



Universität Hamburg

DER FORSCHUNG | DER LEHRE | DER BILDUNG



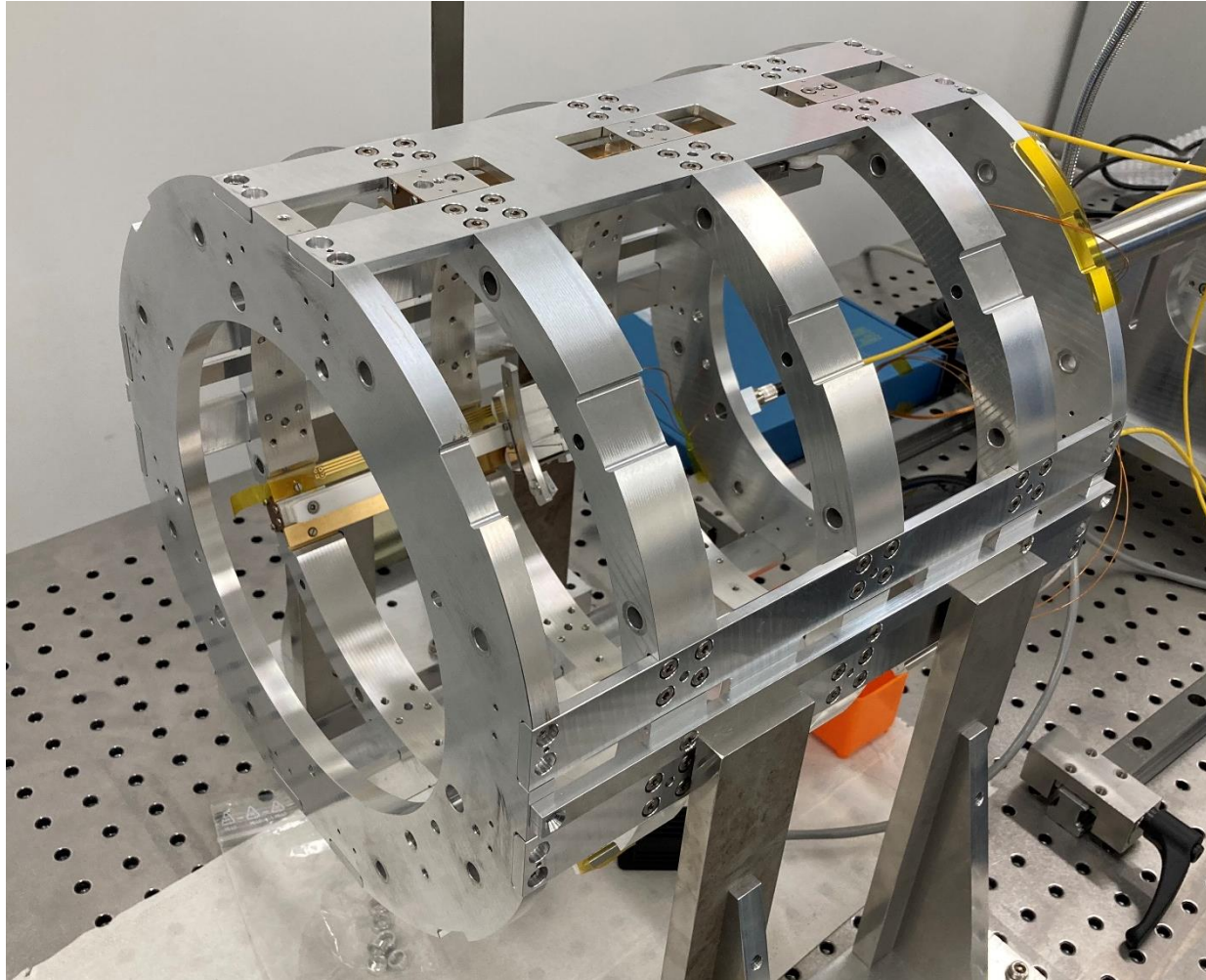
Project200 Setup Status

Christoph Krieger

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Mechanics

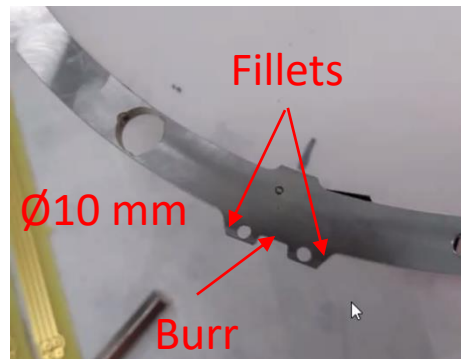
Assembly & Alignment



- P200 was (re-)assembled by Michael in the first week of Jan 2022
- Alignment of back-bone structure and motor rails with high precision dial gauges
- Titanium Disk Ring was fitted incl. titanium leaf springs
→ fits after small modifications
- Disk ring replaced by “cloth hangers” for individual driving of motors during testing and commissioning

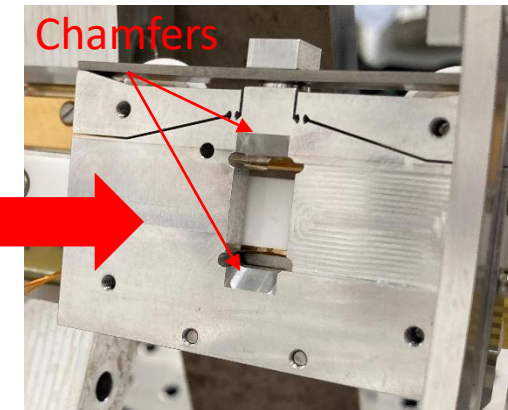
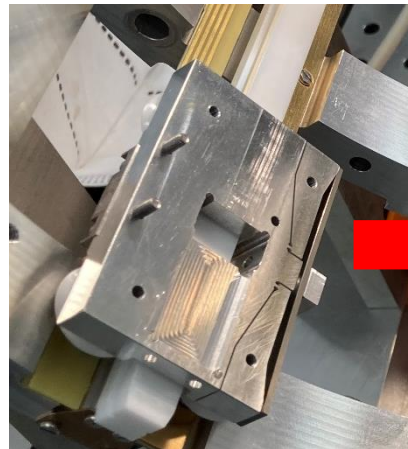
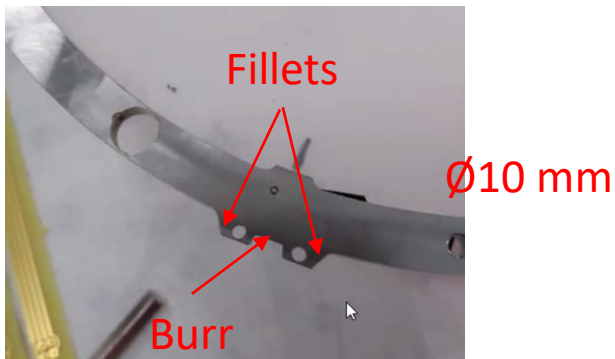
Issues with Titanium Disk Ring manufactured at CPPM:

1. Small burrs from machining at interface to leaf spring/carriage
2. Fillets at interface to leaf spring/carriage which were removed in the latest design
(Possible miscommunication and/or mix-up of designs at different stages)
3. Through holes for interferometer mirrors $\varnothing 10$ mm instead of $\varnothing 8$ mm
(Possible miscommunication and/or mix-up of designs at different stages)



Dealing with with the Titanium Disk Ring issues:

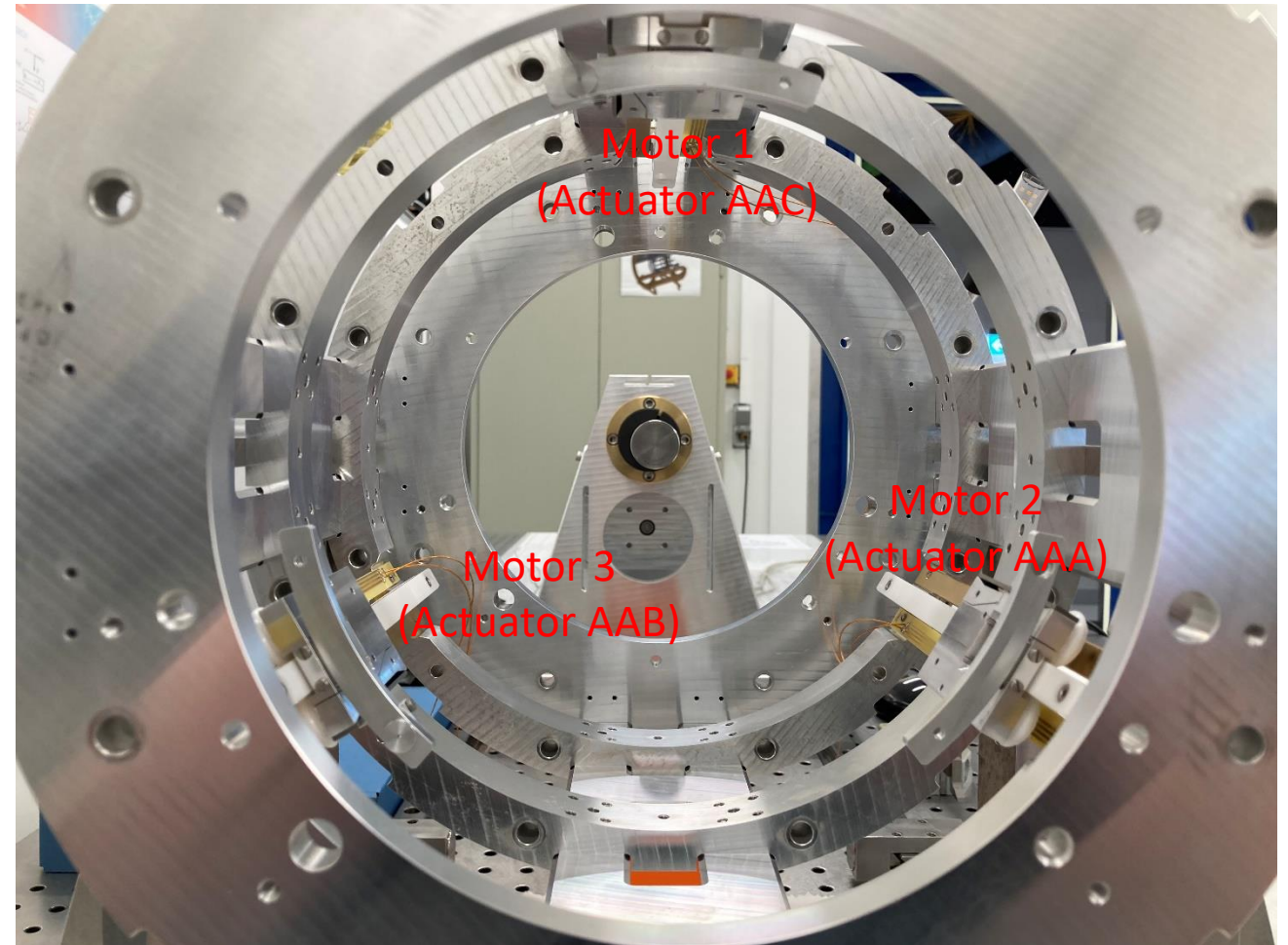
1. Small burrs from machining at interface to leaf spring/carriage
→ Manually removed by Michael with file
2. Fillets at interface to leaf spring/carriage which were removed in the latest design
→ Added chamfers at the carriages to accommodate for fillets
3. Through holes for interferometer mirrors $\varnothing 10$ mm instead of $\varnothing 8$ mm
→ Adapter rings for Attocube retro reflector holders





Motors

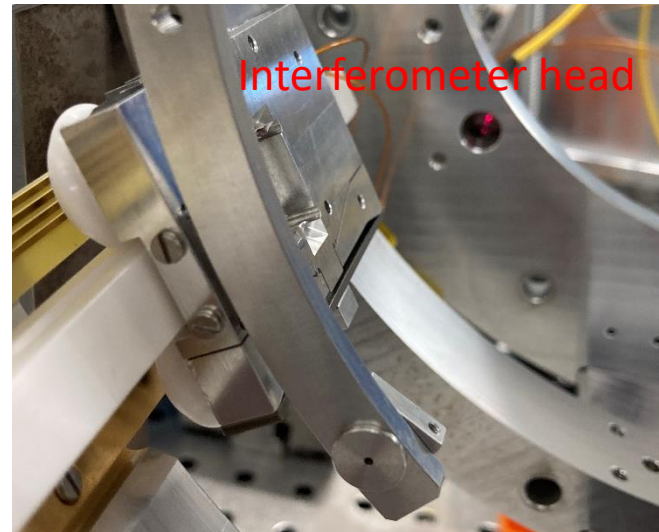
- Three motors and carriages are installed in Project200
- Electrical contact rails are installed and wired
- Electrical wiring incl. vacuum feedthrough have been tested successfully
- First test drive along full length of rails was successful
- More intricate tests (stable movement/step size) still to be done



Attocube

Attocube Integration

- Attocube interferometer arrived at UHH on 23.12.2021
- Package was “found” on 06.01.2022
- Fast and easy commissioning (works out of the box!)
- Integration in Project200 went smooth thanks to Michael’s preparation (fine threaded adapters for the interferometer heads and mounting adapter for the retro reflectors)
- Alignment of heads and retro reflectors worked



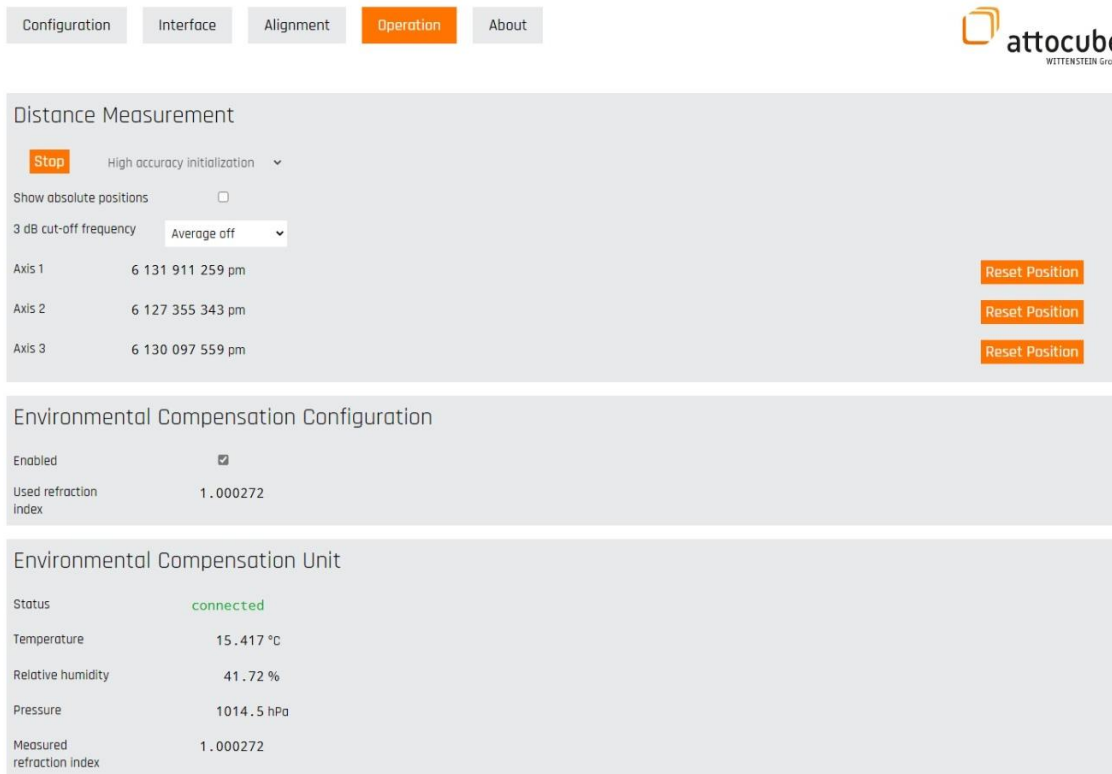
Attocube Integration

Project200

JPE Controller

Attocube IDS

Attocube measurement from IDS Web Interface



Configuration Interface Alignment **Operation** About

attocube
WITTENSTEIN Group

Distance Measurement

Stop High accuracy initialization ▾

Show absolute positions

3 dB cut-off frequency Average off ▾

Axis 1	6 131 911 259 pm	Reset Position
Axis 2	6 127 355 343 pm	Reset Position
Axis 3	6 130 097 559 pm	Reset Position

Environmental Compensation Configuration

Enabled

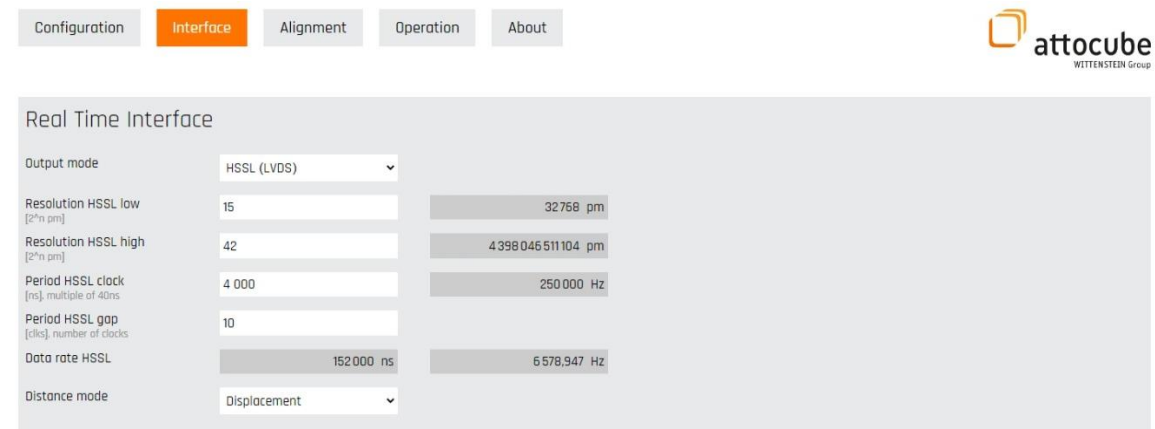
Used refraction index 1.000272

Environmental Compensation Unit

Status **connected**

Temperature	15.417 °C
Relative humidity	41.72 %
Pressure	1014.5 hPa
Measured refraction index	1.000272

Configuration of Real Time Interface



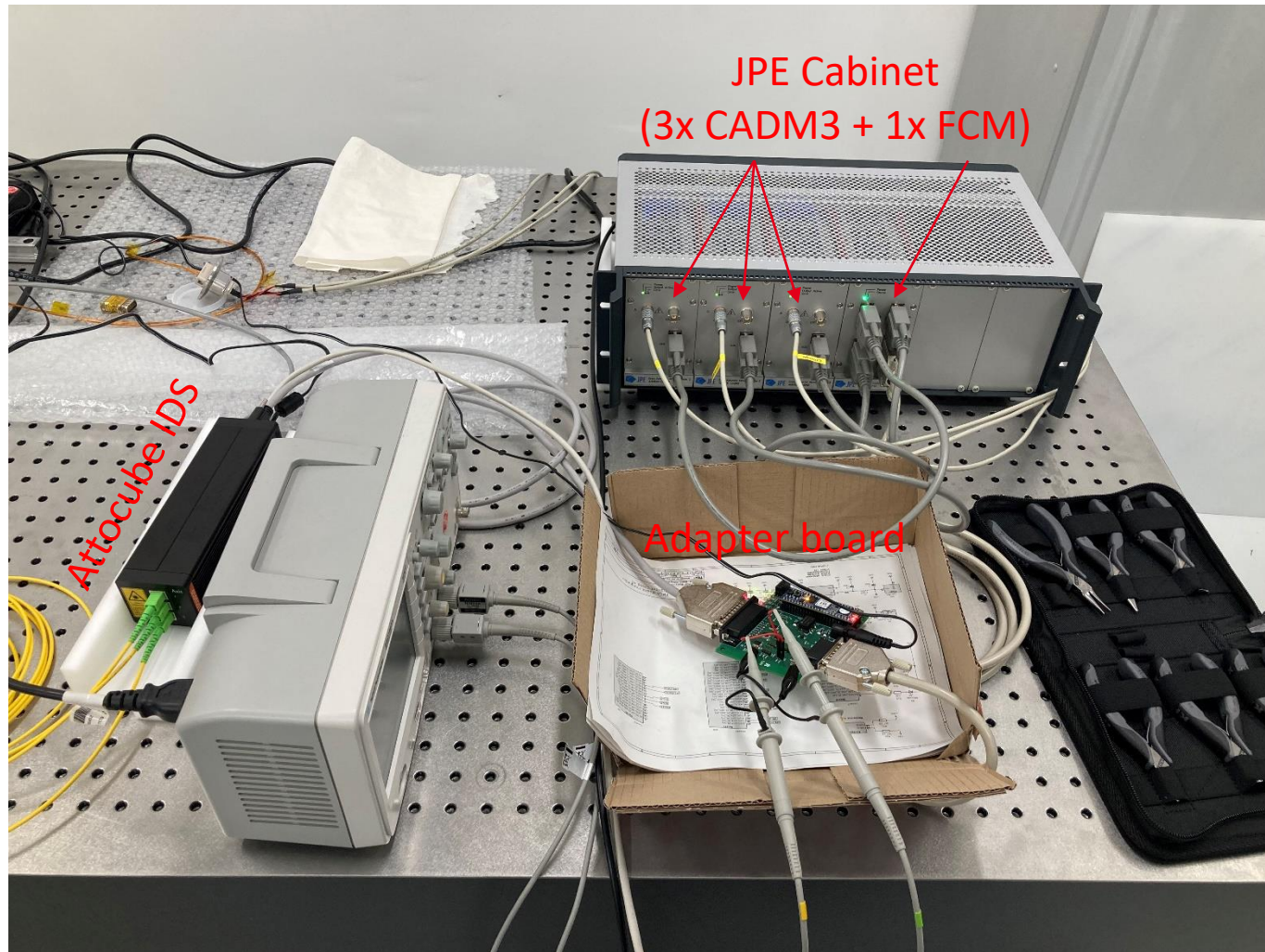
Configuration **Interface** Alignment Operation About

attocube
WITTENSTEIN Group

Real Time Interface

Output mode	HSSL (LVDS) ▾	
Resolution HSSL low [2 th nm]	15	32768 pm
Resolution HSSL high [2 th nm]	42	4398046511104 pm
Period HSSL clock [ns], multiple of 40ns	4 000	250 000 Hz
Period HSSL gap [clks], number of clocks	10	
Data rate HSSL	152000 ns	6 578.947 Hz
Distance mode	Displacement ▾	

Attocube Integration



Attocube JPE Adapter Board

- Planned and build by Jens Scharschmidt (UHH electronic technician)
- First test on 19.01.2021
- Adapter board works
- Successfully established data link between Attocube IDS and JPE FCM Controller
- Displacements measured by IDS are correctly read by JPE FCM



Synchronized Motor Drive

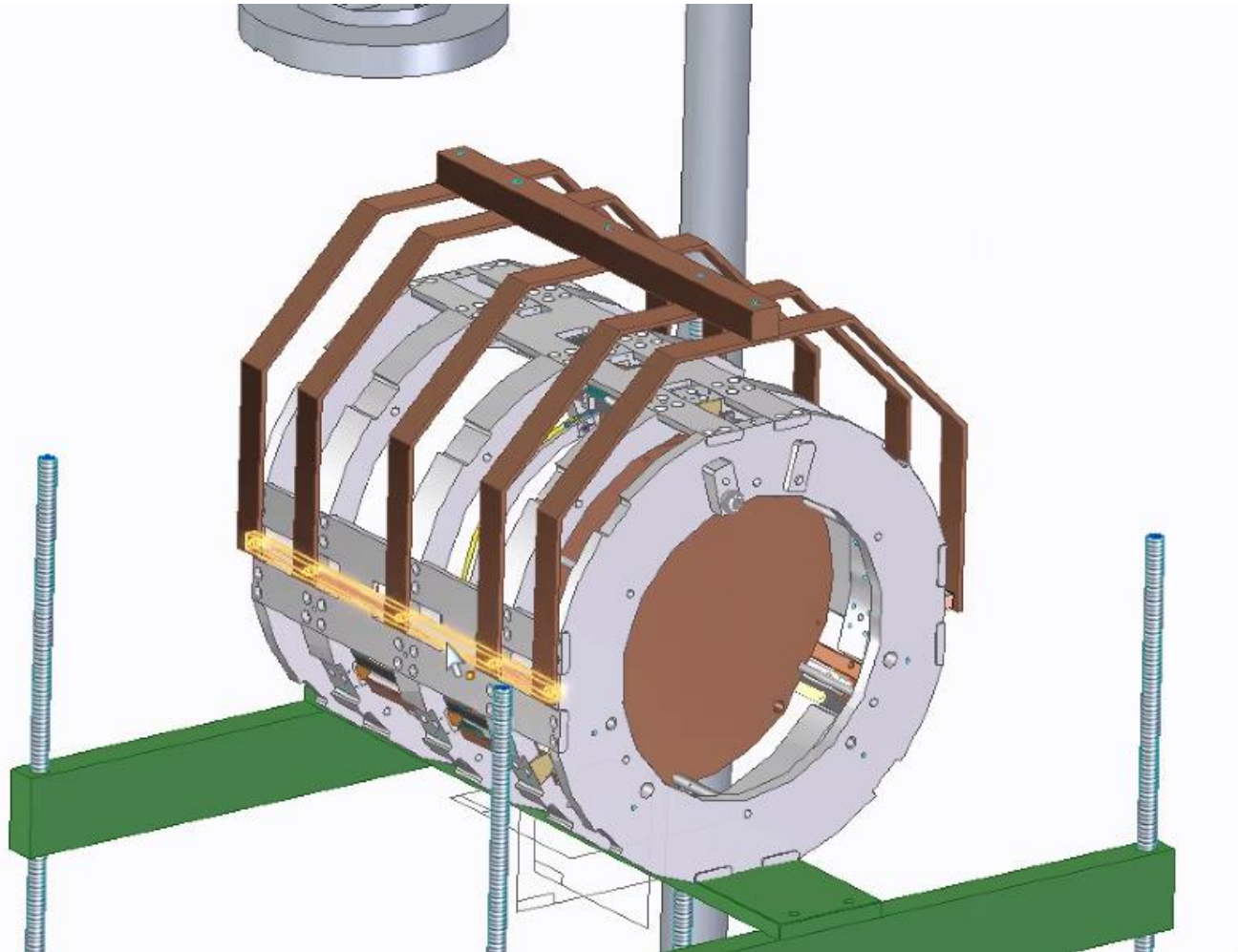


- Attocube IDS provides position data (here displacement with arbitrary origin point as substitute for absolute position data) via adapter board to JPE FCM controller
- Link between IDS and FCM set up successfully
- Cloth hangers instead of disk ring to avoid damage and to have no additional mechanical constraints during first tests
- Position data correctly read by FCM after initialization
- Driving of motors via FCM does **NOT** work **yet**
 - Error report with detailed description send to JPE, waiting for reply from engineer responsible for FCM development
 - Still a few features to sort out (and probably to discover...), e.g. position is read by FCM only after setting the first target position blindly (only then link between IDS and FCM is established)



Cryostat

Cryostat Integration



- Copper structure for thermal connection to cryocooler head via copper braids
- GFK (G10) structure to suspend Project200 in octagon cryostat via G11 threaded rods
- Copper structure produced by RWTH Aachen (minus holes for copper braids)





ToDo

ToDo



List of items/actions still to do prior to the tests in octagon cryostat @ CERN:

- Perform individual motor tests/characterization in Project200 configuration
- Write software to readout interferometer data while driving
(Attocube provides a Python interface for the IDS 😊)
- Get synchronized motor drive running → Waiting for reply from JPE
- Test-fit titanium disk ring incl. retro reflectors and test driving it with all three motors
- Fit temperature sensors
(cryogenic tape and MLI available for fixing sensors on disk (ring) and carriage)
- Manufacture G10 supports
- Add holes for copper braids to copper structure (meeting with CERN cryolab on Wed)
- Test operation (interfaces, drivers, software, etc.) on notebook to be used for CERN tests
- Test optical fibre setup for cryostat (feedthrough and additional/other fibres)