

# On programming with algebraic groups

Laura Voggesberger

AGAG  
FB Mathematik  
TU Kaiserslautern

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# Algebraic Groups

A quick introduction

Throughout this talk let  $k$  be an algebraically closed field.

## Example

$GL_n(k) \subseteq k^{n \times n}$  is also a subset of a vector space and the set of roots of the polynomial

$$f : k^{n \times n} \times k \longrightarrow k, \quad (A, y) \mapsto \det(A)y - 1.$$



## Zariski topology

Algebraic groups are groups as well as topological spaces equipped with the **Zariski topology**. The closed sets are given by the set of roots of a set of polynomials (for example).

# Algebraic Groups

A quick introduction

## Algebraic groups

For simplicity we will assume

$$G \leq \mathrm{GL}_n(k),$$

where  $G$  is a closed subgroup in  $\mathrm{GL}_n(k)$  with respect to the Zariski topology.

# Properties

We are especially interested in learning about additional structures in these groups. We will from now on consider *reductive, connected* groups. They include

- maximale tori ?
- Borel subgroups ?
- root systems and root subgroups ?
- Lie algebras ?

## Structures in $GL_n(k)$

- **maximal tori** are maximal abelian subgroups which are isomorphic to  $k^\times \times \dots \times k^\times$ .

$$T := \left\{ \begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix} \mid t_i \in k^\times \right\} \subseteq GL_n(k)$$

- **Borel subgroups** are maximal, closed, connected, and solvable subgroups of an algebraic group  $G$

$$B := \left\{ \begin{pmatrix} * & & * \\ & \ddots & \vdots \\ 0 & & * \end{pmatrix} \right\} \subseteq GL_n(k)$$

in particular we for each maximal torus we can find a Borel subgroup such that  $T \subseteq B$ .

## Structures in $GL_n(k)$

- A **root system** is given by a subset  $\Phi \subseteq \text{Hom}(T, k^\times)$ , in  $GL_n(k)$  we obtain

$$\chi_{ij} : T \longrightarrow k^\times, \quad \begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix} \longmapsto t_i t_j^{-1}$$

with root system  $\Phi := \{\chi_{ij} \mid 1 \leq i, j \leq n, i \neq j\}$ .

- As for abstract root systems there is a **Weyl group**,

$$W = N_G(T)/C_G(T) \simeq \langle s_\alpha \mid \alpha \in \Phi \rangle.$$

In  $GL_n(k)$  we have  $W \simeq S_n$  generated by permutation matrices.

## Structures in $GL_n(k)$

- For each  $\alpha \in \Phi$  we can define **root subgroups**  $U_\alpha$  by taking  $U_\alpha$  to be the image of an isomorphism

$$u_\alpha : (k, +) \longrightarrow U_\alpha \leq G,$$

such that  $tu_\alpha(c)t^{-1} = u_\alpha(\alpha(t)c)$  for all  $t \in T, c \in k$ .

In  $GL_n(k)$  we obtain

$$U_{\chi_{ij}} = \left\{ \begin{array}{c} \begin{matrix} & & i \\ & & \downarrow \\ \left( \begin{array}{cccc} 1 & & & \\ & \dots & & \\ & & a & \\ & & \dots & \\ & & & 1 \end{array} \right) & \leftarrow j \\ \end{matrix} \\ \left. \vphantom{\begin{matrix} & & i \\ & & \downarrow \\ \left( \begin{array}{cccc} 1 & & & \\ & \dots & & \\ & & a & \\ & & \dots & \\ & & & 1 \end{array} \right) } \right| a \in k \end{array} \right\}.$$



For  $u_a = \begin{pmatrix} 1 & & & \\ & \dots & & \\ & & a & \\ & & \dots & \\ & & & 1 \end{pmatrix} \in U_{\chi_{ij}}$  and  $t \in T$  we get

$$tu_a t^{-1} = u_{\chi_{ij}(t)a} = \begin{pmatrix} 1 & & & \\ & \dots & & \\ & & \chi_{ij}(t)a & \\ & & \dots & \\ & & & 1 \end{pmatrix}.$$

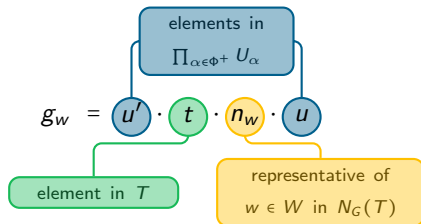
## Structures in $GL_n(k)$

- For each algebraic group, we can define a **Lie algebra** (given by the tangent space),  $\text{Lie}(GL_n(k)) = \mathfrak{gl}_n(k) = k^{n \times n}$ .
- We have an action of  $G$  on  $\text{Lie}(G)$ :

$$\text{Ad} : G \longrightarrow GL(\text{Lie}(G)).$$

In  $GL_n(k)$  this is given by conjugation:  $\text{Ad}(A)(B) = ABA^{-1}$ ,  $A \in GL_n(k)$  and  $B \in k^{n \times n}$ .

- every element in  $G$  is given as a multiplication of four group elements, also called **Bruhat decomposition**:





# Properties

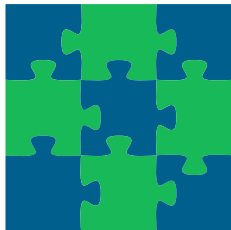
We are especially interested in learning about additional structures in these groups. They include

- maximale tori  $\leadsto$  is something like this:  $\begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix}$
- Borel subgroups  $\leadsto$  looks something like this:  $\begin{pmatrix} * & \cdots & * \\ & \ddots & \\ 0 & & * \end{pmatrix}$
- root systems and root subgroups  $\leadsto \Phi \subseteq \text{Hom}(T, k^\times)$ , with  $\chi_{ij} : \begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix} \mapsto t_i t_j^{-1}$  and  $u_a = \begin{pmatrix} 1 & & & \\ & \ddots & a & \\ & & \ddots & \\ & & & 1 \end{pmatrix} \in U_{\chi_{ij}}$ .
- Lie algebras  $\leadsto$  linearisation of problems in algebraic groups, for example the vector space  $k^{n \times n}$

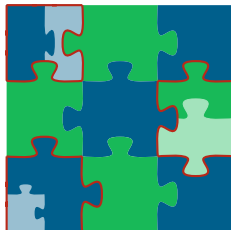
## How can we use this for computing?

- The multiplication of group elements is well understood
  - ↪ In some algebra computer programmes it is even possible to define algebraic groups directly and compute the multiplication with elements
- Action by group elements on the Lie algebra leads to linear combinations in Lie algebra depending on parameters in  $k$
- **However**, not every computer programme does allow us to do so over algebraic closures
  - ↪ in Magma, we can work over algebraic closures. We can define Lie algebras and the action of  $G$  on  $\text{Lie}(G)$  is given by linear maps that can easily be implemented

# The problem with the orbits



In “good” characteristic



In small characteristic

# Nilpotent Pieces

## Definition (Nilpotent Pieces)

Let

**1**  $\delta : \Phi \rightarrow \mathbb{Z}$  be a linear map describing a nilpotent orbit in good characteristic

**2**  $R$  be a set of the representatives of nilpotent orbits

**3**  $R_\delta \subseteq R$  such that  $x \in R_\delta \Leftrightarrow \exists g \in G$  such that

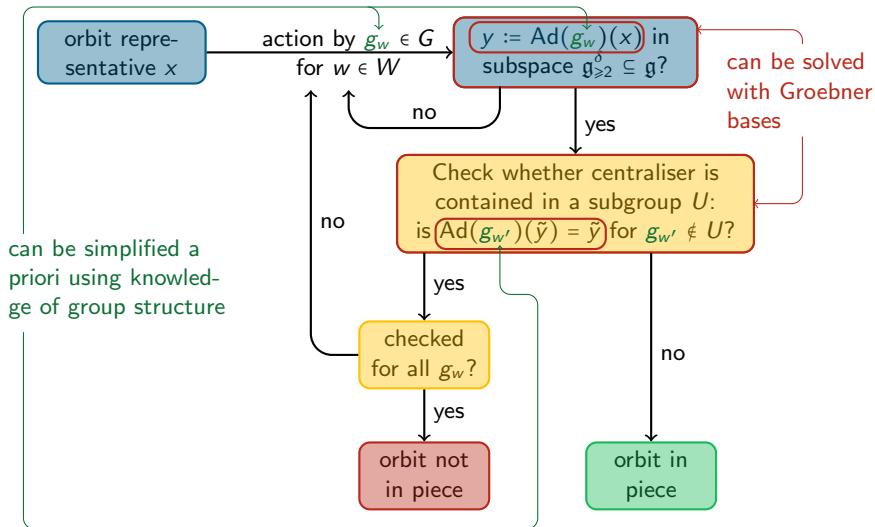
**i**  $g \cdot x \in \mathfrak{g}_{\geq 2}^\delta \leftarrow$  specific subset of  $\text{Lie}(G)$

**ii**  $C_G([g \cdot x]_{\mathfrak{g}_2^\delta}) \subseteq \langle T, U_\alpha \mid \delta(\alpha) \geq 0 \rangle$  set linear coefficients of elements in  $g \cdot x$  not in  $\mathfrak{g}_2^\delta$  to 0

Then  $\mathcal{N}_\mathfrak{g}^\delta = \bigsqcup_{x \in R_\delta} \mathcal{O}_x$ .

Union of nilpotent orbits

# A schematic representation of the algorithm



## Example

Let  $\Phi(G_2) := \{\pm\alpha, \pm\beta, \pm(\alpha + \beta), \pm(2\alpha + \beta), \pm(3\alpha + \beta), \pm(3\alpha + 2\beta)\}$ ,  
 $\text{char}(\mathbb{k}) = 3$ , and  $x = e_\beta + e_{\alpha+\beta} \in \text{Lie}(G)$ .

**1** Elements like

$$u_\beta(c_\beta)u_{\alpha+\beta}(c_{\alpha+\beta})u_{2\alpha+\beta}(c_{2\alpha+\beta})u_{3\alpha+2\beta}(c_{3\alpha+2\beta})$$

for all  $c_\beta, c_{\alpha+\beta}, c_{2\alpha+\beta}, c_{3\alpha+2\beta} \in \mathbb{k}$  fix  $x$

$\leadsto$  enough to compute the action of  $u' t n_w u_\alpha(c_\alpha) u_{3\alpha+\beta}(c_{3\alpha+\beta})$  on  $x$ .

**2** for  $w = n_{s_\beta s_\alpha}$  compute the coefficients of linear combination of  $g_w \cdot x$

$\leadsto$  obtain an equation system:

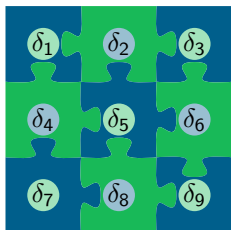
$$2 \frac{d_1^5}{d_2^2} c_\alpha^3 = 0$$

where  $d_1, d_2 \in \mathbb{k}^\times, c_\alpha \in \mathbb{k}$ .

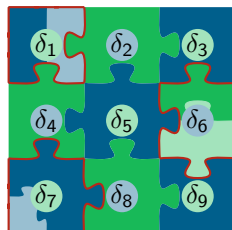
$$2d_1^2 d_2 c_\alpha^2 + d_1^2 d_2 c_\alpha = 0$$

with solution  $c_\alpha = 0$ .

# Results



In “good” characteristic



In small characteristic