



Grounding & Shielding

Main issues

(electronics integration)

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OUTLINE

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- 2. Grounding
 - Recommendations
- 3. Noise sources
 - Switching converters
- 4. Noise victims
 - FEE
- 5. Conclusions

1. Introduction

- The electronics integration is an important task in a HEP experiment .
- The main goal is to ensure the correct performance of HEP detectors or experiments.
- Electronics integration is mainly defined by three elements:
 - Grounding strategy
 - Noise sources
 - Noise victims

2. Grounding

- What is a ground ?
 - It is a reference
 - Uniform reference voltage at any frequency
 - It is a structure to bypass currents
 - Fault (short circuits ..)
 - Noise
- Reasons for Grounding
 - Safety
 - Equipment protection
 - Equipment performance
- Golden rule:
 - **“Make the system safe and then make it work”**

2. Grounding: Some recommendations

- **Selection of reference** (grid 3D or plane)
 - Detector & Experiment level
 - Reinforcement structure
 - Any metal structure
 - It should have low impedance from DC to High frequency
- **Safety ground & Equipment protection**
 - Laboratory codes and European directives.
 - Metal parts that can be energized – should be grounded
 - Ground connections - Bonding and straps
 - Ground path should be free of operational currents

2. Grounding: Some recommendations

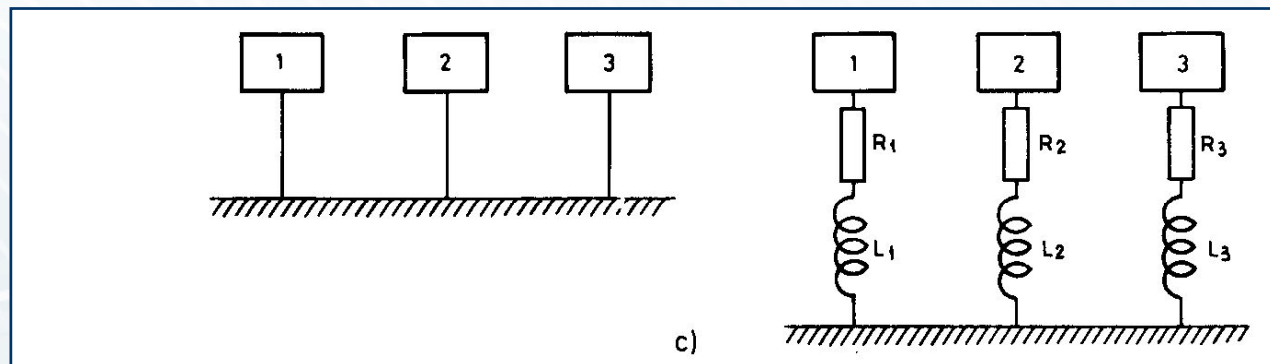
- Ground to improve the equipment performance

- **Multipoint ground topology** is the preferred option

- Multiple ground connection to ground
 - Digital and analog has to be grounded separate and later connected to common point at board level
 - Electronics , hardware and power parts should be grounded separately at module level and then connected together

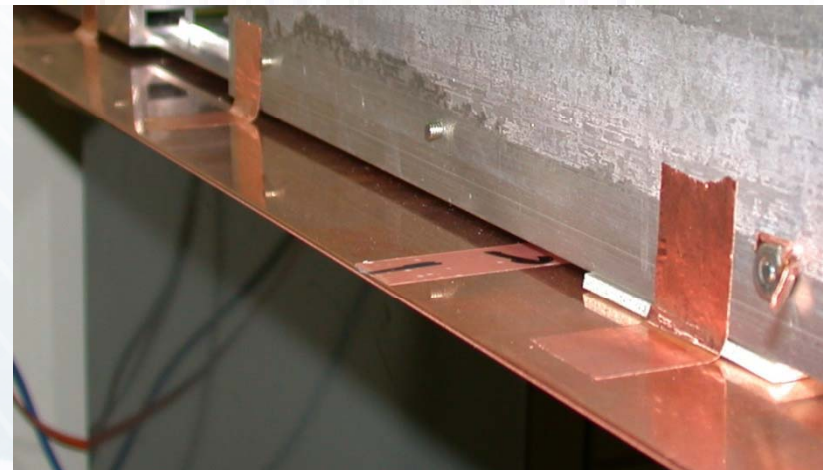
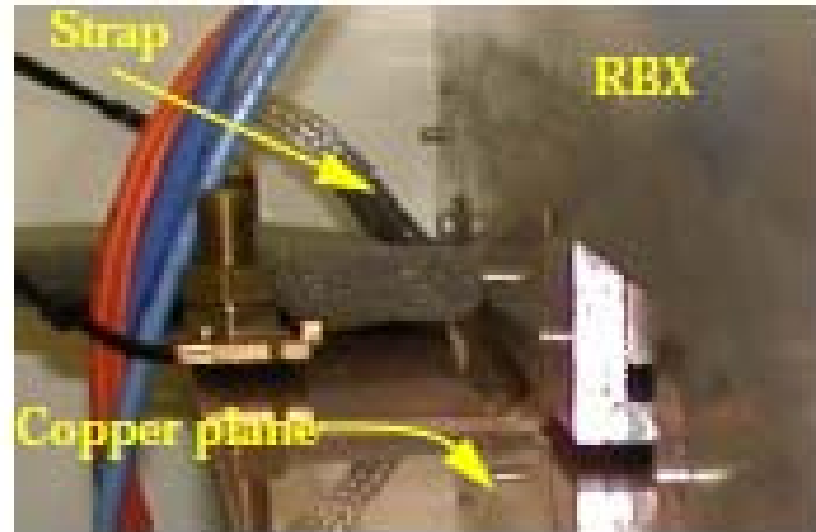
- **Ground connection has to be short**

- It has to present low impedance path at high frequency



2. Grounding: Some recommendations

- Low impedance connection example
- One single connection a few cm
 - It resonates 14 MHz
- Multiple connections
 - It resonates above 50 MHz
- Main characteristics of multiple ground connections
 - They should be connected to:
 - Opposite corners of the equipment
 - The nearest points on the signal reference grids.
- Very special cases it can be done via capacitors
 - Several

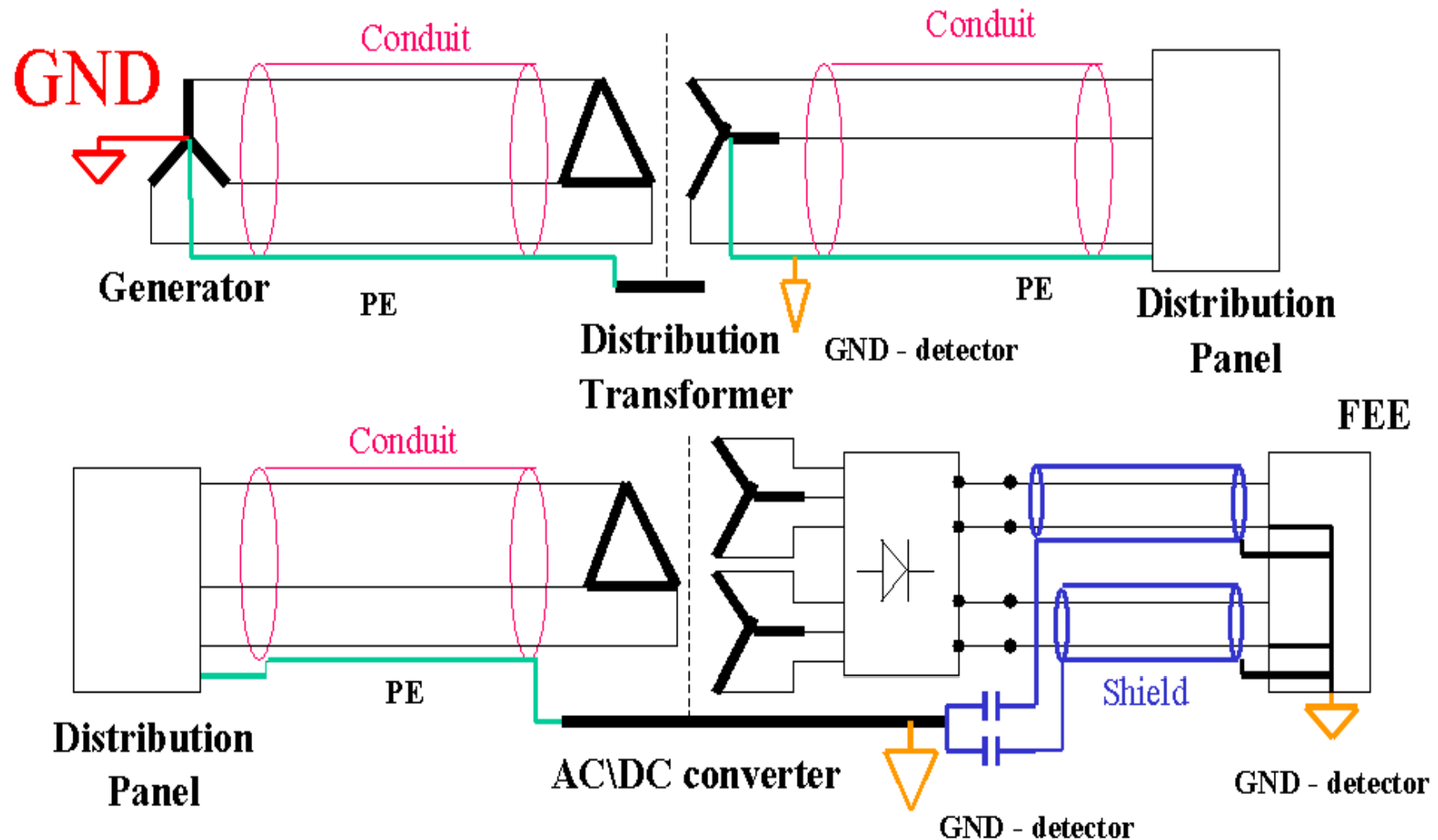


2. Grounding: Some recommendations

- **The grounding designs to improve the equipment performance can be tackled in two steps:**
 - At LF – Avoid ground loops
 - Detector is a kind of resistor divider where currents flows everywhere
 - At HF – Avoid noise currents pass through sensitive parts
 - Everything is connected (real or parasitic impedance) and designing a low impedance paths for these currents
- **It is recommended to have an schematic ground design first and later mechanical ground design**
 - Mechanical and electrical integration issues should be tackle at the same time.
- **All experiment subsystems has to present the same ground topology.**

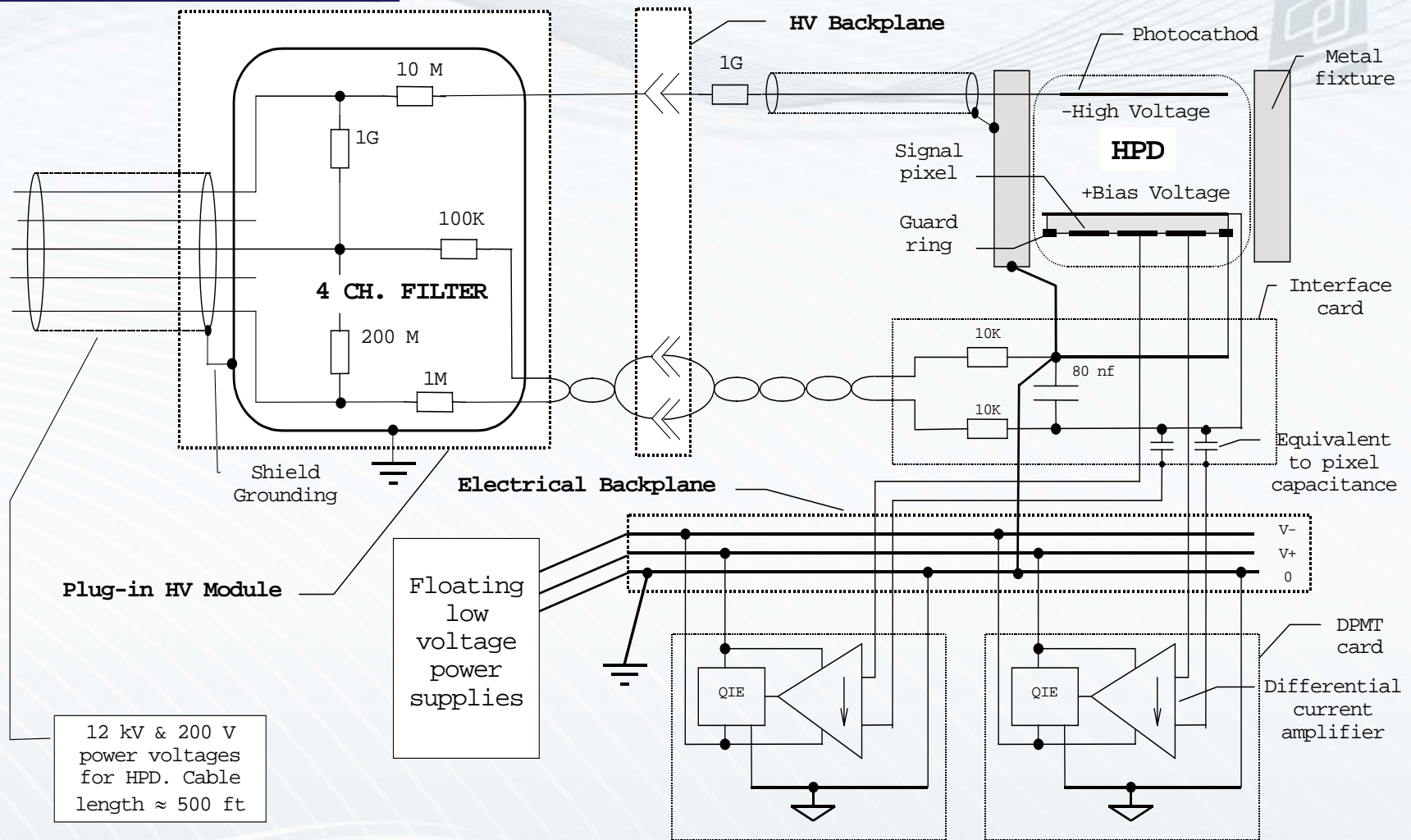
2. Grounding

Experiment level



2. Grounding

Sub-detector level

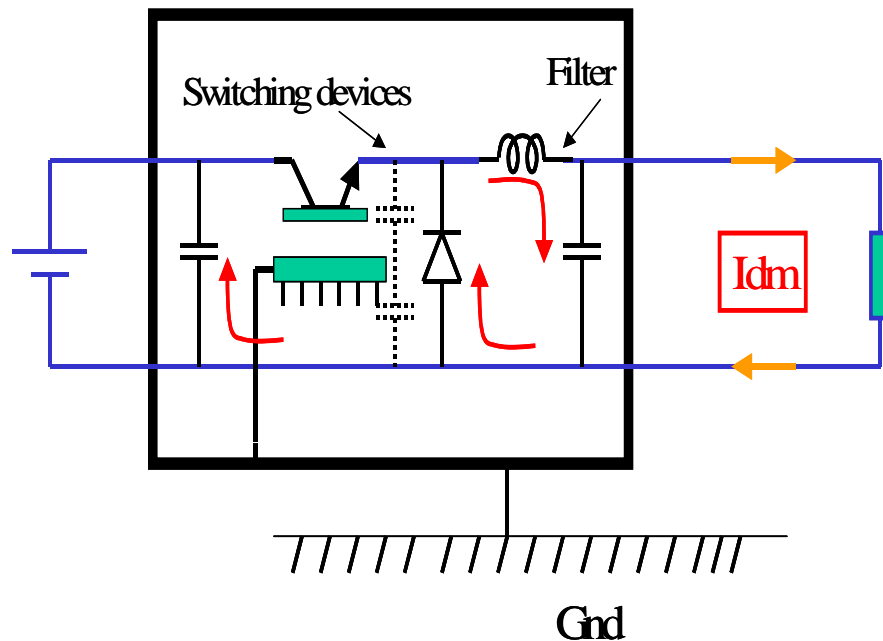


Global & System grounding policy have to be coordinated

3. Noise sources

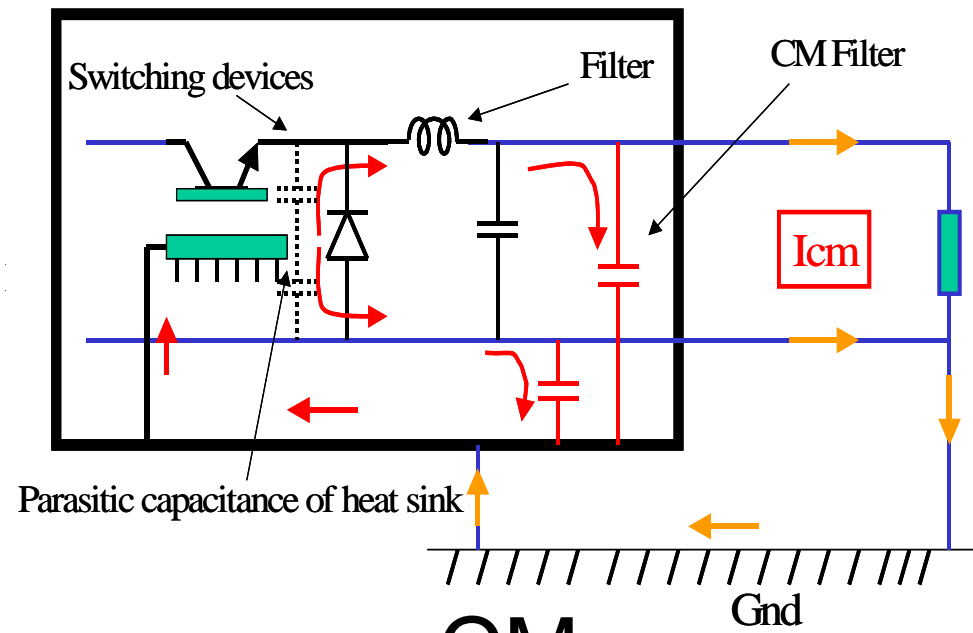
- Switching converters generates conducted noise
 - At the input & output
- It is generally the main noise source in HEP
- Two modes of noise emissions (kHz - MHz range)
 - **Common mode & Differential mode**

Power switching converter



DM

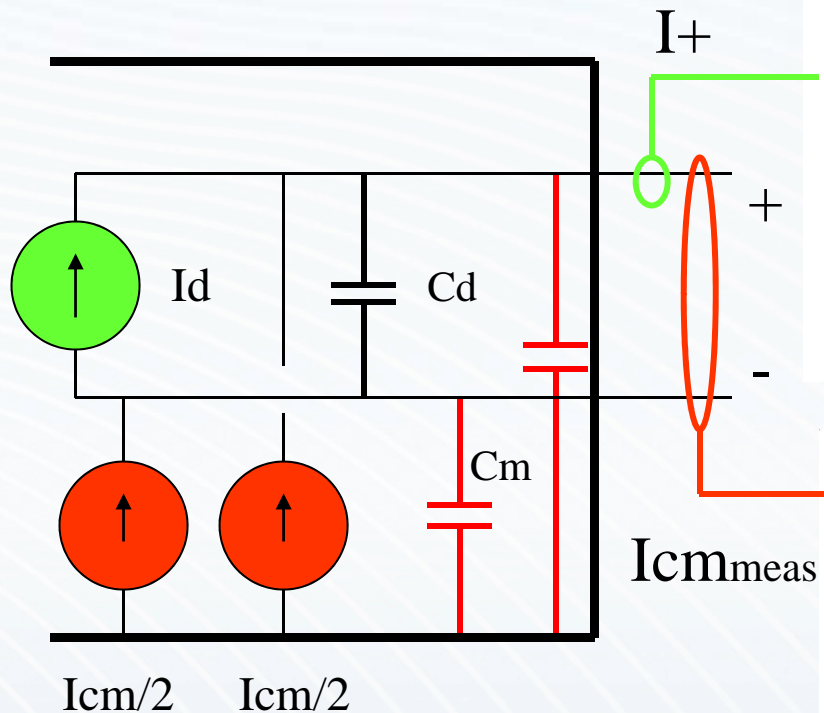
Power switching converter



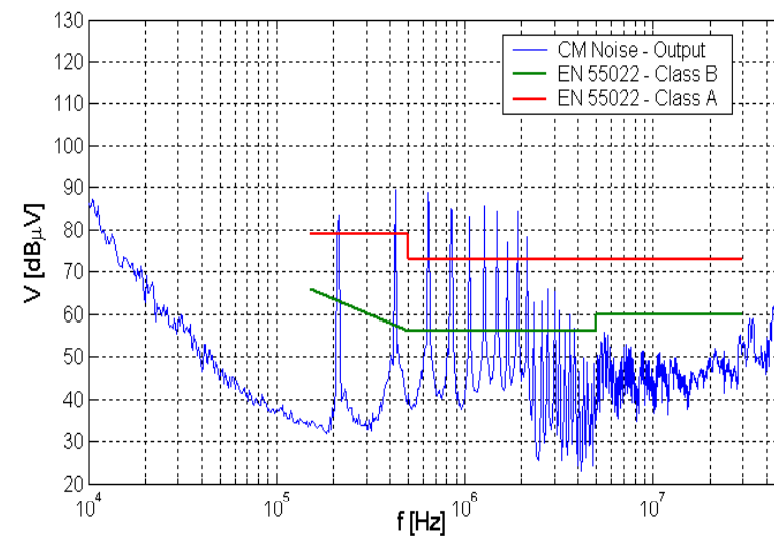
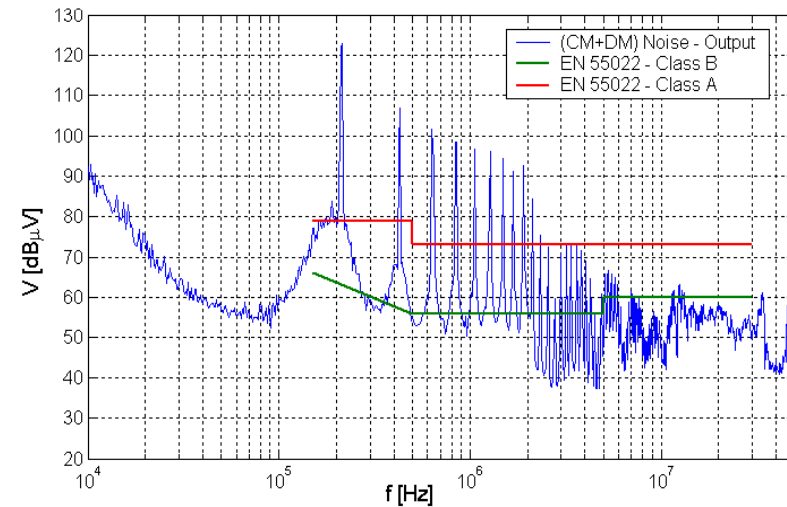
CM

3. Noise sources

CMS - HCAL



- Output currents –
(ref. = 50 ohms)

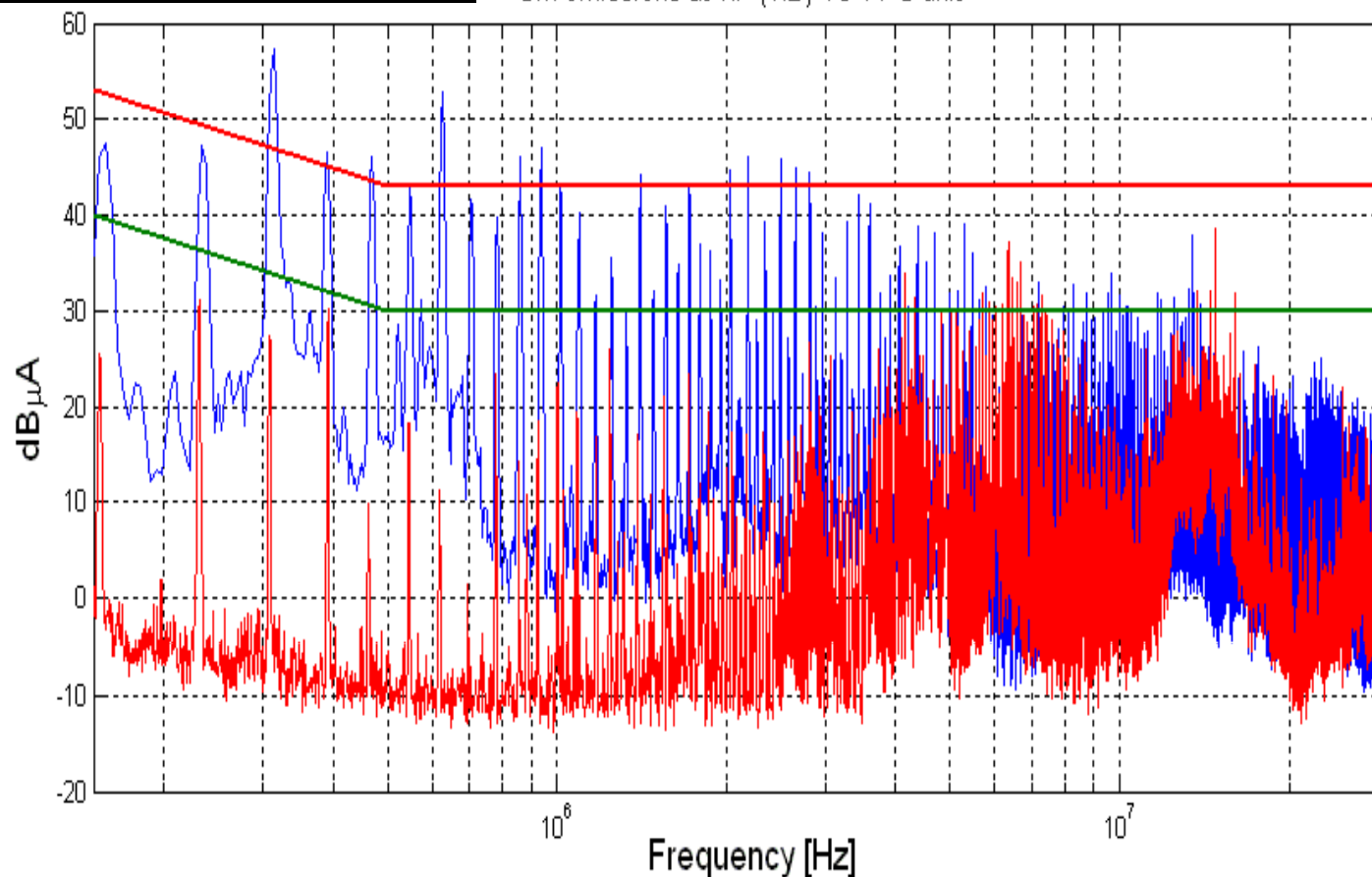


3. Noise sources

CMS – TRACKER

CM emissions at TIF (TIB) Vs 1 PS unit

1 unit Vs 50 units



- Multiple PS units may increase the noise level
- Design issue

4.Noise victims

- The most sensitive component in HEP experiment is the FEE
- Noise components that deteriorates the FEE performance are:
 - Intrinsic thermal noise
 - EM noise
 - EM noise picked-up by the connection detector – FEE
 - EM noise picked-up by the connection FEE - Power supply

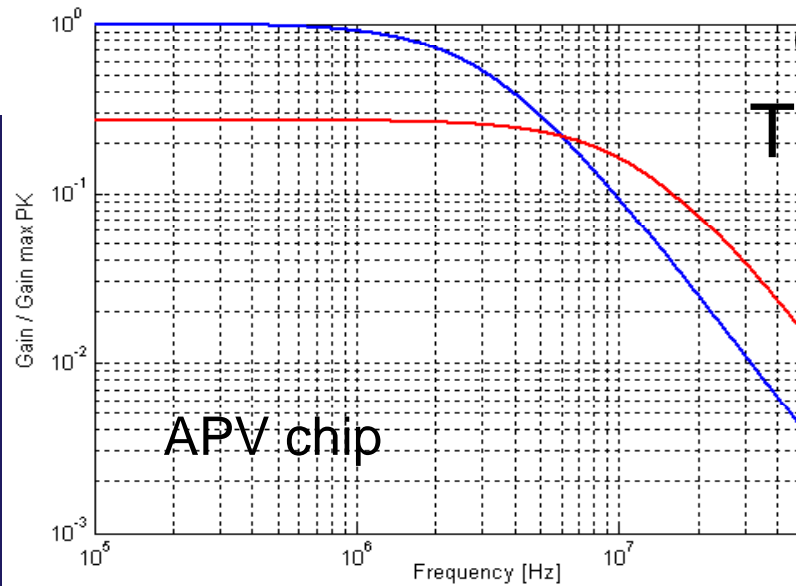
$$n_a(t) = n_{th}(t) + n_{in}(t) + n_{ps}(t) + \dots$$

4.Noise victims

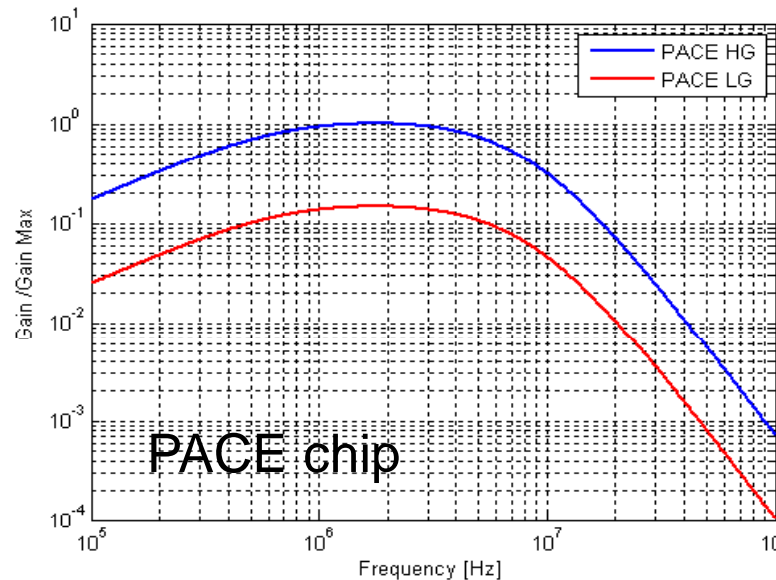
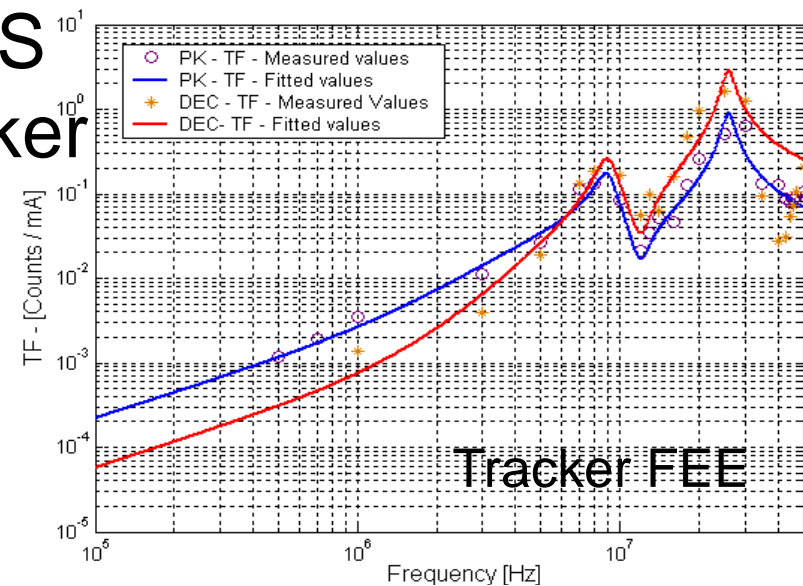
- This noise defines the minimum signal level that the FEE can process
 - Thermal noise dominant effect (by design)
 - EM noise has to be characterized and minimized
- EM noise contribution depends on two factors
 - It depends on Front End Amplifier frequency response.
 - Coupling mechanisms (coupling network) between EM noise and output of the FEE.
- EM noise contribution is not constant.
 - It may change from hundreds kHz to several tenths of MHz
 - FEE characterization to EM noise help to improve the FEE immunity (identify weak areas & frequencies).

4.Noise victims

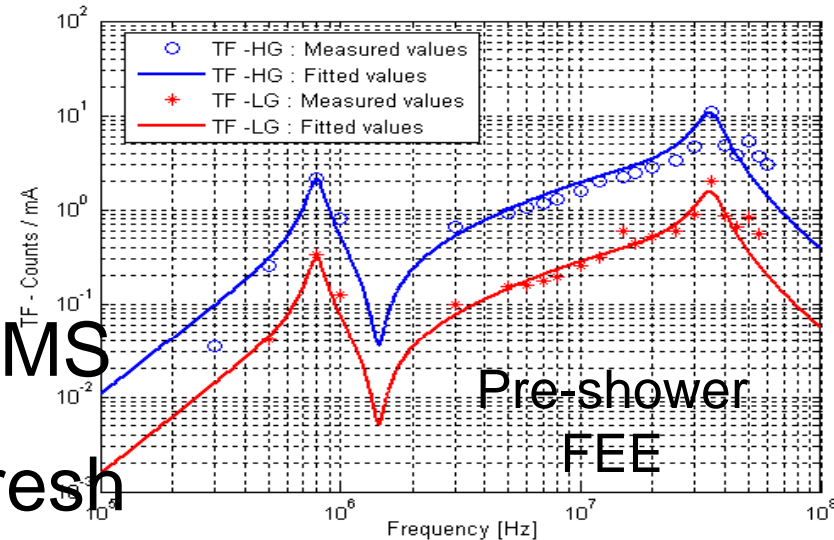
Frequency response



CMS
Tracker



CMS
Pre-sh



5 CONCLUSIONS

- The main elements of electronics integration has been presented.
- **Grounding strategy:**
 - It has to cover safety and performance issues (LF & HF)
 - It should involves all disciplines – Mechanical , electrical.....
 - All disciplines has to be coordinated – **UNIQUE ENTITY**
 - It has to be coordinated between sub-systems.
 - It saves money, time and “discussions between groups”.
 - It should be designed to work from DC to MHz
- **Noise sources**
 - Switching power converters are one of the main noise sources
 - SMPS emits noise form kHz to several tenths of MHz
 - Number of PS may increase system noise a lot.
- **Noise victims**
 - FEE is the main noise victim in any HEP experiment.
 - FEE is sensitive to noise from kHz to several tenths of MHz.
 - Do not forget noise contributions due to EM noise

