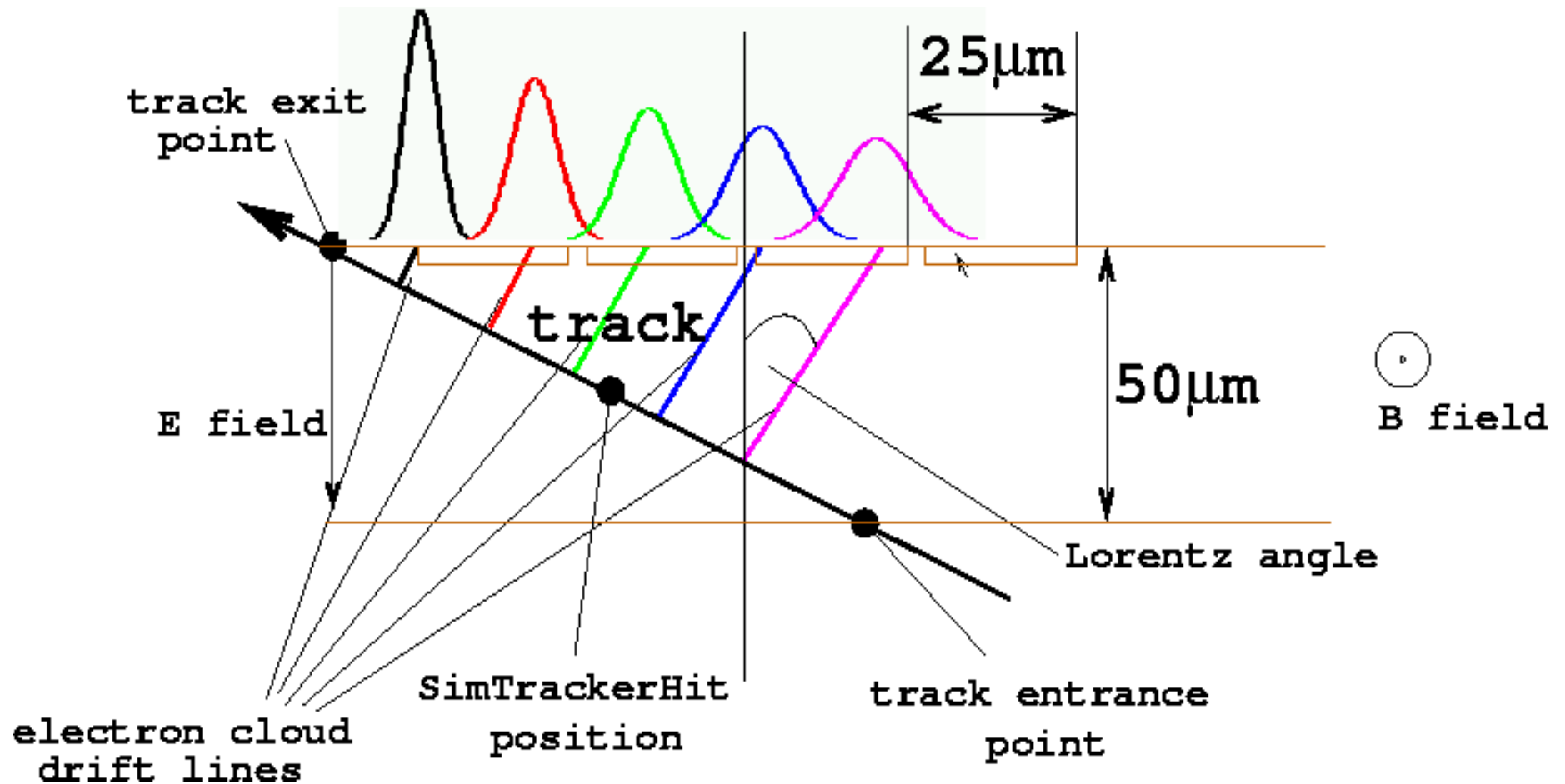


- Effect of Magnetic Field on VXD Performance
- Response of DEPFET Sensors to Inclined Tracks

Alexei Raspereza

ILC-MPI Meeting May 15

Lorentz Effect

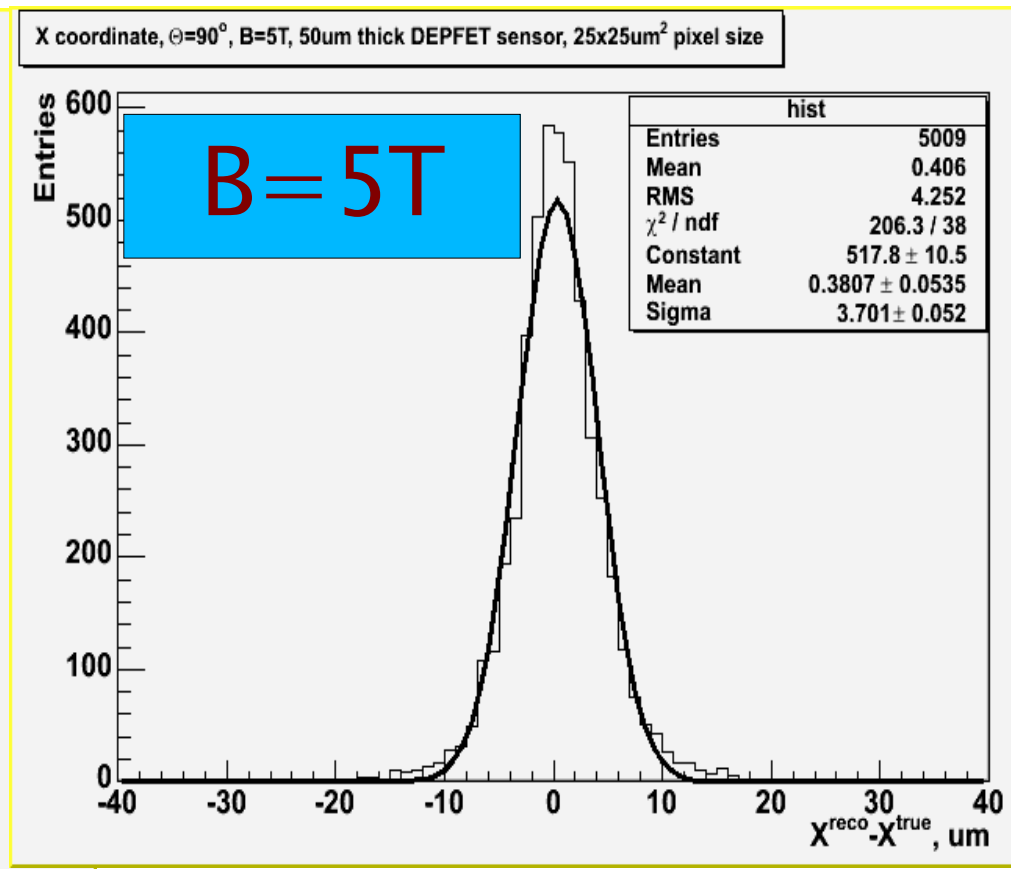
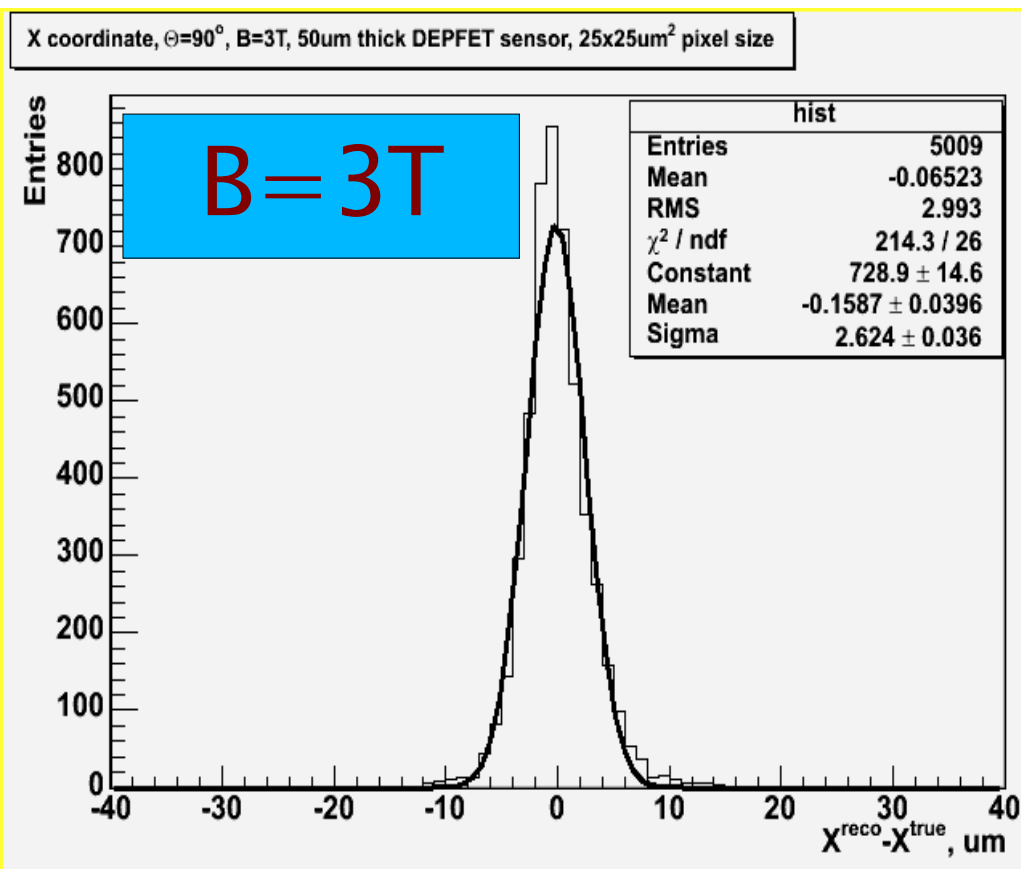


$$\tan\theta_L = \mu r_H B$$

Reference Points

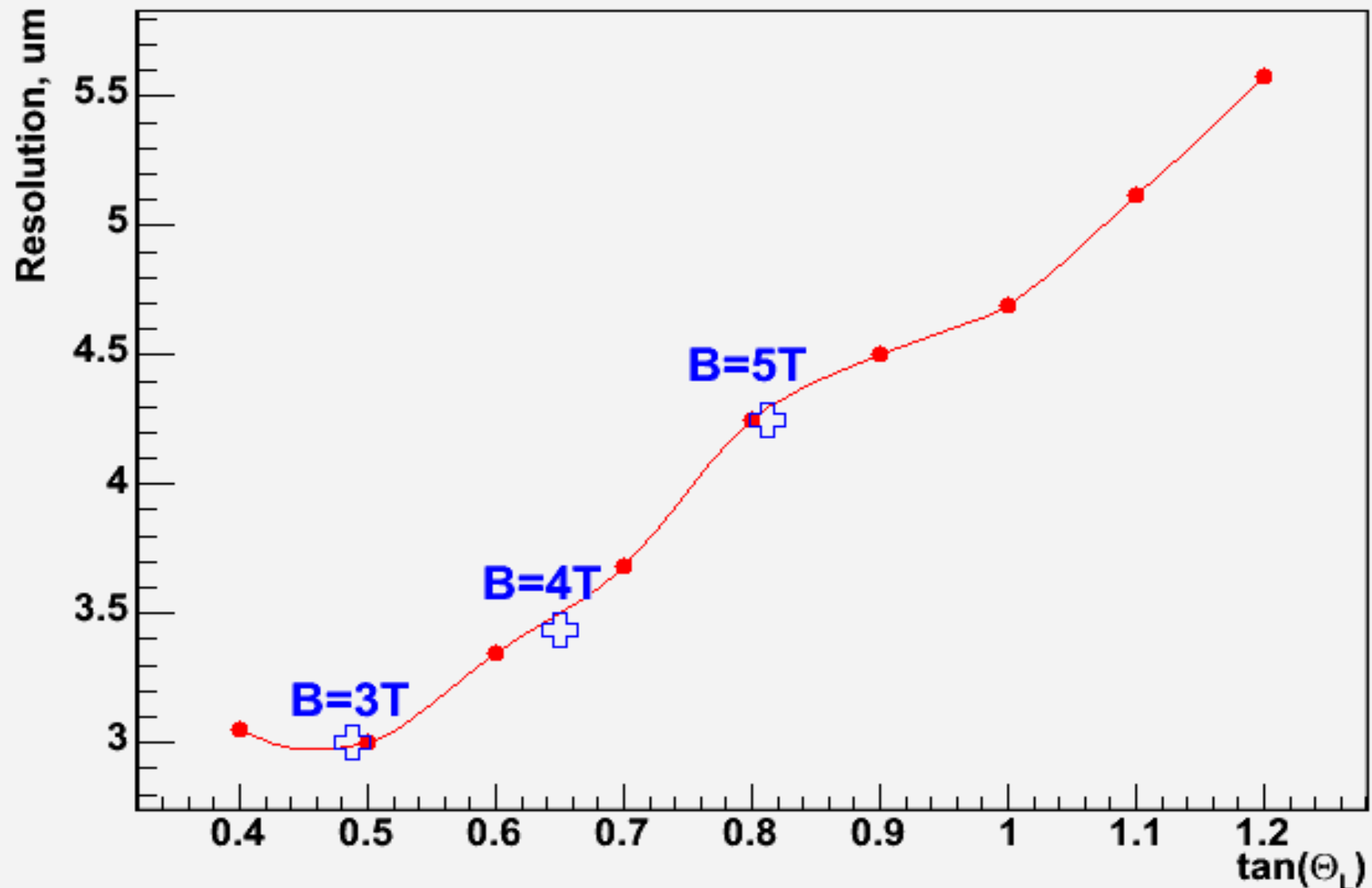
- θ_L has been measured @ 4T field
 - $\theta_L(4T) = 33^\circ$ [W.Boer *etal.* NIM A461 (2001) 200]
- Experimental data and theory : $r_H(B) \approx 1 \Rightarrow$
- $\tan\theta_L(B) = \tan\theta_L(B_0) \times B/B_0 : B_0 = 4T \Rightarrow$
 - x $\tan\theta_L(3T) \approx 0.49$ (GLD);
 - x $\tan\theta_L(4T) \approx 0.65$ (LDC);
 - x $\tan\theta_L(5T) \approx 0.81$ (SiD);

$R\text{-}\phi$ Resolution for normally incident tracks



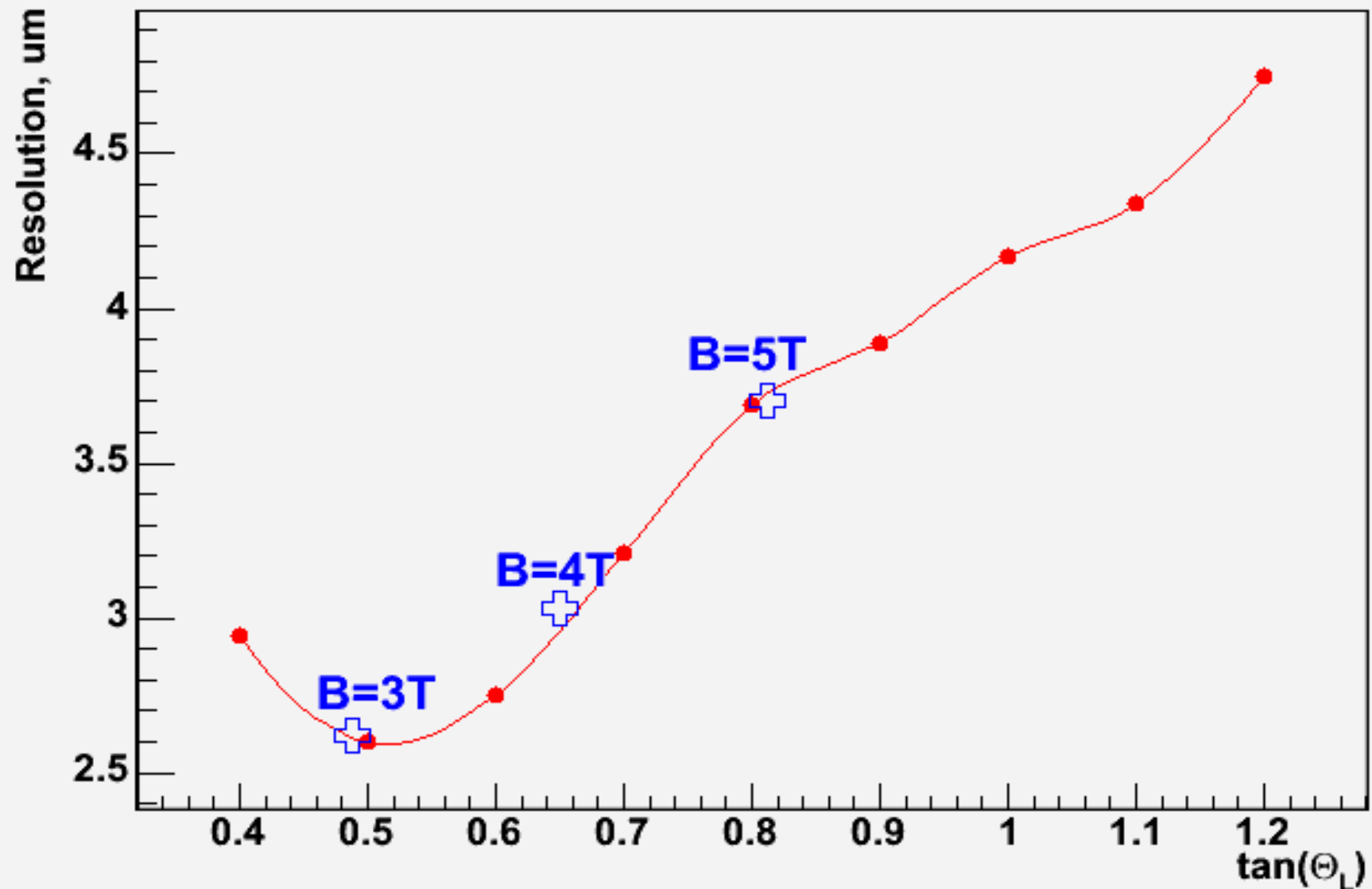
R - ϕ Resolution

Point Resolution (RMS) vs $\tan(\Theta_L)$

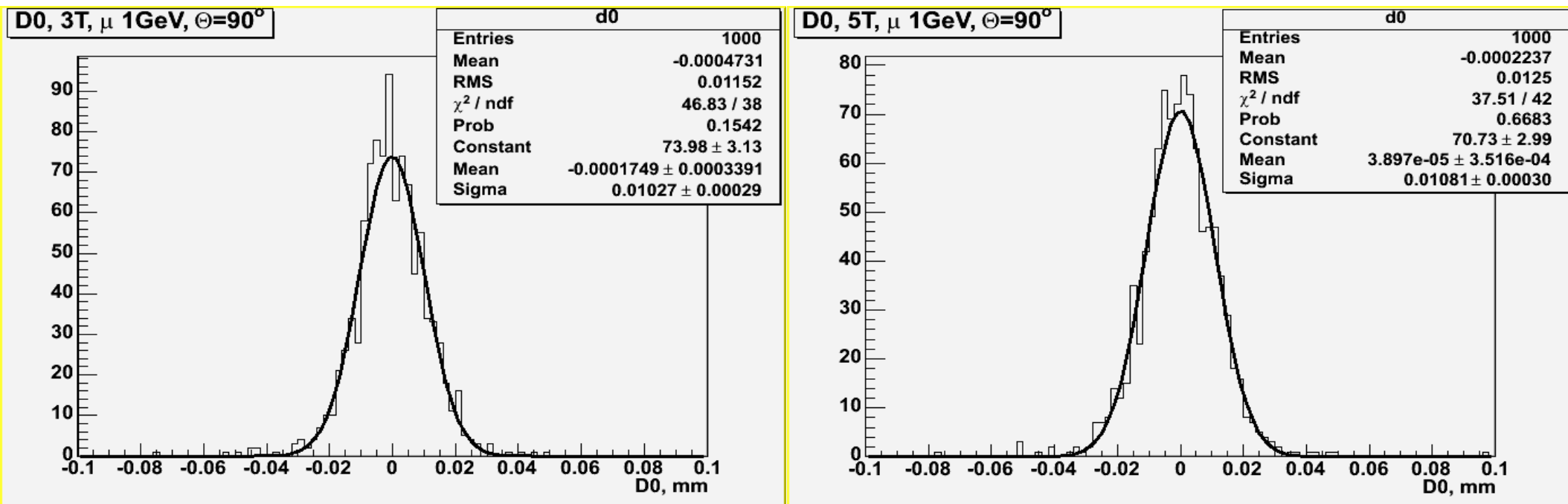


R - ϕ Resolution

Point Resolution (Gaussian Width) vs $\tan(\Theta_L)$

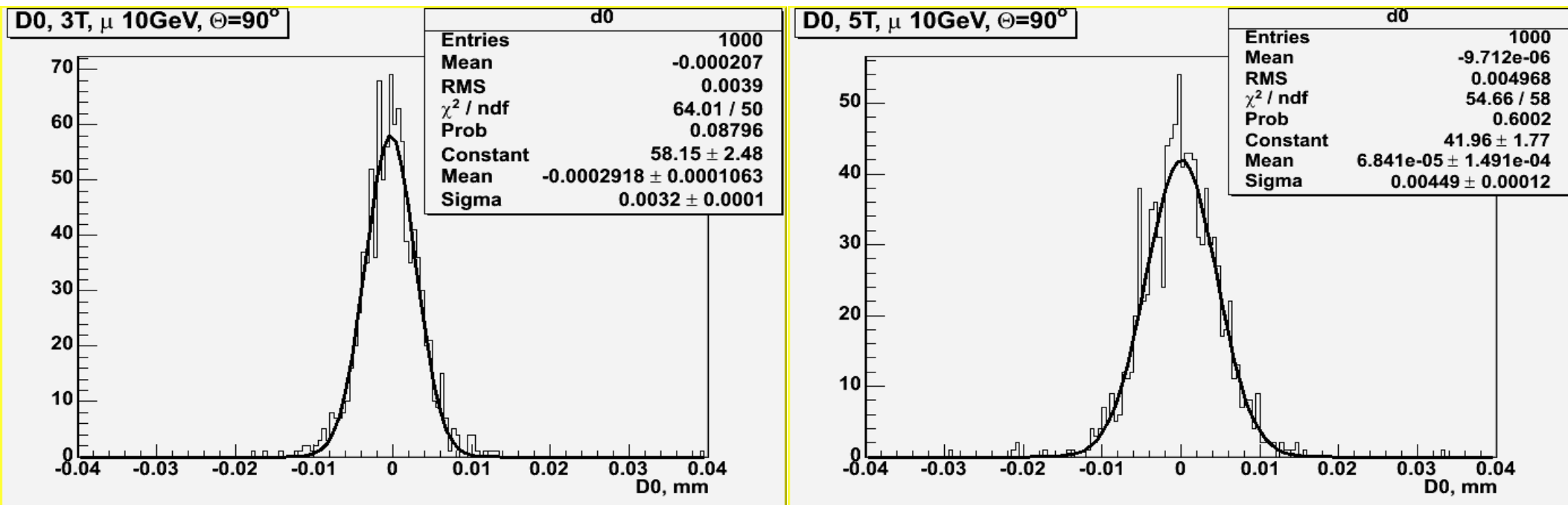


IP Resolution (low p_T tracks)



IP resolution dominated by multiple scattering [b-term ; $\sigma = a \oplus b/p_T \cdot \sin^{3/2}\theta$] $\Rightarrow$ marginal B-field effect

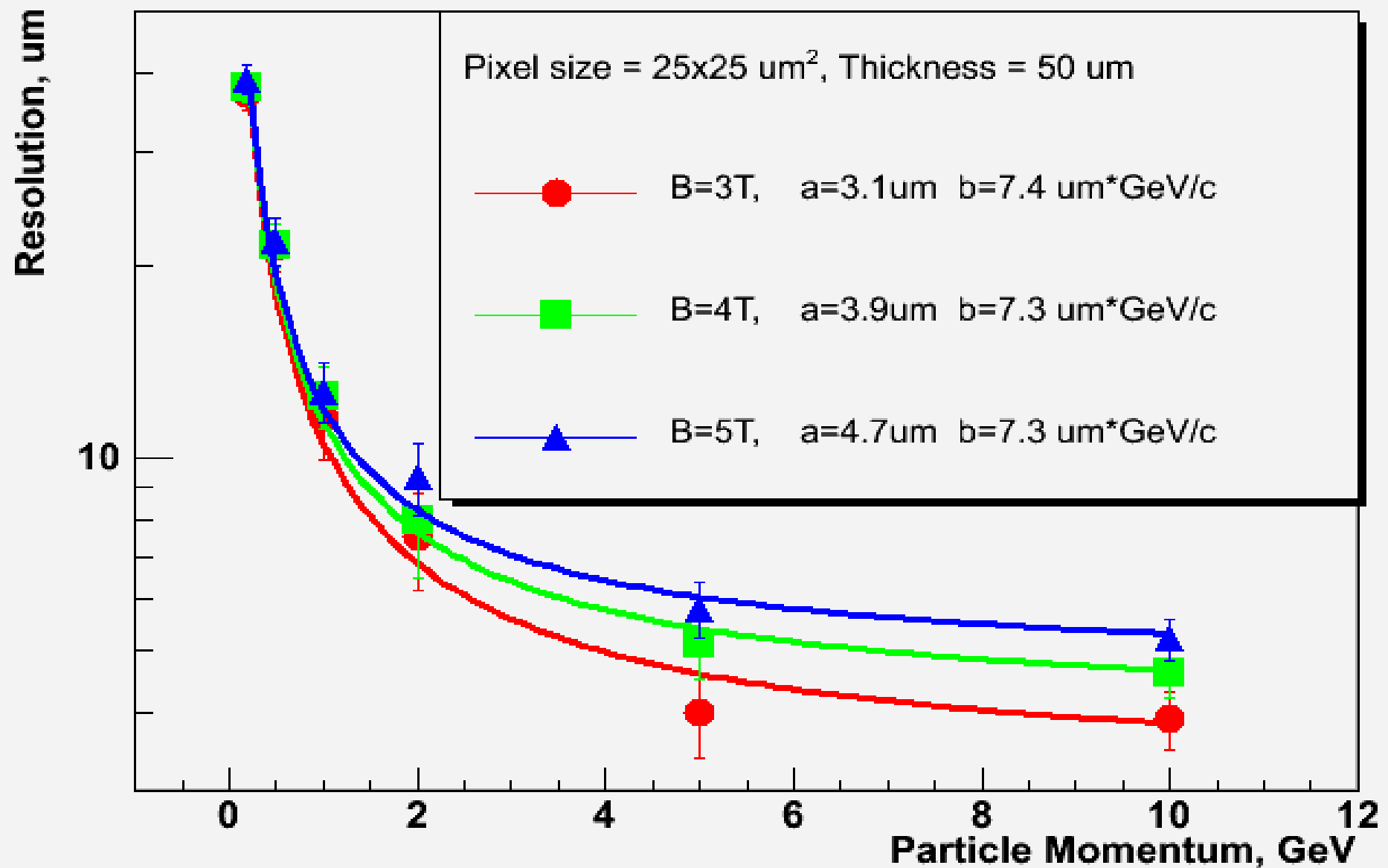
IP Resolution (high p_T tracks)



IP resolution dominated by spatial point resolution [a-term ; $\sigma = a \oplus b/p_T \cdot \sin^{3/2}\theta$] $\Rightarrow$ sizable B-field effect

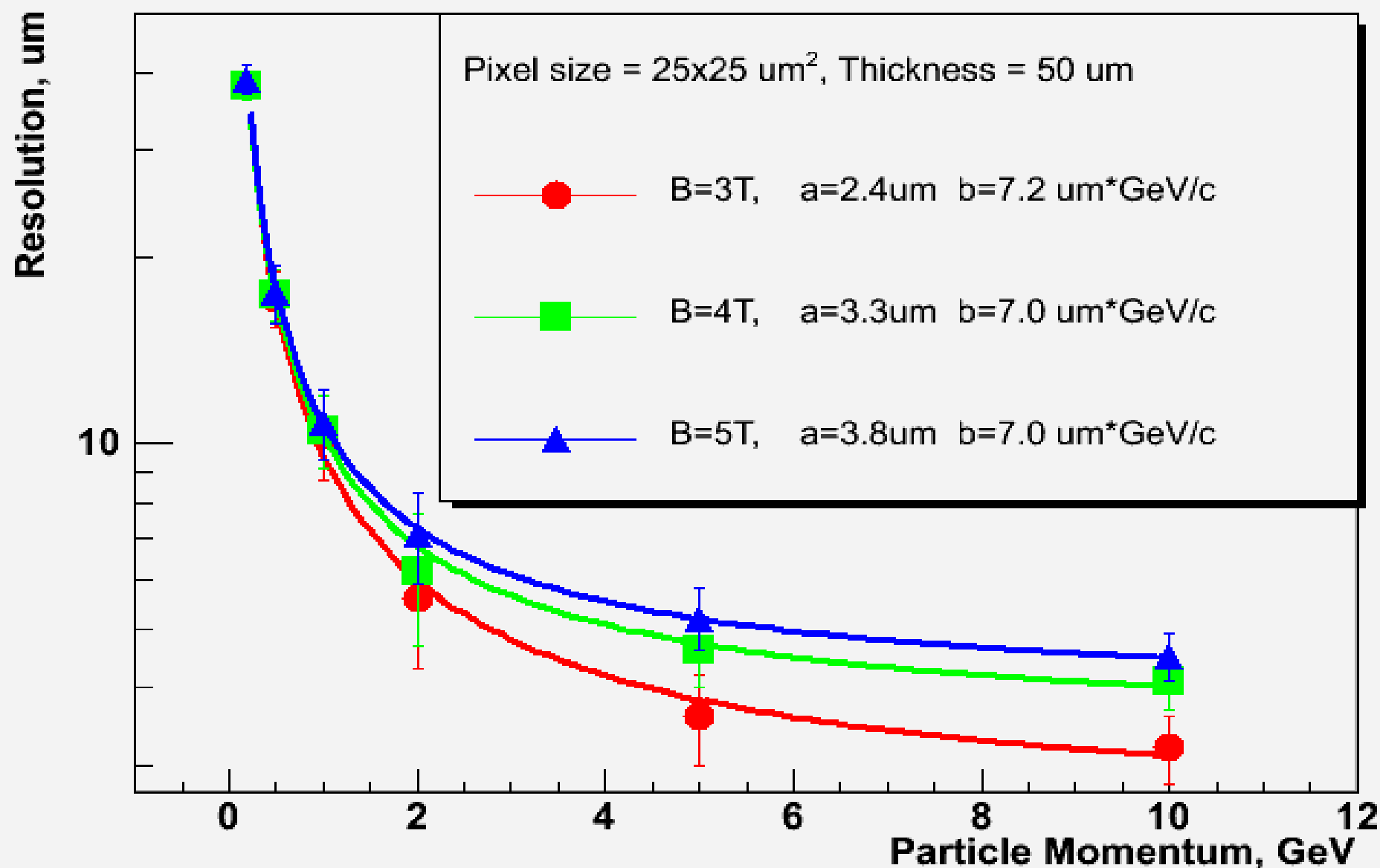
IP Resolution [RMS]

D0 Resolution [RMS]



IP Resolution [Gauss Width]

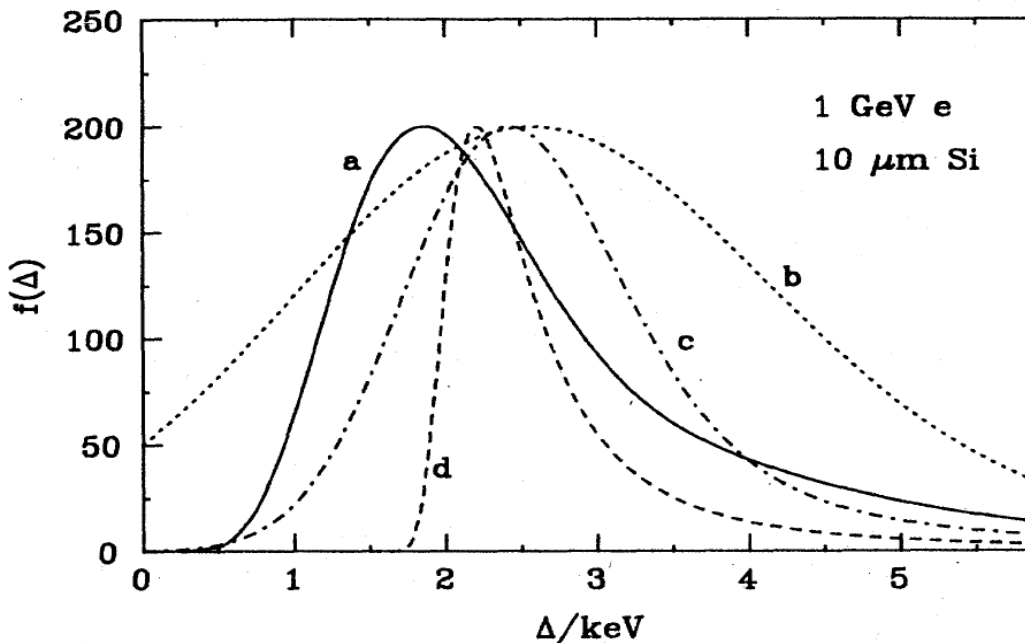
D0 Resolution [Gauss width]



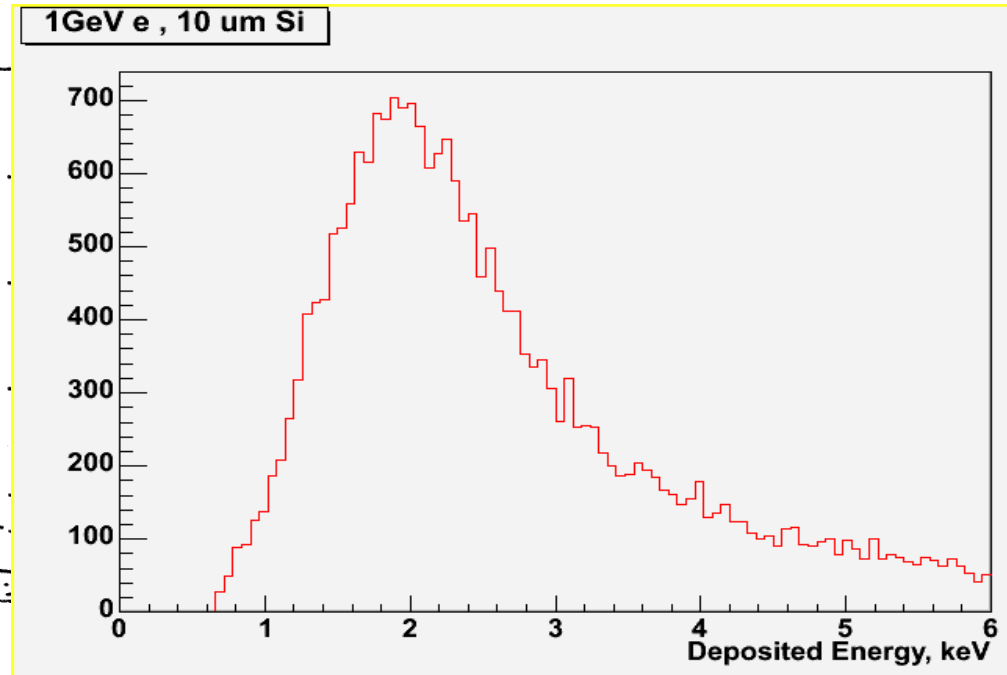
Is G4 Simulation of E_{loss} Fluctuations @ Short Flight Distances reliable?

H.Bichsel

Rev. Modern Physics 60-3 (1998)
plot a)



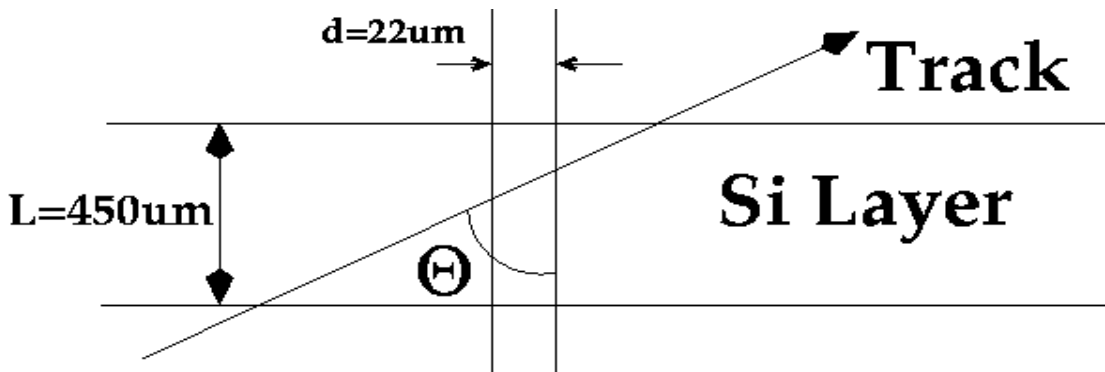
G4 Simulations



DEPFET Sensor Response to Inclined Tracks

- Particularly interesting data

- Allow to check simulation of straggling functions at short flight distance / thin Si sensors

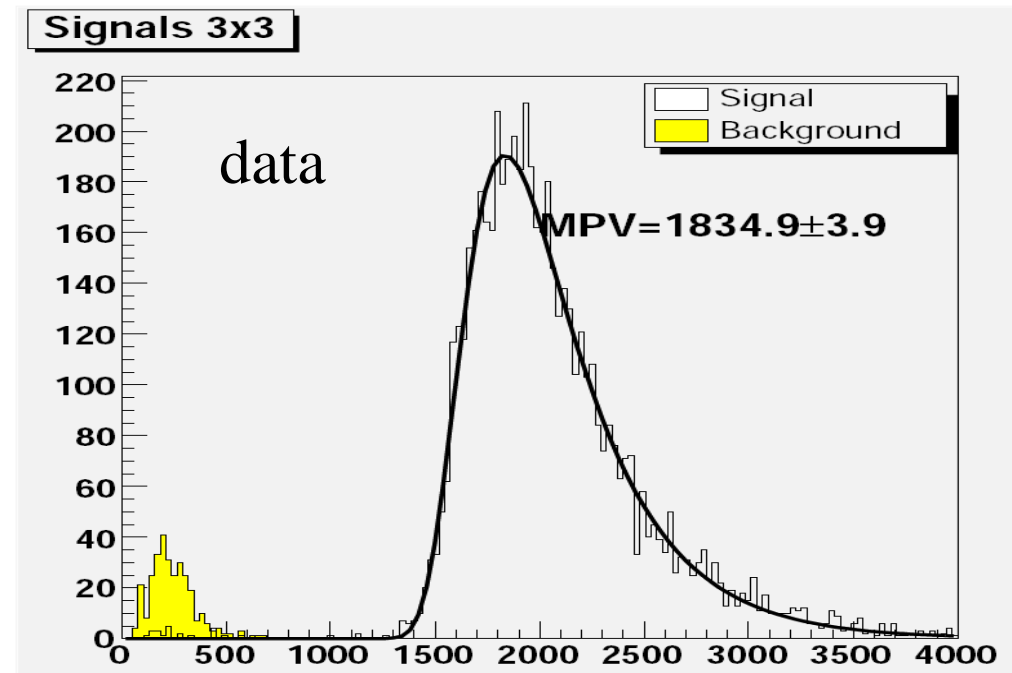
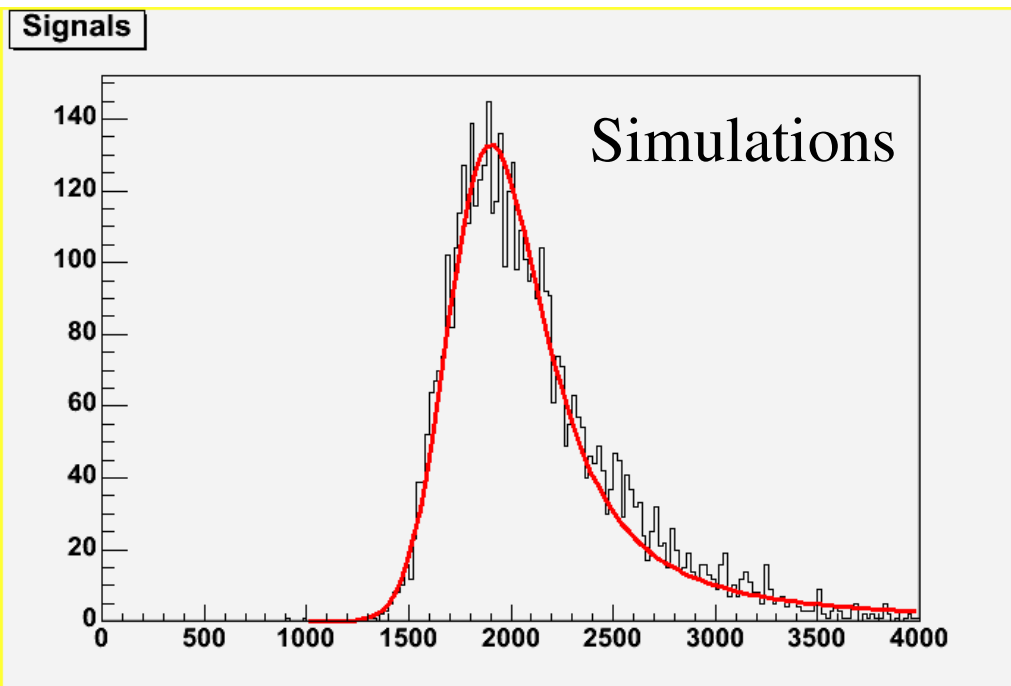


**G4 Simulations can be probed
@ a scale $\approx d/\sin\theta$;
 d – pixel size;
 θ - track incidence angle**

Analyzed DEPFET Matrix (Hyb2A):

- Pixel dimensions : $D_x = 36 \mu\text{m}$, $D_y = 22 \mu\text{m}$;
- Layer thickness = $450 \mu\text{m}$; electronic noise = $300 e^-$
- Rotations up to 40° around X axis [θ -rotations] and Y axis [ϕ -rotations] are performed

Total Cluster Amplitude (Normal Track Incidence)



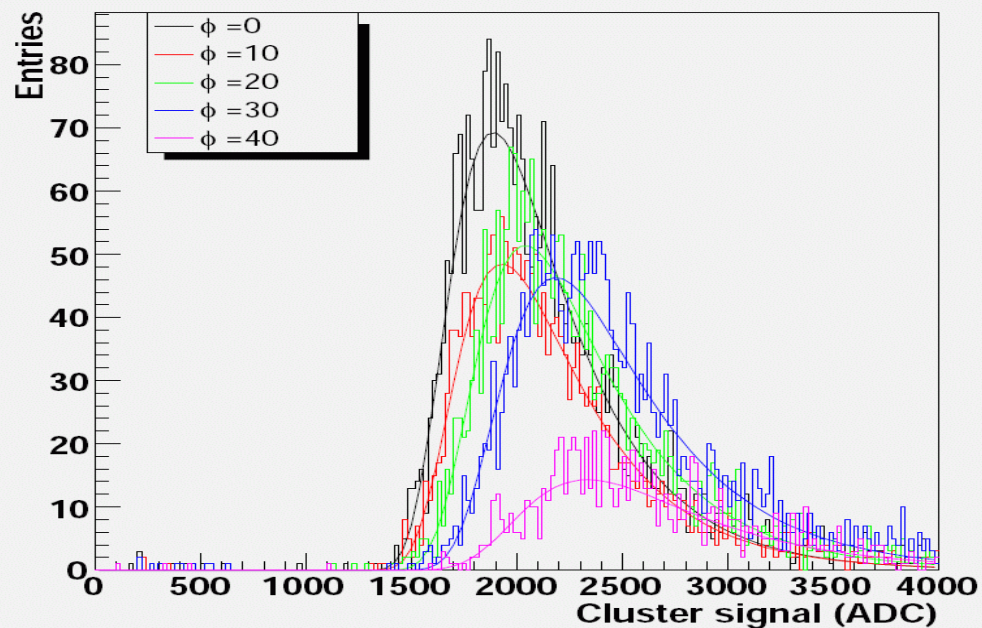
Data collected at normal track incidence is
used to derive coefficient converting
 E_{loss} into ADC counts

Amplitude Distribution vs Incidence Angle

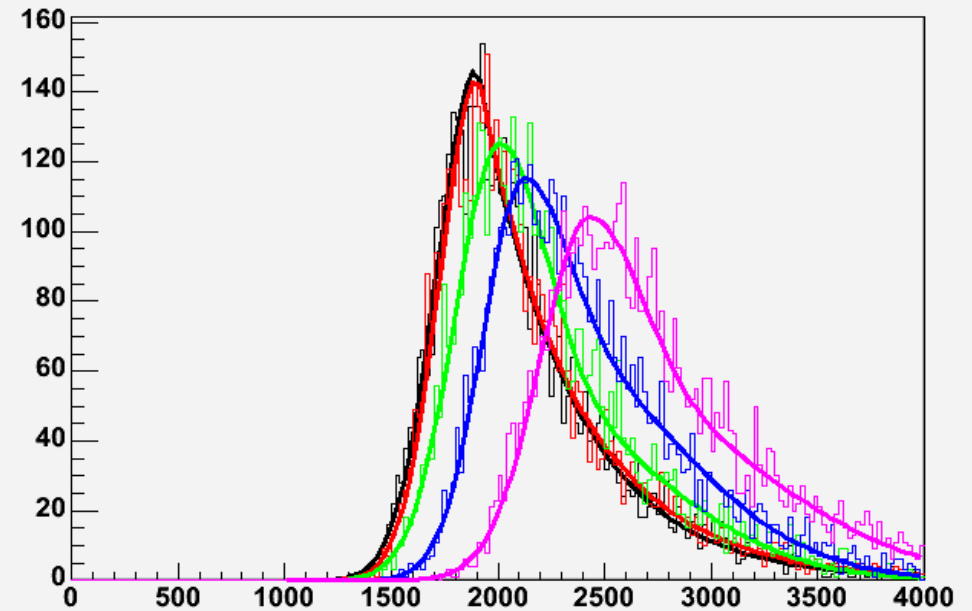
Testbeam data

Simulations

Signals 3x3

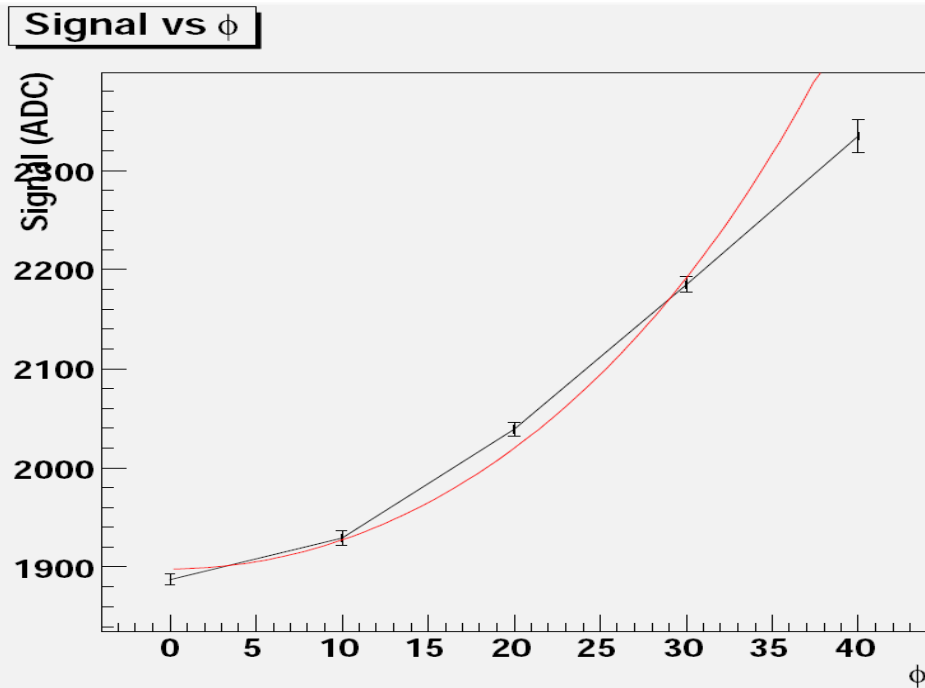


Signal

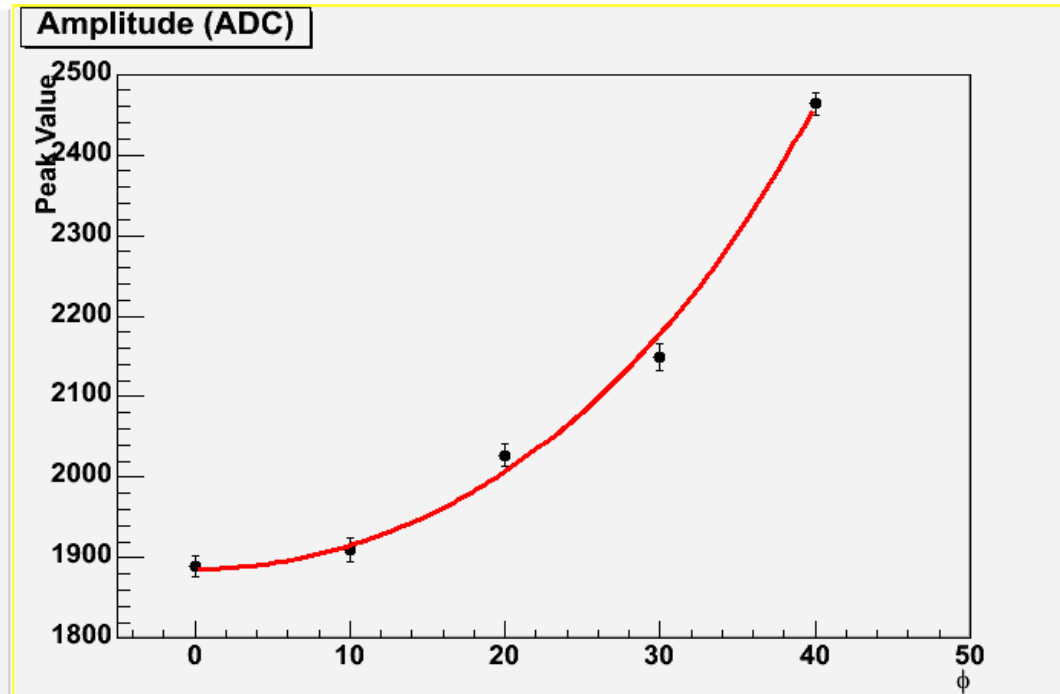


Peak Value vs Incidence Angle

Testbeam data



Simulations

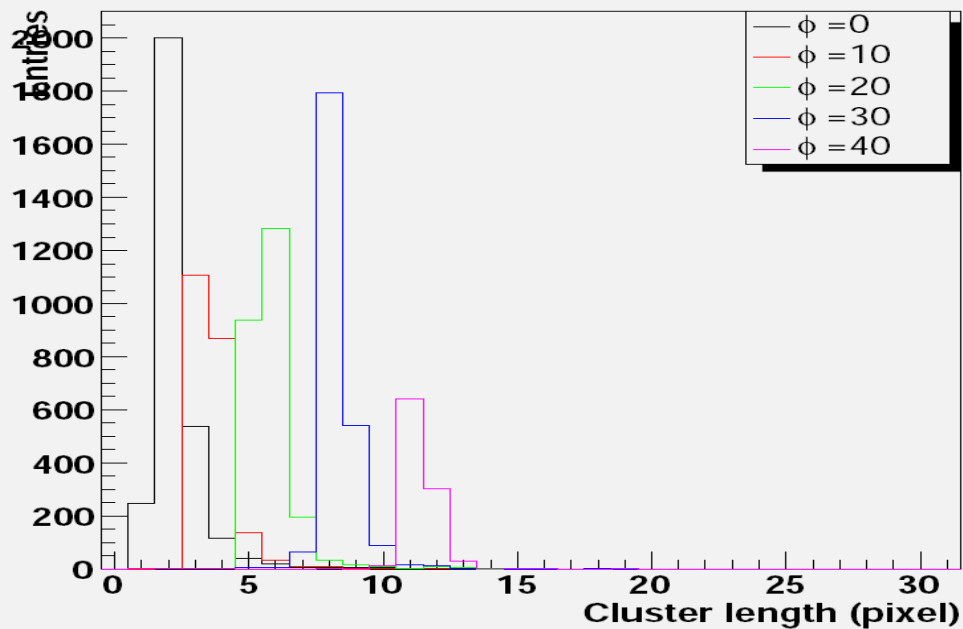


Cluster Length X vs Incidence Angle

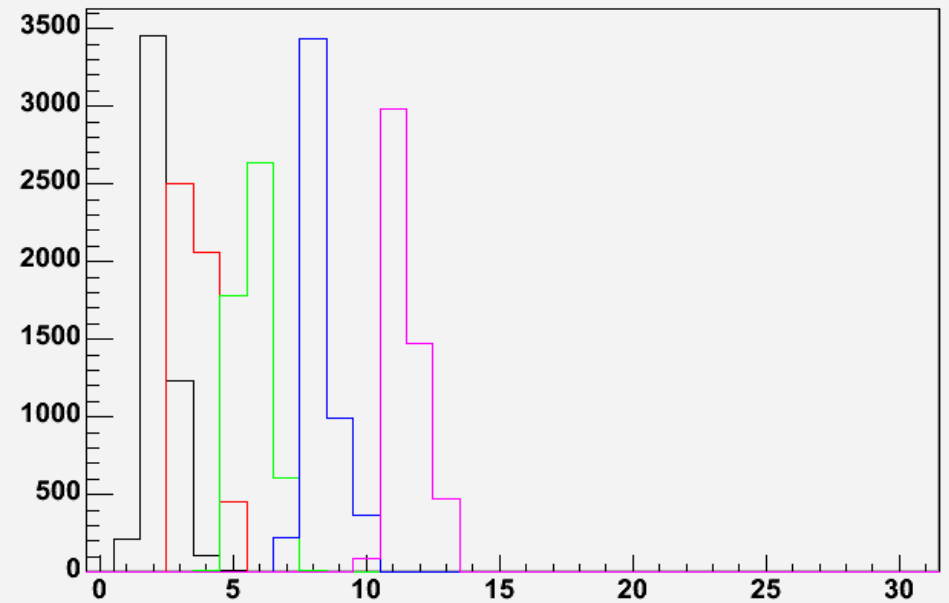
Testbeam data

Simulations

Cluster length X no edge



Cluster Size X

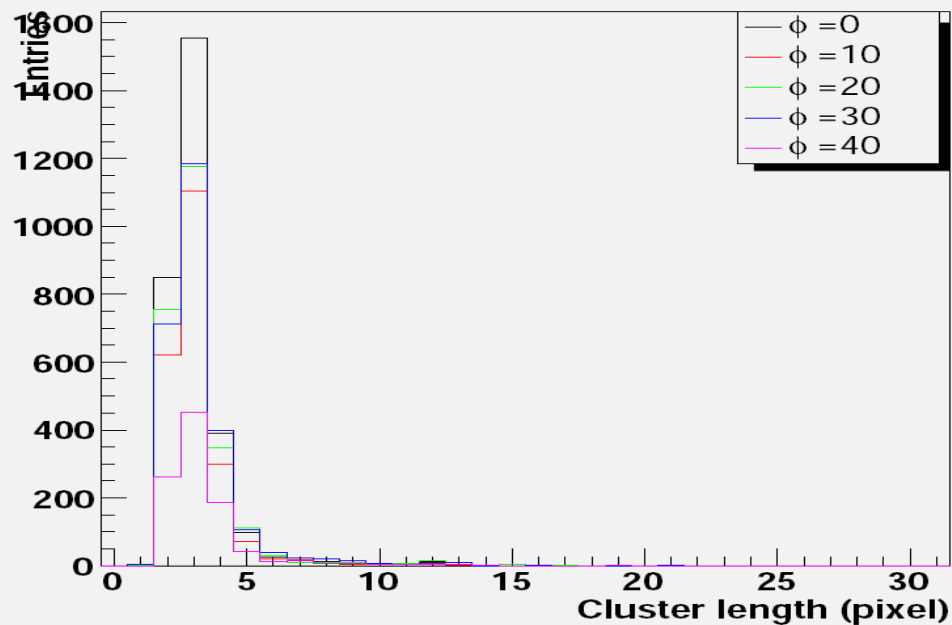


Cluster Length Y vs Incidence Angle

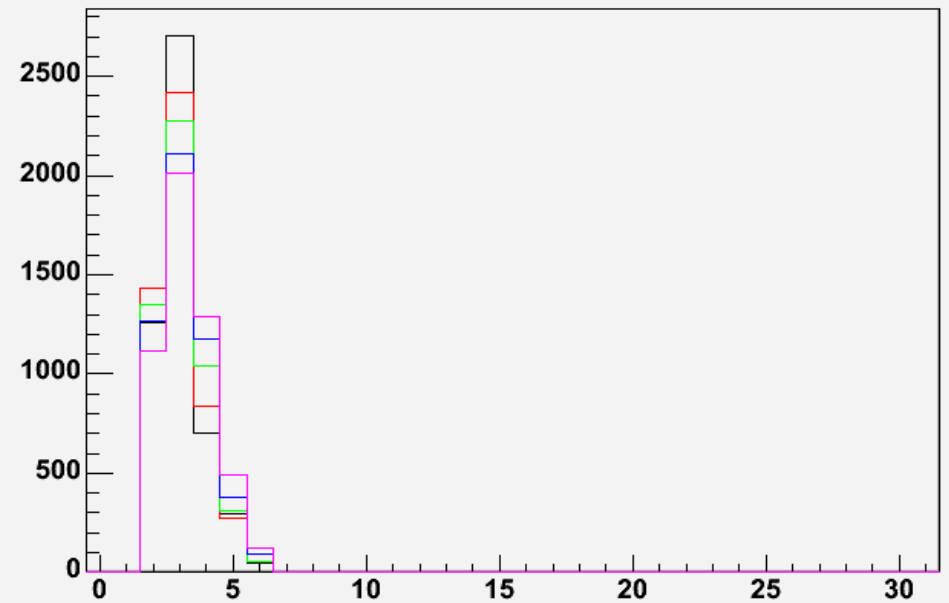
Testbeam data

Simulations

Cluster length Y no edge



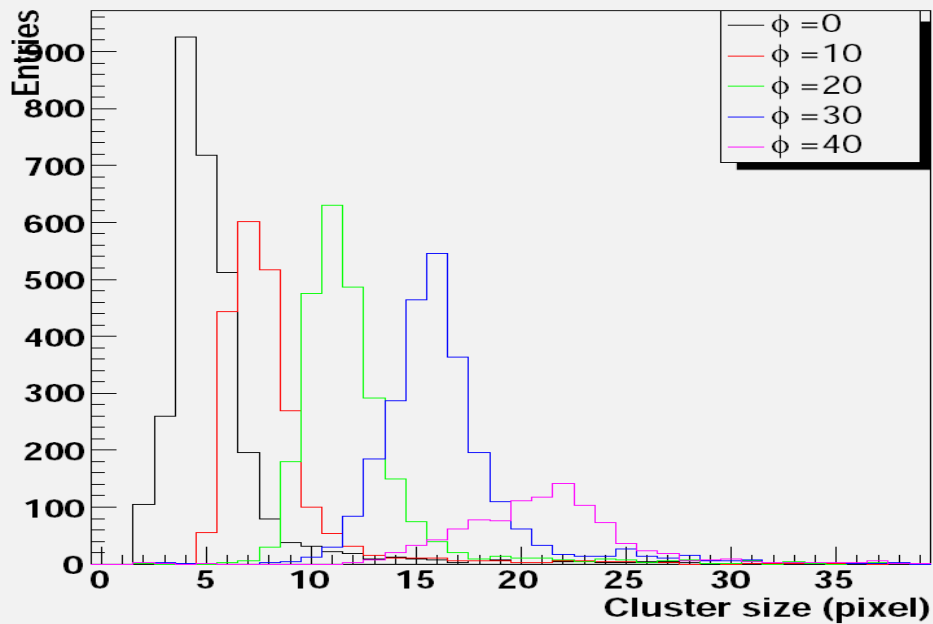
Cluster Size Y



Cluster Size vs Incidence Angle

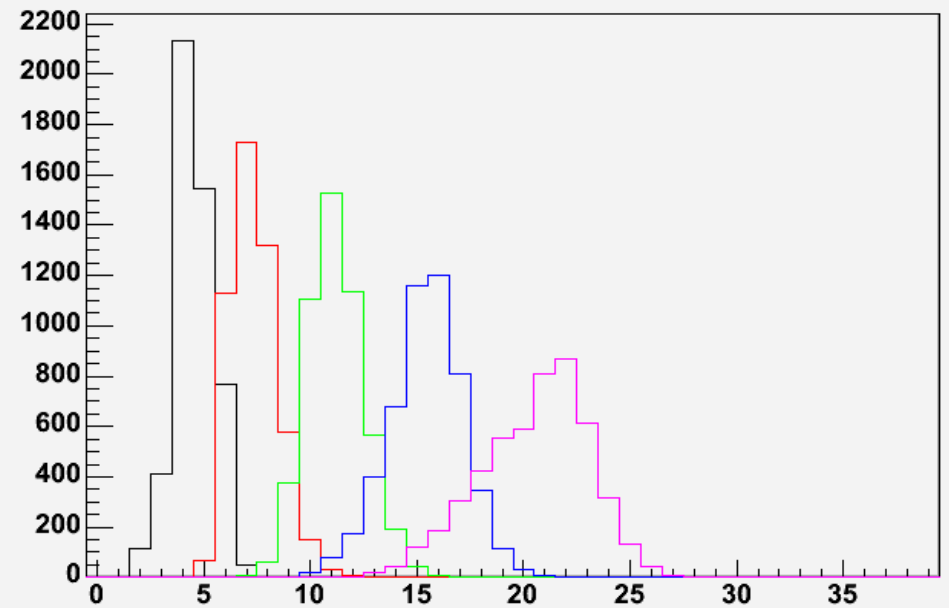
Testbeam data

Number of pixel 3x3



Simulations

Cluster Size



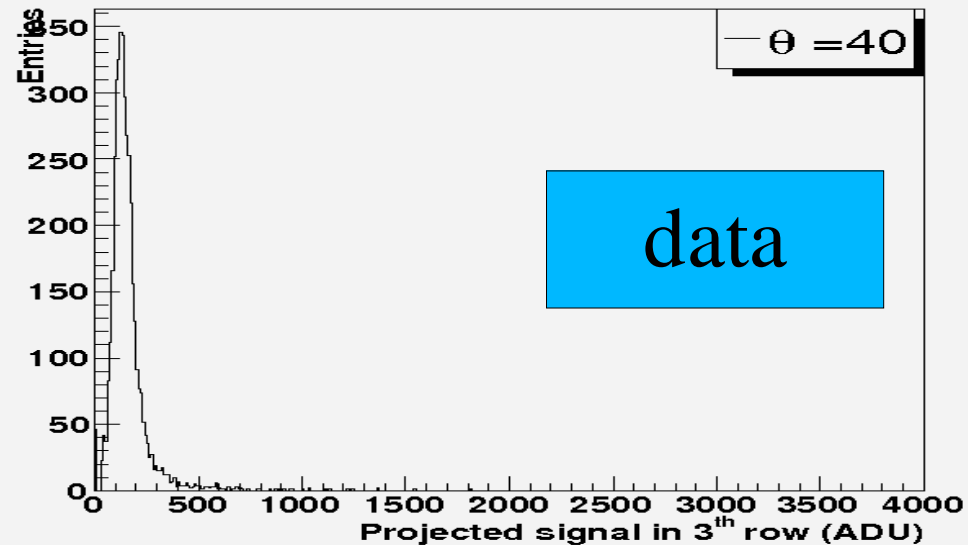
Probing Straggling Functions @ short flight distance

- Validity of G4 simulation of energy loss fluctuations @ short flight distances can be probed by investigating distributions of signal projection on pixel rows (columns) perpendicular to the inclined track momentum
- Probed scale :
$$D_{x,y}/\sin(\theta,\phi), \quad D_{x,y} \text{ being pixel dimensions}$$
- Expected mean signal on central rows (excluding edges) :
$$A_{\text{row,column}} \approx A_0 D_{x,y} / (L \cdot \sin(\theta,\phi)),$$

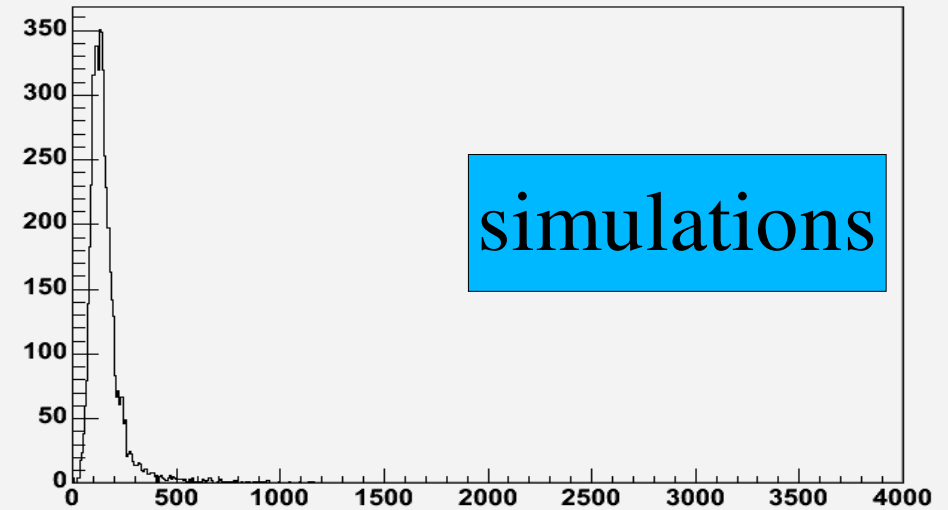
L is layer thickness,
 A_0 is total cluster amplitude for normally incident track
- In the following only few representative columns(rows) are shown

Signal projected on pixel rows [θ -rotation; $\theta=40^\circ$]

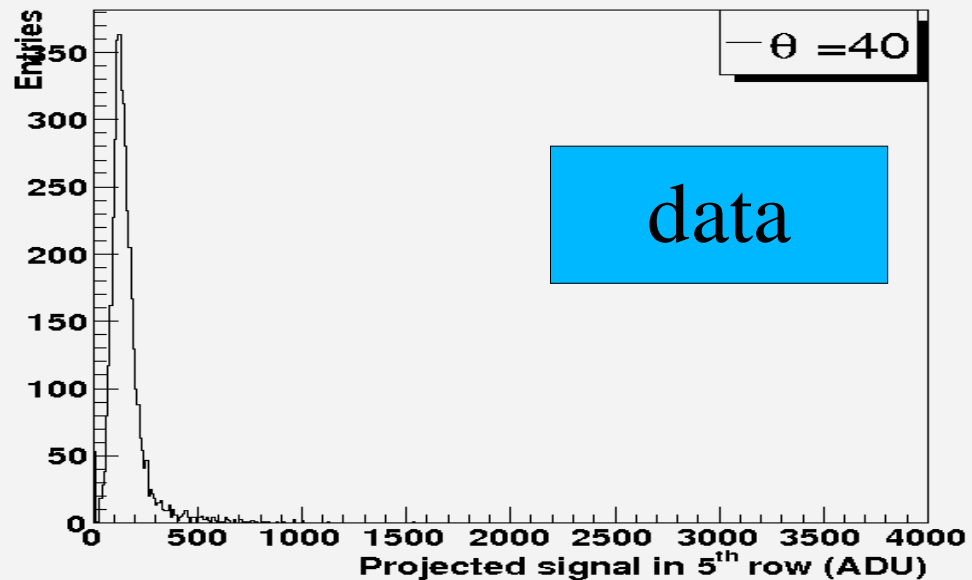
Signal projected row 3



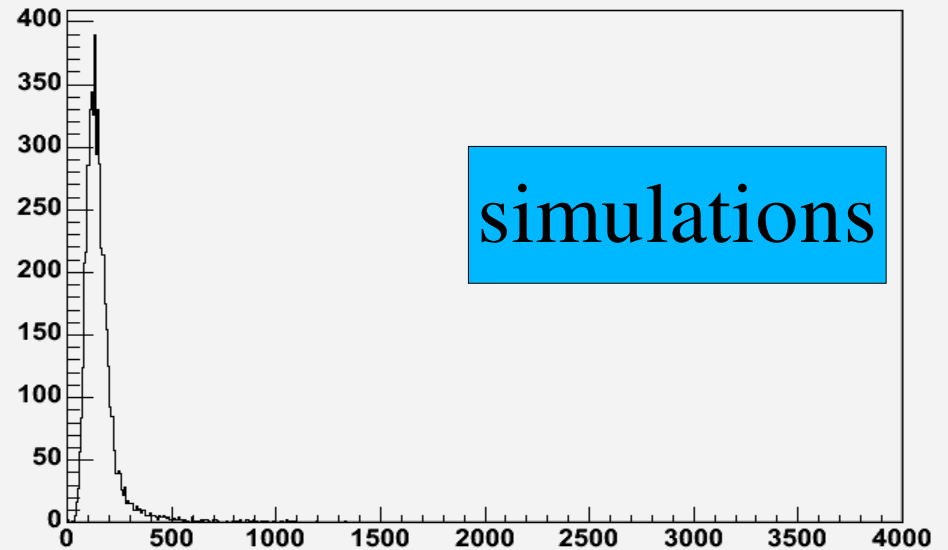
Signal Projected row 3



Signal projected row 5

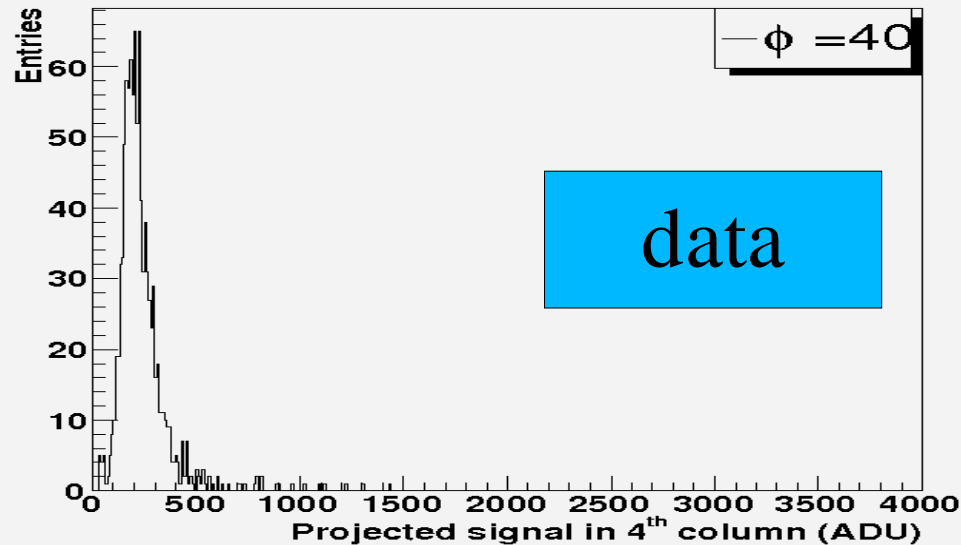


Signal Projected row 5

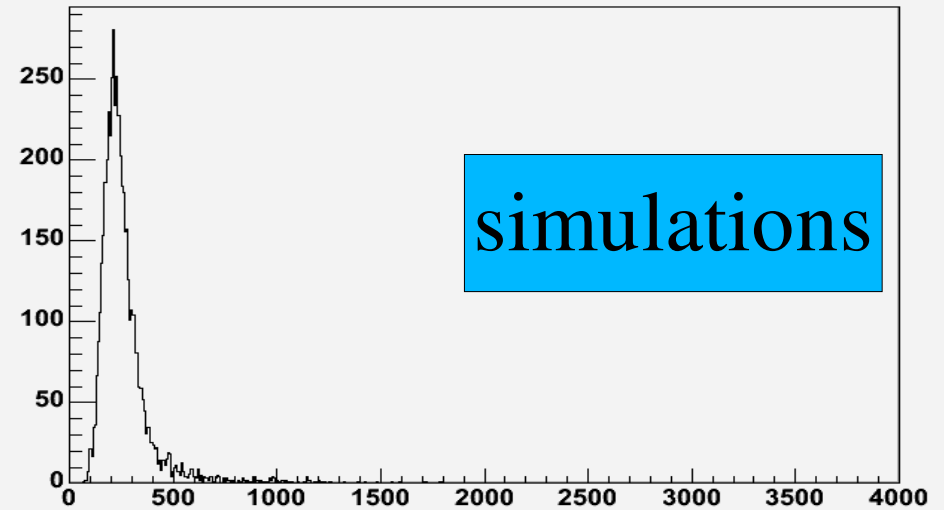


Signal projected on pixel columns [ϕ -rotation; $\phi=40^\circ$]

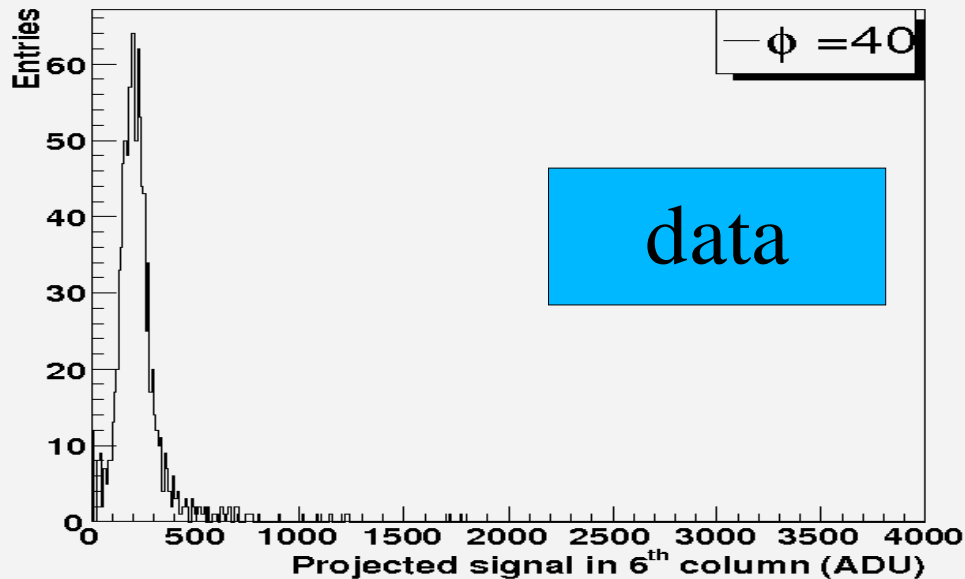
Signal projected column 4



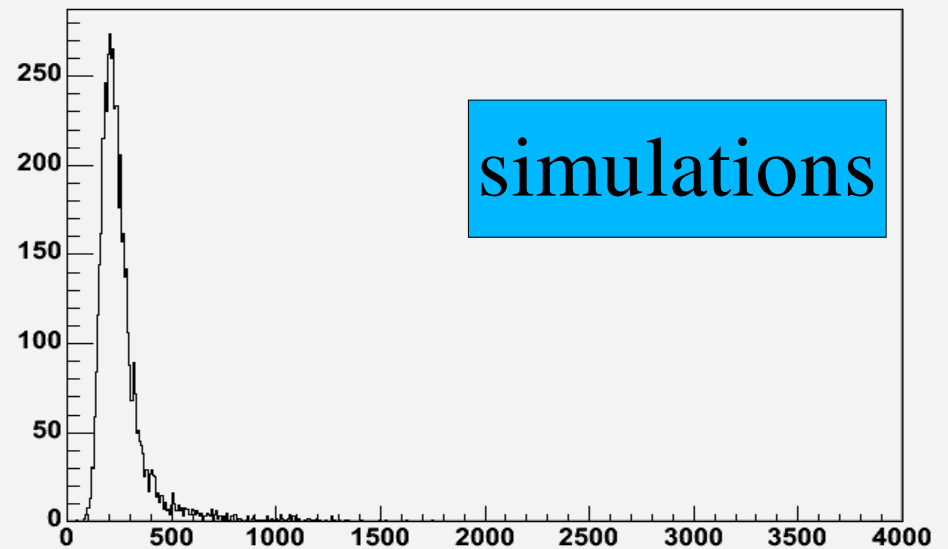
Signal Projected column 4



Signal projected column 6



Signal Projected column 6



Concluding Remarks (1)

- ◆ Simulation study of magnetic field effect on the DEPFET based VXD performance is performed
- ◆ Effect is evaluated in terms of single point and impact parameter resolution
- ◆ No drastic deterioration of VXD performance with increasing magnetic field is found
- ◆ At 5T field VXD performance still meets ILC physics requirements

Concluding Remarks (2)

- ◆ Simulations of DEPFET sensor response to inclined tracks are performed and compared to testbeam data
- ◆ Simulation of E_{loss} fluctuations is verified @ short flight distance of ionizing particles utilizing testbeam data collected at track incidence angles up to 40°
- ◆ These data allow to probe E_{loss} fluctuations @ a scale of $d/\sin\theta \approx 30\mu\text{m}$, where d is the pixel dimensions and θ is the track incidence angle
- ◆ Good agreement between simulations and data is found giving confidence in Geant4 MC simulations